CURRICULUM & SYLLABUS

For

B.E. (Part Time) Mechanical Engineering

(Choice Based Credit System) (With effect from 2018)



DEPARTMENT OF MECHANICAL ENGINEERING

SRI CHANDRASEKHARENDRA SARASWATHI VISWA MAHAVIDYALAYA

SCSVMV

(Deemed to be University U/S 3 of UGC Act 1956)

Accredited with "A" Grade by NAAC

Enathur, Kanchipuram - 631 561

SEMESTER - I						
SL.	Course Code	Course Code Name of the Course		Hours per week		
No		Name of the Course	L	Т	Р	Credit
1.	BMEP181T10	Mathematics - I	3	1	-	4
2.	BMEP181T20	Engineering Mechanics	3	-	-	3
3.	BMEP181T30	Engineering Thermodynamics	3	-	-	3
4.	BMEP181T40	Basic Electronics Engineering	3	-	-	3
5.	BMEP181T50	Materials Engineering	3	-	-	3
	Total					16

	SEMESTER - II					
SL.	Course Code	rse Code Name of the Course		Hours per week		
No	No Course Code	se code Name of the course –	L	Т	Р	
1.	BMEP182T10	Mathematics - II	3	1	-	4
2.	BMEP182T20	Applied Thermodynamics	3	-	-	3
3.	BMEP182T30	Fluid Mechanics & Fluid Machines	3	-	-	3
4.	BMEP182T40	Strength of Materials	3	-	-	3
5.	BMEP182T50	Instrumentation & Control	3	-	-	3
	Total					16

	SEMESTER - III					
SL.	Course Code	Name of the Course		rs per v	Credit	
No	Course Coue	Name of the Course	L	Т	Р	
	Theory					
1.	BMEP183T10	Heat and Mass Transfer	3	-	-	3
2.	BMEP183T20	Kinematics of Machines	3	-	-	3
3.	BMEP183T30	Manufacturing Processes	3	-	-	3
4.	BMEP183T40	Engineering Economics	3	-	-	3
	Practical					
5.	BMEP183P50	I.C. Engines & Heat transfer Lab (Mechanical Lab – 1)	-	-	4	2
		Total				14

	SEMESTER - IV					
SL.	Course Code	Name of the Course	Hou	rs per v	week	Credit
No	Course Coue	Name of the Course	L	Т	Р	
	Theory					
1.	BMEP184T10	Design of Machine Elements	3	-	-	3
2.	BMEP184T20	Dynamics of Machines	3	-	-	3
3.	BMEP184T30	Metrology and Quality Control	3	-	-	3
4.	BMEP184T40	Power Plant Engineering	3	-	-	3
	Practical					
5.	BMEP184P50	Dynamics and Measurement Lab (Mechanical Lab - 2)	-	-	4	2
		Total				14

	SEMESTER - V					
SL.	Course Code	Name of the Course	Hours per week			Credit
No	Course Coue	Name of the Course	L	Т	Р	
		Theory				
1.		CAD/CAM	3	-	-	3
2.		Manufacturing Technology	3	-	-	3
		Elective-I				
		Finite Element Analysis				
		Engineering Fracture Mechanics			-	
3.		Product Design & Development	3	-		3
		3D Printing				
		Tribology				
		Open Elective – I				
		Cloud Computing				
4.		Web Design	3	-		2
		Digital Image Processing	3	-	-	3
		Data Analytics				
	Practical					
5.		CAD/CAM Lab (Mechanical Lab - 3)			4	2
		Total				14

	SEMESTER - VI					
SL.	Course Code	Name of the Course	Hours per week			Credit
No	Course Coue	Ivalle of the Course	L	Т	Р	
	-	Theory			-	
1.		Automation in Manufacturing	3	-	-	3
2.		Mechatronics	3	-	-	3
		Elective-II				
		Refrigeration & Air Conditioning				
		I.C. Engines				
3.		Turbo Machines	3	-	-	3
		Gas Dynamics & Jet Propulsion				
		Energy Conservation in Industries				
		Open Elective – II				
		Autotronics				
4.		Artificial Intelligence & Machine	2			2
		Nano Technology & Surface Engineering	3	-	-	3
		Disaster Management & Mitigation				
	Practical					
5.		Mechanical Lab – 4 (Mechatronics Lab)			4	2
6.		Project Work Phase - I	4 ł	nrs/we	eek	2
		Total				16

	SEMESTER - VII					
SL.	Course Code	Name of the Course	Hou	Hours per week		
No		Name of the Course	L	Т	Р	Credit
		Theory				
1.		Automobile Engineering	3	-	-	3
		Elective-III				
		Sustainable Manufacturing				
•		Design for Manufacturing				
2.		Digital Manufacturing	3	-	-	3
		Composite Materials				
		Theory of Metal Cutting				
		Elective – IV				
		Total Quality Manufacturing			-	
3.		Entrepreneurship Development				
		Non-Traditional Machining	- 3	-		3
		Flexible Manufacturing Systems	-			
	Practical					
4.		Project Work Phase - II	16	hrs/w	eek	10
		Total				19

SEMESTER – I

Course Title	MATHEM	ATICS –I (Calculus & Linear Algebra)	Credits	L T P C
Course Code	BMEP181	T10	Cleans	3003
Course Category		BSC		
Learning Level				
OBJECTIVES				
• To familiarize the prospective engineers with techniques in calculus, multi-variable calculus and sequence and series.				

• To equip the students with standard concepts and tools at an intermediate to advanced level that will serve them well towards tackling more advanced level of mathematics.

UNIT-I: Calculus

Evaluation of definite and improper integrals- Beta and Gamma functions and their properties - Applications of definite integrals to evaluate surface areas and volumes of revolutions.

UNIT-II: Numerical Methods

Solution of polynomial and transcendental equations – Bisection method-Newton-Raphson method-Regula- Falsi Method. Interpolation- Newton's forward and backward difference formulae-Interpolation with unequal intervals-Newton's divided difference and Lagrange's formulae-Numerical Differentiation.

UNIT-III: Sequences and Series

Convergence of sequence and series-tests for convergence- Comparison test- D'Alembert's ratio test-Raabe's test-Logarithmic test- Cauchy's root test- Fourier series: Half range sine and cosine series-Parseval's theorem.

UNIT-IV: Multivariable Calculus (Differentiation)

Limit-Continuity - Partial derivatives, total derivatives- Directional Derivatives-Tangent plane and normal line-Maxima, minima and saddle points-Method of Lagrange multipliers – Gradient Curl-Divergence.

UNIT-V: Matrices

Matrices: Rank of a matrix-rank-nullity theorem-System of linear equations- Symmetric Matrices-Skew symmetric matrices- Orthogonal matrices; Eigen values and Eigenvectors- Cayley-Hamilton theorem- Diagonalization of matrices.

CO	COURSE OUTCOMES	РО		
Upon com	pletion of this course, Students should be able to			
1.	Understand the concept of basic of definite and improper integrals, Beta and Gamma functions, definite integrals to evaluate surface areas and volumes of revolutions and its application of analysis the Engineering problems.			
2.	Solve polynomial and transcendental equations, know to apply Newton's difference formulae for Interpolation problems and can solve Numerical differentiation problems.			
3.	Identify and improve their basic ideas of sequence and series using the method of tests for convergence and can solve problems on Half range sine and cosine series.			
4.	Analyze the concept of multivariable calculus such as limit continuity, partial derivatives, total derivatives directional derivatives, tangent plane and normal line, maxima, minima of function and gradient, curl, divergence of a vector function.			
5.	Understand the concept of basic matrices and evaluate rank of a matrix and solve system of linear equations. Analyzing the concept of symmetric matrices, skew symmetric matrices and orthogonal matrices. Know to find Eigen values and Eigen vectors and diagonalization of matrices.			
TEXT BO				
1.	B.S. Grewal, "Higher Engineering Mathematics", Khanna Publishers, 2000.			
REFEREN				
1.	G.B. Thomas and R.L. Finney, Calculus and Analytic geometry, Pearson, 2	002.		
2.	T. Veerarajan, Engineering Mathematics, Tata McGraw-Hill, New Delhi, 2008.			
3.	B. V. Ramana, Higher Engineering Mathematics, Tata McGraw Hill, New I	Delhi, 2010.		
4.	N.P. Bali and M. Goyal, A text book of Engineering Mathematics, Laxmi Publications, 2010.			
5.	E. Kreyszig, Advanced Engineering Mathematics, John Wiley & Sons, 2006.			

Course Code BMEP181T20 Credits Course Category ESC	3003			
OBJECTIVES				
· · · · · · · · · · · · · · · · · · ·				
To familiarize the basics laws of physics, vector operations and forces.				
• To understand the principles of beams, supports and equilibrium of rigid bodies.				
To know the area and mass property calculations of various sections and solids.				
To study and analyse the dynamics of particles by various methods.				
To understand the applications of friction and rigid body dynamics.				
UNIT-I STATICS OF PARTICLES	9			
Introduction - Laws of Mechanics - Lami's theorem, Parallelogram and triangular Law of forc	es, Principle of			
transmissibility, Vectors - Vectorial representation of forces and moments - Vector operation	ons: additions,			
subtraction, dot product, cross product - Coplanar Forces - Resolution and Composition	n of forces -			
Equilibrium of a particle - Forces in space - Equilibrium of a particle in space - Equivalent syste	ems of forces			
- Single equivalent force.				
UNIT-II EQUILIBRIUM OF RIGID BODIES	9			
Free body diagram - Types of supports and their reactions - requirements of stable equilibriu	ım – Moments			
and Couples - Moment of a force about a point and about an axis - Vectorial representation of				
couples - Scalar components of a moment - Varignon's theorem - Equilibrium of Rigid bodies	n two			
dimensions – Equilibrium of Rigid bodies in three dimensions – Examples				
UNIT-III PROPERTIES OF SURFACES AND SOLIDS	9			
Determination of Area and Volume - First moment of area and the Centroid of sections - Re	ctangle, circle,			
triangle from integration - T section, I section, - Angle section, Hollow section by using stand	lard formula –			
second and product moments of plane area - Rectangle, triangle, circle from integration - T sec	ction, I section,			
Angle section, Hollow section by using standard formula - Parallel axis theorem and perp	endicular axis			
theorem - Polar moment of inertia - Principal moments of inertia of plane areas - Principal a	xes of inertia -			
Mass moment of inertia - Derivation of mass moment of inertia for rectangular section, prism,	sphere from			
first principle – Relation to area moment of inertia.				
UNIT-IV DYNAMICS OF PARTICLES	9			
Displacements, Velocity and acceleration, their relationship - Relative motion - Curviline	ar motion –			
Newton's law - Work Energy Equation of particles - Impulse- Momentum principle - Impact of e	lastic bodies.			
UNIT-V FRICTION AND RIGID BODY DYNAMICS	9			
Frictional force – Laws of Coloumb friction – simple contact friction – Rolling resistance – Belt f	riction-Ladder			
friction- Translation and Rotation of Rigid Bodies – Velocity and acceleration – General Plane mo				
CO COURSE OUTCOMES	PO			
Upon completion of this course, Students should be able to				
1. Get familiarized with the basic laws of physics, vector operations and forces. PO1				
2. Understand the principles of beams, supports and equilibrium of rigid bodies. PO1, PO2				
3. Calculate the area and mass properties of various sections and solids.	PO1, PO2			
4. Know about dynamics of particles and their analysis by various methods.	PO1, PO2, PO3			
5. Know about the applications of friction and rigid body dynamics.	PO1, PO2			

TEXT BO	OK		
1.	Rajasekaran, S, Sankarasubramanian, G., "Fundamentals of Engineering Mechanics",		
1.	Vikas Publishing House Pvt. Ltd., (2007), 3 rd Edition.		
2.	Beer, F.P and Johnson Jr. E.R. "Vector Mechanics for Engineers", Vol. 1 Statics and Vol. 2		
	Dynamics, Tata McGraw-Hill International Edition, 2017, 11 th edition		
REFERENCES			
1.	Hibbeler, R.C., "Engineering Mechanics", Vol. 1 Statics, Vol. 2 Dynamics, Pearson		
1.	Education Asia Pvt. Ltd., (2017).		
2.	Palanichamy, M.S., Nagam, S., "Engineering Mechanics - Statics & Dynamics", Tata		
۷.	McGraw-Hill, (2001).		
3.	Irving H. Shames, "Engineering Mechanics – Statics and Dynamics", IV Edition –		
5.	Pearson Education Asia Pvt. Ltd., (2008).		
4	Ashok Gupta, "Interactive Engineering Mechanics – Statics – A Virtual Tutor		
4.	(CDROM)", Pearson Education Asia Pvt., Ltd., (2002).		
5.	K.L. Kumar, "Engineering Mechanics" Tata McGraw-hill, 2017, 4 th Edition		
6.	S.S. Bhavikatti, "Engineering Mechanics", New Age International Publishers, 2006		
7.	R. S. Khurmi, "Engineering Mechanics", S. Chand Publishers, 2018.		

Course Title	ENGINEERING THERMODYNAMICS	Cradita	LTPC
Course Code	BMEP181T30	Credits	3003
Course Category	PCC		
	OBJECTIVES		
	t the basic concepts of thermodynamics & first law of thermo		
	it application of II law and to understand the concept of en	itropy/ava	ilability
	ne changes in properties of pure substances		
	d various thermodynamic relations & ideal gas concept		
To learn abou	t the concept of psychrometry		
UNIT - I BASI	C CONCEPTS AND FIRST LAW		9
– Thermodynamic Quasi- static, reve thermodynamics	uum- microscopic and macroscopic approach-Path and point is system and their types - Thermodynamic Equilibrium - Sta ersible and irreversible processes - Modes of work - P-V dia – Concept of temperature & heat - First law of thermodyn ystems – steady and unsteady flow processes	ate, path ar agram - Ze	nd process - roth law of
UNIT- II SEC	COND LAW & AVAILABILITY ANALYSIS		9
Applications of II irreversibility. Exp	lity. Concept of entropy, entropy of ideal gas - Principle of Law. Available and non-available energy of a source and fir pressions for the energy of a closed system and open system ration. Irreversibility. I and II law Efficiency	nite body. I	Energy and
UNIT - III PROPI	ERTIES OF PURE SUBSTANCE AND STEAM POWER CY	CLE	9
Use of Steam Tabl	n & its thermodynamic properties - P-v, P-T, T-v, T-s, h-s dia e & Mollier Chart - Application of I and II law for pure substa ycle Improvement Methods - Reheat and Regenerative cycles	ances. Ideal	
	GAS & THERMODYNAMIC RELATIONS		9
	l gas- Ideal and real gas comparison- Equations of state for id	lool and roo	-
Reduced propertie Calculations. Maxwell relations	, Tds equations, Specific heat capacities - Energy equation - J -Clapeyron equation – Third law of thermodynamics.	rt Simple	
UNIT V PSY	CHROMETRY		9
Sensible heating a	operties - Psychrometric chart - Psychrometric processes – Ac nd cooling, humidification, dehumidification, Evaporative co ums - Property calculations		

СО	COURSE OUTCOMES	РО		
Upon com	pletion of this course, Students should be able to			
1.	Apply the first law of thermodynamics for simple open and closed systems under steady and unsteady conditions.	PO1, PO2		
2.	Apply second law of thermodynamics to open and closed systems and calculate entropy and availability	PO1, PO2		
3.	Apply Rankine cycle to steam power plant and compare few cycle improvement methods.	PO2, PO3		
4.	Derive simple thermodynamic relations of ideal and real gases.	PO1		
5.	Calculate the properties of gas mixtures and moist air and its use in psychrometric processes.	PO1, PO2		
TEXT BOC	<u>K</u>			
1.	Yunus A, Cengel & Michael A. Boles, "Thermodynamics – An Engineering Appro	oach", McGraw		
	Hill Education, 8 th edition, 2017.			
REFEREN	CES			
1.	Arora C.P, "Thermodynamics", Tata McGraw-Hill, New Delhi, 2012.			
2.	Borgnakke & Sonnatag, "Fundamental of Thermodynamics", John Wiley, 8 th edition, 2016.			
3.	Chattopadhyay P, "Engineering Thermodynamics", Oxford University Press, 2016.			
4.	J.P Holman, Thermodynamics – Tata McGraw Hill, 2012, 9 th edition.			
5.	Nag. P. K., "Engineering Thermodynamics", 6th edition, Tata McGraw-Hill, New	[,] Delhi, 2017.		
6.	Vanwylen & Sonntag, Introduction to Thermodynamics, Classical & Statistical – Wiley Eastern, 2007, 4 th edition.			

Course Tit	le BASIC ELECTRONICS ENGINEERING	3	Creadita	LTPC
Course Co	de BMEP181T40		Credits	3003
Course Cat	egory ESC			
	OBJECTIVES			
• To pro	vide an overview of electronic device components to	Mechanical engineer	ring student	5.
UNIT-I: Sei	niconductor Devices and Applications			9
	n to P-N junction Diode and V-I characteristics, Half		-	L
	e and its characteristics, Zener diode as voltage reg		•	
	XX series, Introduction to BJT, its input-output and tr	ansfer characteristics	s, BJT as a sir	igle stage
	r, frequency response and bandwidth.			
	perational amplifier and its applications			9
Introduction to operational amplifiers, Op-amp input modes and parameters, Op-amp in open loop configuration, op-amp with negative feedback, study of practical op-amp IC 741, inverting and non-inverting amplifier applications: summing and difference amplifier, unity gain buffer, comparator, integrator and differentiator.				
UNIT-III: Timing Circuits and Oscillators 9				
0	ircuits, IC 555 and its applications as astable and more s criteria for oscillation, R-C phase shift and Wein br		itors, positiv	e feedback,
UNIT-IV: I	igital Electronics Fundamentals			9
Difference between analog and digital signals, Boolean algebra, Basic and Universal Gates, Symbols, Truth tables, logic expressions, Logic simplification using K- map, Logic ICs, half and full adder/subtractor, multiplexers, demultiplexers, flip-flops, shift registers, counters, Block diagram of microprocessor/microcontroller and their applications.				
UNIT-V: El	ectronic Communication Systems			9
The elements of communication system, IEEE frequency spectrum, Transmission media: wired and wireless, need of modulation, AM and FM modulation schemes, Mobile communication systems: cellular concept and block diagram of GSM system.				
СО				PO
Upon comp	letion of this course, Students should be able to		I	
1.	Understand the principles of semiconductor device		ons.	PO1, PO2
2.	Design an application using Operational amplifier.			PO2
3.	Understand the working of timing circuits and osci			PO1, PO2
4.	Understand logic gates, flip flop as a building block	,		PO1, PO2
5.	Learn the basics of Electronic communication syste	m		PO1

TEXT BOC	0K
1.	Floyd ," Electronic Devices" Pearson Education 9th edition, 2012.
2.	R.P. Jain, "Modern Digital Electronics", Tata Mc Graw Hill, 3rd Edition, 2007.
3.	Frenzel, "Communication Electronics: Principles and Applications", Tata Mc Graw Hill, 3rd
	Edition, 2001
REFEREN	CES
1.	Floyd ," Electronic Devices" Pearson Education 9th edition, 2012.
2.	R.P. Jain, "Modern Digital Electronics", Tata Mc Graw Hill, 3rd Edition, 2007.
3.	Frenzel, "Communication Electronics: Principles and Applications", Tata Mc Graw Hill, 3rd
	Edition, 2001

Course Title MATERIALS ENGINEERING	LTPC			
Course Code BMEP181T50 Cred	3003			
Course Category PCC				
OBJECTIVES				
Understanding of the correlation between the internal structure of materials, their mecha	anical properties			
and various methods to quantify their mechanical integrity and failure criteria.				
To provide a detailed interpretation of equilibrium phase diagrams.				
• Learning about different phases and heat treatment methods to tailor the properties of F	e-C alloys.			
UNIT-I: Crystal Structure	9			
Unit cells, Metallic crystal structures, Ceramics. Imperfection in solids: Point, line, interfacial	and volume			
defects; dislocation strengthening mechanisms and slip systems, critically resolved shear stre	SS.			
UNIT-II: Mechanical Property measurement	9			
Tensile, compression and torsion tests; Young's modulus, relations between true and engined	ering stress-strain			
curves, generalized Hooke's law, yielding and yield strength, ductility, resilience, tough	ness and elastic			
recovery; Hardness: Rockwell, Brinell and Vickers and their relation to strength. Fra-	cture mechanics:			
Introduction to Stress-intensity factor approach and Griffith criterion. Fatigue failure: High c				
Stress-life approach, SN curve, endurance and fatigue limits, Introduction to nondestructive	testing (NDT).			
UNIT-III: Alloys, Substitutional and interstitial solid solutions-Phase diagrams	9			
Interpretation of binary phase diagrams and microstructure development; eutectic, peritectic	-			
monotectic reactions. Iron-carbon phase diagram and microstructure aspects of ledeburite, at	istenite, ferrite			
and cementite, cast iron.				
UNIT-IV: Heat treatment of Steel	9			
Annealing, tempering, normalizing and spheroidising, isothermal transformation diagrams for				
microstructure development. Continuous cooling curves and interpretation of final mic				
properties- austempering, martempering, case hardening, carburizing, nitriding, cyaniding, carbo-nitriding,				
flame and induction hardening, vacuum and plasma hardening. UNIT-V: Metals and Alloys	9			
Alloying of steel, properties of stainless steel and tool steels, maraging steels- cast irons; grey,	white, malleable			
and spheroidal cast irons- copper and copper alloys; brass, bronze and cupro-nickel; Alumin				
Mg alloys- Nickel based super alloys and Titanium alloys.				
CO COURSE OUTCOMES	РО			
Upon completion of this course, Students should be able to				
1. Identify crystal structures for various materials and understand the defects in	PO1, PO2			
such structures.	101,102			
2. Understand how to tailor material properties of ferrous and non-ferrous alloys	PO1, PO2			
and how to quantify mechanical integrity and failure in materials				
 Understand the micro structural aspects and phases of Fe-C systems. Understand the various heat treatment process. 	PO4 PO2			
 Understand the various heat treatment process. properties and applications of ferrous and non ferrous metals. 	PO2			
5. properties and applications of ferrous and non ferrous metals.	PO1, PO2			

TEXT BOO	K
1.	W. D. Callister, 2006, "Materials Science and Engineering-An Introduction", 6th Edition, Wiley
	India.
2.	Kenneth G. Budinski and Michael K. Budinski, "Engineering Materials", Prentice Hall of India
	Private Limited, 4 th Indian Reprint, 2002.
3.	V. Raghavan, "Material Science and Engineering', Prentice Hall of India Private Limited, 2004,
	5 th Edition.
4.	U. C. Jindal, "Engineering Materials and Metallurgy", Pearson, 2011.
REFERENC	CES
1.	W. D. Callister, 2006, "Materials Science and Engineering-An Introduction", 6th Edition, Wiley
	India.
2.	Kenneth G. Budinski and Michael K. Budinski, "Engineering Materials", Prentice Hall of
	India Private Limited, 4th Indian Reprint, 2002.
3.	V. Raghavan, "Material Science and Engineering', Prentice Hall of India Private Limited,
	2004, 5th Edition.
4.	U. C. Jindal, "Engineering Materials and Metallurgy", Pearson, 2011.

SEMESTER - II

Course Titl		MATHEMATICS - II Calculus, Ordinary Differential Equations, and Complex Variables)	Credits	LTPC
Course Cod		3MEP182T10	Creuns	3104
Course Cate	egory	BSC		
		OBJECTIVES		
par • To e	tial differ equip the	te the prospective engineers with techniques in multivariate integrential equations and complex variables. Is students to deal with advanced level of mathematics and applic their disciplines.		,
		ble Calculus (Integration)		9
-	0	Double and Triple integrals (Cartesian) - Change of order of integrals on Green, Gauss and Stokes theorems.	egration ir	n double
UNIT-II: O	rdinary I	Differential Equations of Higher Orders		9
-	rential e	or finding complementary function – Rules for finding particula quations with variable coefficients: Cauchy-Euler equation -	0	
UNIT-III: P	Partial Di	fferential Equations of Higher Orders		9
differential	equation	Differential Equations- Formation of Partial differential equatio -Linear equations of the first order - Solution to homogenous and puations of second order by complementary function and particu	non-hom	ogenous linear
UNIT-IV: C	Complex	Variable – Differentiation		9
		chy-Riemann equations - Analytic functions - Harmonic functior al mappings: $z+c$, $1/z$, cz , z^2 , $z+1/z$, e^z - Mobius transformations		,
		ariable – Integration		9
Taylor's ser	ries - Lau	Cauchy - Goursat theorem (without proof) - Cauchy Integral fourent's series - Zeros of analytic functions –singularities – Respoof) – Simple problems.	•	± /
CO		COURSE OUTCOMES		РО
Upon comp		this course, Students should be able to		
1.	volum gives t	the concept of double, triple integration and allow to compute the e and surface area for the given shapes and the three main the he relation between them. Change of order of integration enables ntegration simpler.	eorems P	01, PO2, PO5, 07
2.		fective mathematical tools for the solutions of differential equation physical processes		01, PO2, 03, PO7, PO12
3.	Solve f	ield problems in engineering involving PDEs.		O1, PO2, PO5, O7, PO11, O12
4.		ols of differentiation of functions of a complex variable that are u s techniques dealing engineering problems.	sed in	01, PO2, PO7
5.	Know Mecha	that complex integration is used in various techniques dealing nical engineering problems for mechanical vibration, and in quar nics and electromagnetism.	ntum P	01, PO2, PO7

TEXT BOC	KS
1.	B.S. Grewal, Higher Engineering Mathematics, Khanna Publishers, 36th Edition, 2010.
2.	Erwin kreyszig, Advanced Engineering Mathematics, 9th Edition, John Wiley & Sons, 2006
3. G.B. Thomas and R.L. Finney, Calculus and Analytic geometry, 9th Edition, Pearso	
5.	2002.
REFERENC	CES
1.	W. E. Boyce and R. C. DiPrima, Elementary Differential Equations and Boundary Value
1.	Problems, 9th Edition, Wiley India, 2009.
2.	S. L. Ross, Differential Equations, 3 rd Ed., Wiley India, 1984.
3.	N.P. Bali and Manish Goyal, A text book of Engineering Mathematics, Laxmi Publications,
3.	Reprint, 2008.

Course Tit	tle AP	PLIED T	THERMODYNAMICS	Cruchita	LTPC
Course Co	de BM	EP182T2	0	Credits	3003
Course Cat	egory		PCC		
			OBJECTIVES		
	apply the co gram of vari		thermodynamics to steam Nozzle & to understand th ines	e velocity tr	riangle
	U U		us systems of I.C. Engines		
• To	analyse the	different	gas power cycles		
• The	e principles o	of recipro	cating & rotary air compressors are studied		
• To	apply the co	ncepts of	thermodynamics to refrigeration & Air conditioning	r >	
UNIT- I Flo	ow Through	Nozzle &	& Steam Turbines		9
			hrough nozzle - Nozzle types - Critical pressure ratio	o – Nozzle e	fficiency -
	ated flow in				2
-			inciples - Compounding - Types - Velocity diagrams lations - Governors.	for simple a	ind
UNIT-II I.		ceuregu			9
	e	σ Princin	le - Components and their function. Valve timing &	b port timir	-
actual and t injector sys	heoretical p- tem - Ignitio	V diagrai n System	m of four stroke and two stroke engines. Simple Carb - Principles of Combustion and knocking in SI and C Performance calculations.	urettor Dies	
	as Power Cy				9
Air Standard Cycles - Otto, Diesel, Dual & Brayton cycle Analysis – methods of cycle improvement.					
	•		ed cycles and their combinations -Performance Calcu	-	
UNIT-IV A	Air Compres	sors			9
- Single and		compres	Classifications - Working principle – work done - Ef sors, Volumetric efficiency – calculation of power req		
UNIT-V R	UNIT-V Refrigeration & Air Conditioning 9				9
Refrigeration cycles- Reversed Carnot – Bell Coleman cycle - Vapour compression system –Super heating/Sub cooling - Vapour absorption refrigeration system- Properties of refrigerants. – Simple Problems on VCR system Principles of air-conditioning - Types of A/C Systems –Industrial, Summer, Winter - Comfort and Year-round air conditioners – Window & Centralised A/C - Concept of GSHF – RSHF – ESHF.					
air conditio		ow & Cer	ntralised A/C - Concept of GSHF – RSHF – ESHF.		r rear-round
air conditio		ow & Cer	ntralised A/C - Concept of GSHF - RSHF - ESHF. COURSE OUTCOMES		PO
СО	ners – Wind		_		
СО	ners – Wind letion of this Analyse tl	s course, s ne proble	COURSE OUTCOMES Students should be able to ms of nozzles & turbines.		
CO Upon comp	ners – Wind letion of this Analyse tl	s course, S ne proble ne functio	COURSE OUTCOMES Students should be able to	rmance	РО
CO Upon comp 1.	ners – Wind Detion of this Analyse th Explain th of I.C. Eng	s course, s ne proble le functio gines.	COURSE OUTCOMES Students should be able to ms of nozzles & turbines.	rmance	PO PO2
CO Upon comp 1. 2.	ners – Wind detion of this Analyse th Explain th of I.C. Eng Analyse &	s course, s ne proble le functio gines. t solve the ne perform	COURSE OUTCOMES Students should be able to ms of nozzles & turbines. ning & features of I.C. Engines & Calculate the perfor	rmance	PO PO2 PO2, PO4

TEXT BOO	K
1.	Kothandaraman.C.P., Domkundwar. S, Domkundwar. A.V., "A course in thermal Engineering",
	Fifth Edition, "Dhanpat Rai & sons , 2016
2.	Rajput. R. K., "Thermal Engineering" S. Chand Publishers, 2017
REFERENC	CES
1.	Arora.C.P, "Refrigeration and Air Conditioning," Tata McGraw-Hill Publishers 2017
2.	Ganesan V" Internal Combustion Engines", 3rd Edition, Tata McGraw-Hill 2017
3.	Rudramoorthy, R, "Thermal Engineering ", Tata McGraw-Hill, New Delhi, 2003
4.	Sarkar, B.K,"Thermal Engineering" Tata McGraw-Hill Publishers, 2007
5.	P. L. Ballaney, Thermal Engineering, Khanna Publishers, 2007, 24th Edition.

Course Title FLUID MECHANICS & MACHINERY		LTPC	
Course Code BMEP182T30	Credits	3003	
Course Category PCC			
OBJECTIVES			
• To understand the properties of fluids and concept of control volume.			
• To understand the applications of the conservation laws to flow through pip	es.		
To understand the importance of dimensional analysis			
• To understand the importance of various types of flow in pumps.			
• To understand the importance of various types of flow in turbines.			
UNIT-I FLUID PROPERTIES & FLOW CHARACTERISTICS		9	
Units and dimensions - Types of flows - Properties of fluids - mass density, specific specific gravity, viscosity, compressibility, vapor pressure – Gas laws - Surface tensi characteristics – concept of control volume – Bernoulli's Theorem – Concept of contro of continuity equation, energy equation, momentum equation and moment of moment	ion and capi l volume – A	llarity. Flow pplication	
UNIT - II FLOW THROUGH CIRCULAR CONDUITS		9	
Hydraulic and energy gradient - Laminar flow through circular conduits and circula energy gradient-Boundary layer concepts – types of boundary layer thickness – Da friction factor- Moody diagram- commercial pipes- minor losses – Flow through pipe	rcy Weisbac	h equation –	
UNIT-III-DIMENSIONAL ANALYSIS		9	
Dimensional analysis – methods of dimensional analysis - Similitude –types of similit parameters- Application of dimensionless parameters – Model analysis	tude – Dimei	nsionless	
UNIT-IV HYDRAULIC PUMPS		9	
Impact of jets - Euler's equation - Theory of roto-dynamic machines – various efficien - Centrifugal pumps– Multi stage centrifugal pumps - working principle - work performance curves – Priming – Cavitation - Reciprocating pump- working principle diagram - Rotary pumps – Working Principles.	done by th	e impeller -	
UNIT-V HYDRAULIC TURBINES		9	
Hydraulic turbines – Classification - working principles - Pelton wheel, Kaplan turbine - Francis turbine - velocity triangles - theory of draft tubes – Performance – Specific speed – Unit Quantities - Selection of turbines - governing of turbines - hydraulic coupling - Torque converter			
COCOURSE OUTCOMESPO			
Upon completion of this course, Students should be able to			
1. Apply mathematical knowledge to predict the properties and characteria a fluid.	stics of	PO1, PO2	
2. Analyse and calculate major and minor losses associated with pipe flow piping networks.	in	PO1, PO2	
3. Mathematically predict the nature of physical quantities		PO1, PO2	
4. Analyse the performance of pumps		PO2	
5. Analyse the performance of turbines		PO2	

TEXT BOC)K
1.	K.L. Kumar, Engineering Fluid Mechanics, S. Chand Publishing, 2016.
2.	Modi P.N. & Seth, S.M. "Hydraulics and Fluid Mechanics", Standard Book House, New Delhi 2013.
REFERENC	CES
1.	S. K. Som, G. Biswas, S Chakraborty, Introduction to Fluid Mechanics and Fluid Machines, Tata
1.	McGraw Hill, 2008, 3 rd Edition.
2.	K. R. Arora, Fluid Mechanics Hydraulics and Hydraulic Machines, Standard Publishers, 2007, 9th
Ζ.	Edition.
3.	C. P. Kothandaraman & R. Rudramoorthy. Fluid Mechanics and Machinery, New Academia
5.	Science, 2011, 3 rd Edition.
4.	Douglas J.F, Solving Problems in Fluid Mechanics Vol I & II, John Wiley & Sons Inc., 1986.
5.	Victor L. Streeter and E. Benjamin Wylie & Keith W.Bedford. Fluid Mechanics, Mc Graw-Hill 1999,
5.	8 th Edition.

Course Ti	tle STRENGTH OF MATERIALS	Cristia	LTPC
Course Co	de BMEP182T40	Credits	3003
Course Cat	regory PCC		
	OBJECTIVES		
• To u	nderstand the nature of stresses developed in simple and composite bars.		
• To u	nderstand the nature of stresses developed in beams.		
• To u	nderstand the slope and deflection developed in beams.		
• To c load	alculate the elastic deformation occurring in various simple geometries for ing.	different ty	pes of
• To u load	nderstand the nature of stresses developed in cylinders and spheres for va s.	rious types	of simple
UNIT - I SI	IMPLE STRESS AND STRAIN		9
	n in solids- Hooke's law- stress and strain -tension, compression and shea c constants and their relations-Volumetric, linear and shear strains.	ar stresses-	composite
UNIT - II S	HEAR FORCE AND BENDING MOMENT DIAGRAM		9
supports-S	types-Transverse loading on beams- shear force and bend moment dia imply supported, over-hanging beams and cantilevers- Theory of bending and neutral axis-shear stress distribution- point and distributed loads.	•	-
UNIT – III	DEFLECTION OF BEAMS		9
	of a beam using double integration method, moment area method and mac n of slopes and deflection in beams–Maxwell's reciprocal theorems.	aulay's met	hod-
UNIT – IV	TORSION OF SHAFT AND SPRINGS		9
	resses and deformation in circular and hollow shafts- stepped shafts-Defle Stresses and deflection of helical springs, laminated spring - principal stres hr's circle.		
UNIT – V	THIN AND THICK CYLINDER		9
	oop stresses in cylinders subjected to internal pressure-Deformation of thi n in spherical shells subjected to internal pressure.	ck and thin	cylinders-
СО	COURSE OUTCOMES		РО
Upon comp	pletion of this course, Students should be able to		
1.	Recognize various types loads applied on machine components of simpl composite bars.	le and	PO2, PO3
2.	Recognize the stresses developed on various types of beams.		
2.			PO2
3.	Recognize the slope and deflection developed on various types of beams		PO2 PO2, PO3
	Recognize the slope and deflection developed on various types of beams Evaluate the strains and deformation that will result due to the elastic st developed within the materials for simple types of loading.		

TEXT BOC	K
1.	S. Ramamrutham and R. Narayan, Strength of Materials, Dhanpat Rai and Sons, New Delhi.2007,
	15 th Editon.
2.	L.S. Srinath, Advanced Mechanics of Solids, Tata McGraw HIll, 2009, 3rd Edition
REFERENC	CES
1.	Beer & Johnson, Mechanics of materials, SI Metric Edition, McGraw Hill, ISE, 2017.
2.	Gere and Timensenko, Mechanics of Materials, CBS Publishers, 2006.
3.	S.P. Timoshenko J.N Goodier, Theory of Elasticity, Mc Graw Hill International Edition, 2017.
4.	S.M.A.Kazimi, Solid Mechanics, Tata McGraw Hill Publishing Company Ltd., 2004.
5.	Timoshenko & D.H. Young, J.V. Rao, Sukumar Pati, Engineering Mechanics, McGraw Hill, 2017.
6.	J. B. K Das & P.L. Srinivasa Murthy, Mechanics of Materials, Sapna Book House, 2018.

Course Title	INSTRUM	ENTATION AND CONT	ROL	Crallin	LTPC				
Course Code	BMEP182T5)		Credits	3003				
Course Category		PCC							
		OBJECTIVE	S						
• To provide a b	asic knowledg	ge about measurement syste	ms and their component	S					
• To learn about	various sense	ors used for measurement of	mechanical quantities						
• To identify the	e type of meas	uring instrument required f	or a specific application.						
• To learn about	system stabil	ity and control							
• To integrate th	e measureme	nt systems for process moni	toring and control						
UNIT – I					9				
General concept – (Generalised m	easurement system-Units ar	nd standards-measuring	instruments	sensitivity,				
		cision-static and dynamic re							
		roduction to Dimensional a							
UNIT – II					9				
PRESSURE MEAS	UREMENT: (Gravitational, Bourdon, Ela	astic transducers, strain	gauge, Pre	essure cells,				
Measurement of his	gh and low pr	essure, Dynamic characteris	tic of pressure measurin	g devices.					
TEMPERATURE N	MEASUREME	NT: Bi-metallic, pressure	and resistance thermo	meter, The	rmocouples,				
Pyrometer and The	ermistors, Cal	ibration. Pressure and temp	perature measurement ir	n rotating sy	stems – slip				
rings.		-			-				
FLOW MEASUREN	MENTS: Orific	e, flow nozzle, venturi, pitot	tube, rotometer, Turbine	type Anemo	ometer, Hot-				
wire anemometer, N	Magnetic flow	meter, Ultrasonic flow met	er - Calibration.						
DENSITY MEASU	REMENT: Phe	nometer, Hydrometer, diffe	rential bubbling, Liquid	level Measu	DENSITY MEASUREMENT: Phenometer, Hydrometer, differential bubbling, Liquid level Measurements.				
VISCOSITY: Capilla	ary tube visco	meter, efflux viscometer, fal	ling sphere viscometer, I	VISCOSITY: Capillary tube viscometer, efflux viscometer, falling sphere viscometer, Rotating cylinder					
viscometer.				Cotating Cyn					
HUMIDITY: Sling p	psychrometer,			cotating cyn					
UNIT – III		Absorption hydrometer, De	ew point meter.						
CTD AINI, Churchen and		Absorption hydrometer, De	ew point meter.						
prikany: Strain gat	1ges, types, su	Absorption hydrometer, De			nder 9				
compensation, Gau	0 1	rfaces preparation and bond			nder 9				
compensation, Gau	ge rosettes, C	rfaces preparation and bond	ling technique, Wheatstc	one Circuit, T	nder 9 [°] emperature				
compensation, Gau	ge rosettes, Ca MENT: Scales	rfaces preparation and bond alibration.	ling technique, Wheatstc	one Circuit, T	nder 9 [°] emperature				
compensation, Gau FORCE MEASURE pneumatic load cell	ge rosettes, Ca MENT: Scales ls.	rfaces preparation and bond alibration.	ling technique, Wheatstc neter, Strain gauge, Load	one Circuit, T cells Hydra	nder 9 Temperature ulic and				
compensation, Gau FORCE MEASURE pneumatic load cell	age rosettes, Ca MENT: Scales ls. REMENT: Mec	rfaces preparation and bond alibration. and balance, Elastic force n	ling technique, Wheatstc neter, Strain gauge, Load	one Circuit, T cells Hydra	nder 9 Temperature ulic and				
compensation, Gau FORCE MEASURE pneumatic load cell TORQUE MEASUF	age rosettes, Ca MENT: Scales ls. REMENT: Mec	rfaces preparation and bond alibration. and balance, Elastic force n	ling technique, Wheatstc neter, Strain gauge, Load	one Circuit, T cells Hydra	nder 9 Temperature ulic and				
compensation, Gau FORCE MEASURE pneumatic load cell TORQUE MEASUF gauge torsion meter UNIT - IV	ige rosettes, Ca MENT: Scales Is. REMENT: Med r.	rfaces preparation and bond alibration. and balance, Elastic force n	ling technique, Wheatsto neter, Strain gauge, Load cal torsion meter, Electric	one Circuit, T cells Hydra al torsion m	nder 9 Cemperature ulic and eter, Strain 9				
compensation, Gau FORCE MEASURE pneumatic load cell TORQUE MEASUF gauge torsion meter UNIT - IV CONTROL SYSTEM	ge rosettes, Ca MENT: Scales ls. REMENT: Med r. MS: Open and	rfaces preparation and bond alibration. and balance, Elastic force n hanical torsion meter, Optic	ling technique, Wheatsto neter, Strain gauge, Load cal torsion meter, Electric anisms, Transfer function	one Circuit, T cells Hydra al torsion m	nder 9 Cemperature ulic and eter, Strain 9 v graphs,				
compensation, Gau FORCE MEASURE pneumatic load cell TORQUE MEASUF gauge torsion meter UNIT - IV CONTROL SYSTEM	ge rosettes, Ca MENT: Scales Is. REMENT: Med r. MS: Open and bra, Hydrauli	rfaces preparation and bond alibration. and balance, Elastic force n hanical torsion meter, Optic closed systems, Servomech c and pneumatic control sys	ling technique, Wheatsto neter, Strain gauge, Load cal torsion meter, Electric anisms, Transfer function	one Circuit, T cells Hydra al torsion m	nder 9 Cemperature ulic and eter, Strain 9 v graphs,				

Time response of first order and second order systems. Concept of stability. Necessary Condition for stability, Routh stability constraint, Polar and Bode plots, Nyquist stability Criterion. Simple problems.

CO	COURSE OUTCOMES	РО		
Upon completion of this course, Students should be able to				
1.	Understand the measurement of various quantities using instruments.	PO1		
2.	Understand the types of sensors used in mechanical systems	PO1, PO2		
3.	Understand their accuracy & range of usage of the instrument	PO1, PO2		
4.	Understand the techniques for controlling devices automatically.	PO1, PO2		
5.	Understand the techniques used in process monitoring and control systems.	PO1, PO2		
TEXT BOO	K			
1.	Instrumentation and control systems by W. Bolton, 2 nd edition, Newnes, 2000			
2.	Thomas G. Beckwith, Roy D. Marangoni, John H. LienhardV , Mechanical Meas Edition), Pearson Education India, 2007	urements (6 th		
3.	Gregory K. McMillan, Process/Industrial Instruments and Controls Handbook, Tata McGraw-Hill: New York, 1999.	Fifth Edition,		
REFERENC	TES			
1.	B.G. KUO, Automatic Control Systems, Tata McGraw Hill, ISE.			
2.	D' AZZO AND HOUPIS, Feedback Control Systems - Analysis and synthesis, Ta ISE.	ata McGraw Hill.		
3.	KUMAR. D.S. Mechanical Measurements & Control, Metropolitan Book Co., 198	39		
4.	SIROHI RS. & RADHAKRISHNAN H.C, Mechanical Measurement, New Age In Ltd., 2005, 3 rd Edition.	nternational (P)		
5.	RANGAN C.S, SARMA G.S & MANI VSV, Instrumentation Device and Systems	s, TMH, 1989		
6.	DOEBLIN, Measurement Systems Application and Design, TMH, 1990			
7.	A. K. Sawhney, Mechanical Measurements and Instrumentation, Dhanpat Rai & Ltd, 2007, 12 th Edition			
8.	R.K. Jain, Mechanical and Industrial Measurements, Khanna Publishers, 2004, 1	2 th Edition.		
9.	M. Gopal, Control Systems, TMH, 2007, 2 nd Edition.			

SEMESTER – III

Course Tit	le	HEAT AND MASS TRANSFER	Carlin	LTPC
Course Co	de	BMEP183T10	Credits	3003
Course Cate	egory	PCC		
		OBJECTIVES		
• To und	lerstand	the mechanisms of conduction heat transfer under steady and tran	sient condi	tions.
• To und	lerstand	the mechanisms of convection heat transfer and boundary layer co	ncept.	
To lear	n the th	ermal analysis and sizing of heat exchangers.		
• To lear	n the co	ncepts of radiative heat transfer & its related laws.		
• To lear	n the ba	sic concepts of mass transfer.		
UNIT - I CO	ONDUC	TION		9
		equation of Heat Conduction- Cartesian and Polar Coordinates -	One Dimer	sional
		onduction planeand Composite Systems - Conduction with Inte		
		s – Unsteady Heat Conduction – Lumped Analysis – Semi Infinite an		
of Heisler's				
UNIT - II C	ONVE	CTION		9
Free and Fo	rced Co	nvection - Hydrodynamic and Thermal Boundary Layer. Free and	d Forced Co	onvection of
		Plates and Cylinders and Internal flow through tubes - Dimensio		
free convec	tion)			
UNIT - III I	PHASE	CHANGE HEAT TRANSFER AND HEAT EXCHANGERS		9
Nusselt's th	eory of	condensation - Regimes of Pool boiling and Flow boiling. Correlation	ons in boili	ng and
condensatic	on. Heat	Exchanger Types - Overall Heat Transfer Coefficient - Fouling Factor	tor - Analys	sis – LMTD
method - N	TU metl	nod.		
UNIT - IV I				9
-		on - Radiation laws - Grey body radiation - Shape Factor - Electrica	l Analogy ·	- Radiation
		through gases.		
UNIT - V M				9
	1	Diffusion Mass Transfer - Fick's Law of Diffusion - Steady state		
Convective Correlations		Transfer – Momentum, Heat and Mass Transfer Analogy –Con	vective M	ass Transfer
	s.	COURCE OUTCOMES		DO
CO	lation	COURSE OUTCOMES		PO
Upon comp		f this course, Students should be able to / heat conduction equations to different surface configurations und	or	
1.		y state and transient conditions and solve problems		PO1, PO2
		<i>y</i> free and forced convective heat transfer correlations to internal an	d	
2.		al flows through/over various surface configurations and solve		PO2, PO4
	proble	· · ·		-
	_	in the phenomena of boiling and condensation, apply LMTD and N		
3.		ods of thermal analysis to different types of heat exchanger configur	rations	PO2
		olve problems		
		in basic laws for Radiation and apply these principles to radiative h	neat	
4.				PO1, PO2
4.	transf	er between different types of surfaces to solve problems v diffusive and convective mass transfer equations and correlations		PO1, PO2

TEXT BOC	ОК
1.	Holman, J.P., "Heat and Mass Transfer", Tata McGraw Hill, 2000
2.	Yunus A. Cengel, "Heat Transfer A Practical Approach", Tata McGraw Hill, 5thEdition, 2015.
3.	R.C. Sachdeva, "Fundamentals of Engineering Heat & Mass transfer", New Age International Publishers, 2009.
REFERENC	CES
1.	Frank P. Incropera and David P. Dewitt, "Fundamentals of Heat and Mass Transfer", John Wiley & Sons, 1998.
2.	Kothandaraman, C.P., "Fundamentals of Heat and Mass Transfer", New Age International, New Delhi, 1998.
3.	Nag, P.K., "Heat Transfer", Tata McGraw Hill, New Delhi, 2002
4.	Ozisik, M.N., "Heat Transfer", Tata McGraw Hill Book Co., 1994.

Course Title KINEMATICS OF MACHINES	Creatite	LTPC			
Course Code BMEP183T20	Credits	3003			
Course Category PCC					
OBJECTIVES					
To understand the basic components and layout of linkages in the assembly	oly of a system / m	achine.			
• To understand the principles in analyzing the assembly with respect to th acceleration at any point in a link of a mechanism.	e displacement, ve	locity, and			
• To understand the motion resulting from a specified set of linkages, desig	n few linkage mec	hanisms and			
cam mechanisms for specified output motions.					
To understand the basic concepts of toothed gearing and kinematics of gea	r trains and the effe	cts of friction			
in motion transmission and in machine components.					
UNIT-I: Introduction to links, Pairs and Chains		9			
Links, Pairs, Chains, Mechanisms, Inversion of machines, Structure - Degrees					
chains. Velocity and acceleration: Velocity and acceleration of simple mechani					
Klein's constructions for slider crank chain oscillating cylinder and swivel bear	ring mechanisms.	Analytical			
solution for slider crank mechanisms.					
UNIT-II: Cams		9			
Introduction to Cams, Types of cams and followers, displacement, velocity &	acceleration curves	s for uniform			
velocity, uniform acceleration and retardation. SHM, cycloidal curves, lay ou					
above types with reciprocating and oscillating followers - knife edge rollers ar	nd flat faced follow	ers,			
cylindrical and face cams, polynomial cams, cams with special contours.					
UNIT-III: Theory of gearing		9			
Introduction to Toothed gears, law of gearing, minimum number of teeth, lengt	h of arc of contact, i	nterference.			
UNIT-IV: Gear trains		9			
Introduction to gear trains, Types, velocity ratio and torque calculation in epic	yclic gear trains an	d differential			
gear train.					
UNIT-V: Drives and Lubrication		9			
Belt and rope drives, single plate, multiple plate, cone clutches, power trans Theory of lubrication, hydrostatic and hydrodynamic bearings, frictional					
CO COURSE OUTCOMES		РО			
Upon completion of this course, Students should be able to					
1. Understand the basics of mechanism					
2. Calculate velocity and acceleration in simple mechanisms		PO1			
		PO1 PO2, PO4			
3. Develop CAM profiles					
3. Develop CAM profiles 4. Solve problems on gears and gear trains 5. Examine friction in machine elements		PO2, PO4			

TEXT BOC	DK
1.	Amitabh Ghosh and Ashok Kumar Mallik, Theory of mechanism and Machines – 3 nd Edition,
1.	Affiliated East West Press Limited, 2017.
2.	J.E.Shigley and J.J.Vicker Jr. Theory of Machines and Mechanism, 2 nd ed. Mc GrawHill ISE 1995
3.	R.S. Khurmi & Gupta. J.K, A text book of Theory of Machines, S. Chand & Co., 2008, 14th Edition.
REFEREN	CES
1.	J.Hannah and R.C Stephens, Mechanics of Machines – Edward Arnold, 1999.
2.	Beer & Johnston 11th Edition, Vector Mechanics for Engineers. McGraw Hill. ISE 2017.
3.	Thomas Bevan – 3rd Edition, The Theory of Machines – CBS, Pearson 2009.
4.	P.L.Ballaney, Theory of Machines, Khanna Publishers, 2005, 24th Edition.
5.	S.S.Rattan, Theory of Machines, Tata McGraw Hill, 2017, 2nd Edition, 2017.
6.	Rao .J.S. & Dukkipati. R.V. Mechanism and Machine Theory, 2nd ed. Wiley Eastern Ltd., 2007,
7.	Hamilton H. Mabie & Charles F. Reinnoltz, Mechanisms and Dynamics of Machinery, 4th ed. John Wiley & Sons, 1995
8.	Thomson W.T, Theory of Vibration and Applications, Prentice Hall Inc, 1997.
9.	Sadhu Singh, Theory of Machines, Pearson Education Ltd, 2011.
10.	Ashok G. Ambekar, Mechanism and Machine Theory, Eastern Economy Edition. 2007.
11.	John. J. Uicker, Theory of Machines and Mechanisms, Oxford University Press, 2008, 3rd Edition.

Course Tit	le MANUFACTURING PROCESSES	Credito	LTPC
Course Co	de BMEP183T30	Credits	3003
Course Cate	egory PCC		
	OBJECTIVES		
• T	o motivate and challenge students to understand the basic casting techni	ques.	
• T	o introduce the concepts of basic metal forming processes		
• T	o provide the concept and basic mechanics of metal cutting, working of s	standard mac	hine tools
	uch as lathe, shaping and allied machines, milling and drilling.		
	o learn the various joining process.		
• T	o learn the basic concepts of unconventional machining processes		
UNIT-I: CA	ASTING AND MOLDING		9
Sand casting	g – Sand moulds - Type of patterns – Pattern materials – Pattern allowanc	es – Types of	Moulding
sand - Prop	erties - Core making- Working principle of Special casting processes - Sh	ell, investmer	nt casting -
die casting -	- Centrifugal casting - Sand Casting defects - Inspection methods		
UNIT-II: M	IETAL FORMING PROCESSES		9
	g and cold working of metals - Forging processes - Open, impression		
	tics of the process – Types of Forging Machines – Typical forging operat		
	lling mills - Shape rolling operations - Defects in rolled parts - Principle		
	ring Principles of Extrusion - Types of Extrusion - Hot and Cold extrus	sion –– Equip	ment used
	SHEET METAL FORMING		9
	perations- Blanking-blank size calculation, draw ratio, drawing force, Pier	-	-
-	Stretch Forming, Deep Drawing, Shearing, Metal Spinning, Bending, Tub	-	-
-	& Coining, Types of Dies, Progressive, Compound and Combination die	-	
-	Forming, Electro Hydraulic Forming, Electro Magnetic Forming, Dyn	apack Machi	ne, Rubber
	Iper Plastic Forming.		0
-	OINING/FASTENING PROCESSES	· · · · · · · · · · · · · · · · · · ·	9
	ling processes – Types of Gas welding – Equipments used – Flame chara		
	Arc welding equipments - Electrodes – Coating and specifications – Princip	-	-
	, seam welding – Gas metal arc welding – Flux cored – Submerged a		
0	IG welding – Principle and application of special welding processes - Plas ng – Friction welding – Diffusion welding – Weld defects – Brazing and sc		0
	and process capabilities – Filler materials and fluxes – Types of Adhesive	01	288
	nconventional Machining Processes	bonung.	9
	n, Classification, Applications, Benefits Abrasive Jet Machining, Water	Iet Machinii	,
	achining, Ultrasonic Machining, principles and process parameters Electr		
	d processes parameters, MRR, surface finish maskant, process parameter		e iviaciming,
	sh. Laser Beam Machining (LBM), Plasma Arc Machining (PAM) and Elec		lachining
CO	COURSE OUTCOMES		PO
	letion of this course, Students should be able to		
1.	Apply the concepts of different metal casting processes, associated defe	ects	PO2
2.	Gain the knowledge in various metal forming processes.		PO2
3.	Understand the sheet metal and forming processes.		PO2, PO3
4.	Understand the application of welding process		PO2
	Understand the different unconventional Manufacturing Methods emp	oloyed	
5.	for making different products.		PO1, PO2

TEXT BOO	K
1.	Kalpakjian and Schmid, Manufacturing processes for engineering materials (5th Edition)- Pearson
	India, 2014
2.	Mikell P. Groover, Fundamentals of Modern Manufacturing: Materials, Processes, and Systems,
	Wiley, 3 rd Edition, 2009.
3.	J.T. Black & Ronald A. Kohser, Degarmo's Materials and Processes in Manufacturing, John Wiley
	& Sons, 12th Edition 2017.
REFERENC	CES
1.	Banga T.R, Agarwal. R.K. & Manghrani. T.M., "Foundry Engineering", Khanna Publishers, New
	Delhi, 1995
2.	Jain.R.K. "Production Technology" Khanna Publishers, 1988
3.	Bhattacharyya.A. "Metal Cutting Theory and Practice", Central Book Publishers, 1984
4.	S. K. Hajra Chowdhery, & A. K. Hajra Chowdhery, Elements of Workshop Technology, Vol 1 &
	2, Media Promoters and Publishers, 2007, 14th Edition.

			ING ECONOMICS		Credits	LTPC
Course Co	de	BMEP183T4			Cleuits	3003
Course Cate	egory		HSMC			
			OBJECTIVES			
• To	understa	ind about the	basic principles and methodologies of	economics su	ich as dema	nd-supply,
0		t policies, tax				
	-	0	public sector economics which include			·
		-	ance of managerial economics and var		e	
		-	of process planning and cost estimation	-	-	ics.
	understa	ind the proce	ure followed in economics of different	t machining	operations.	-
UNIT – I						9
	-		y of Economics. Demand/Supply – e	-		
		5	m and Market Structure. Basic Ma		-	· 0
		-	me) and Identities for both closed and	-	00 0	gate demand
	(IS/LM)	. Price Indice	(WPI/CPI), Interest rates, Direct and	Indirect Taxe	25.	0
UNIT – II						9
			e, Externalities, Labour Market. Com	-	•	
5		5	Aggregates; Commercial Banks & their		*	ebt Markets.
Monetary a	nd Fisca	Policy Tools	& their impact on the economy – Inflat	tion and Phill	ips Curve.	
UNIT – III						9
Elements of Business/Managerial Economics and forms of organizations. Cost & Cost Control – Techniques,						
		0	6			-
Types of C	Costs, Lif	ecycle costs,	Budgets, Break even Analysis, Capit	al Budgeting	g, Applicatio	on of Linear
Types of C Programmi	Costs, Lif ng. Inve	ecycle costs, stment Analy	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period,	al Budgeting , Depreciatio	g, Application n, Time valu	on of Linear ue of money
Types of C Programmin (present and	Costs, Lif ng. Inve d future	ecycle costs, stment Analy worth of cash	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element	al Budgeting , Depreciatio	g, Application n, Time valu	on of Linear ue of money
Types of C Programmin (present and flow, Finand	Costs, Lif ng. Inve d future	ecycle costs, stment Analy	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element	al Budgeting , Depreciatio	g, Application n, Time valu	on of Linear ue of money nts – Cash
Types of C Programmin (present and flow, Finand UNIT – IV	Costs, Lif ng. Inve d future cial. Case	ecycle costs, stment Analy worth of cash e Study Meth	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element <u>d.</u>	al Budgeting , Depreciatio tary techniqu	g, Application, Time values. Statemer	on of Linear ue of money nts – Cash 9
Types of C Programmin (present and flow, Finand UNIT – IV Introduction	Costs, Lif ng. Inve d future cial. Case n- metho	ecycle costs, stment Analy worth of cash study Meth ods of proces	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma	al Budgetinş , Depreciatio tary techniqu aterial evalu	g, Application, Time values. Statemer ation – step	on of Linear ue of money nts – Cash 9 s in process
Types of C Programmin (present and flow, Finand UNIT – IV Introduction selectionPr	Costs, Lif ng. Inve d future cial. Case n- metho roductio	ecycle costs, stment Analy worth of cash Study Meth ods of proces n equipment	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to c	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio	g, Application, Time values. Statemer ation – step n- importan	on of Linear ue of money nts – Cash 9 s in process ace of costing
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat	Costs, Lif ng. Inver d future cial. Case n- metho roduction cion, metho	ecycle costs, stment Analy worth of cash Study Meth ods of proces n equipment hods of costin	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to co g, elements of cost estimation, types of	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio	g, Application, Time values. Statemer ation – step n- importan	on of Linear ue of money nts – Cash 9 s in process ace of costing ocedure,
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation c	Costs, Lif ng. Inver d future cial. Case n- metho roduction cion, metho	ecycle costs, stment Analy worth of cash Study Meth ods of proces n equipment hods of costin	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to c	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio	g, Application, Time values. Statemer ation – step n- importan	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost.
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation of UNIT - V	Costs, Lif ng. Inver d future cial. Case n- metho roductio cion, met of labor c	ecycle costs, stment Analy worth of cash study Meth ods of proces n equipment hods of costin	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to co g, elements of cost estimation, types of ost, allocation of overhead charges, cal	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio estimates, es lculation of d	g, Application, Time values. Statemer ation – step n- importan stimating pro lepreciation	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation of UNIT - V Machining	Costs, Lif ng. Inves d future cial. Case n- metho roductio cion, met of labor c	ecycle costs, stment Analy worth of cash Study Meth ods of proces n equipment hods of costin ost, material	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to c g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation,	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio estimates, es lculation of d	g, Application, Time values. Statement ation – step n- important stimating pro- lepreciation	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9 fferent lathe
Types of C Programmin (present and flow, Finand UNIT – IV Introduction selectionPr and estimat estimation of UNIT – V Machining operations,	Costs, Lif ng. Inves d future cial. Case n- metho roduction cion, metho of labor of time est drilling a	ecycle costs, stment Analy worth of cash study Meth ods of proces n equipment hods of costin cost, material imation- imp	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to co g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, we calculations, Machining time calculation	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio estimates, es lculation of d , machining tion for Milli	g, Application, Time values. Statemer ation – step n- importan stimating pro lepreciation time for di ng, Shaping,	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9 fferent lathe Planing and
Types of C Programmin (present and flow, Finand UNIT – IV Introduction selectionPr and estimat estimation of UNIT – V Machining operations, Grinding Pr	Costs, Lif ng. Invest d future d future cial. Case n- methor roduction cion, methor of labor control time est drilling a roduction	ecycle costs, stment Analy worth of cash e Study Meth ods of proces n equipment hods of costin ost, material imation- imp and boring tin n costs- differ	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to c g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, the calculations, Machining time calculation and production processes for different jo	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimates, es lculation of d , machining tion for Milli obs, estimatio	g, Application, Time values. Statemer ation – step n- importan stimating pro lepreciation time for di ng, Shaping,	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9 fferent lathe Planing and
Types of C Programmin (present and flow, Finand UNIT – IV Introduction selectionPr and estimat estimation of UNIT – V Machining operations, Grinding Pr estimation of	Costs, Lif ng. Invest d future d future cial. Case n- methor roduction cion, methor of labor control time est drilling a roduction	ecycle costs, stment Analy worth of cash e Study Meth ods of proces n equipment hods of costin ost, material imation- imp and boring tin n costs- differ	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to co g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, the calculations, Machining time calculation and production processes for different jo tion of foundry cost, estimation of mac	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimates, es lculation of d , machining tion for Milli obs, estimatio	g, Application, Time values. Statemer ation – step n- importan stimating pro lepreciation time for di ng, Shaping,	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9 fferent lathe Planing and g cost,
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation of UNIT - V Machining operations, Grinding Pr estimation of CO	Costs, Lif ng. Invest d future d future cial. Case n- methor roduction cion, met of labor c time est drilling a roduction of weldir	ecycle costs, stment Analy worth of cash e Study Meth ods of proces n equipment hods of costin cost, material imation- imp and boring tim n costs- differ	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to c g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, the calculations, Machining time calculation and production processes for different jo tion of foundry cost, estimation of mac COURSE OUTCOMES	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimates, es lculation of d , machining tion for Milli obs, estimatio	g, Application, Time values. Statemer ation – step n- importan stimating pro lepreciation time for di ng, Shaping,	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9 fferent lathe Planing and
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation c UNIT - V Machining operations, Grinding Pr estimation c <u>CO</u> Upon comp	Costs, Lif ng. Inves d future cial. Case n- metho roduction cion, metho of labor con time est drilling a roduction of weldir	ecycle costs, stment Analy worth of cash e Study Meth ods of proces n equipment hods of costin ost, material imation- imp and boring tim n costs- differ ng cost, estim	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to co g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, the calculations, Machining time calculation ent production processes for different jo tion of foundry cost, estimation of mac <u>COURSE OUTCOMES</u> students should be able to	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio estimates, es lculation of d machining tion for Milli obs, estimatio	g, Application, Time values. Statemer ation – step n- important stimating pro- lepreciation time for di ng, Shaping, on of forging	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9 fferent lathe Planing and g cost, PO
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation of UNIT - V Machining operations, Grinding Pr estimation of CO	Costs, Lif ng. Invest d future f cial. Case n- methor roduction of labor c time est drilling a roduction of weldir of weldir pletion of Descri	ecycle costs, stment Analy worth of cash e Study Meth ods of proces n equipment hods of costin cost, material imation- imp and boring tin n costs- differ ng cost, estim this course, S be the role of	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to co g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, he calculations, Machining time calculation of foundry cost, estimation of mac <u>COURSE OUTCOMES</u> sudents should be able to economics in the decision-making proc	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio estimates, es lculation of d machining tion for Milli obs, estimatio	g, Application, Time values. Statemer ation – step n- important stimating pro- lepreciation time for di ng, Shaping, on of forging	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9 fferent lathe Planing and g cost,
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation c UNIT - V Machining operations, Grinding Pr estimation c <u>CO</u> Upon comp	Costs, Lif ng. Invest d future d future d future cial. Case n- metho roduction ion, met of labor c time est drilling a roduction of weldir of weldir letion of Descri calcula	ecycle costs, stment Analy worth of cash e Study Meth ods of proces n equipment hods of costin ost, material imation- imp and boring tin n costs- differ ng cost, estim this course, S be the role of ations in rega	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to c g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, the calculations, Machining time calculation ent production processes for different jo tion of foundry cost, estimation of mac <u>COURSE OUTCOMES</u> students should be able to economics in the decision-making proce d to interest formulas	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio estimates, es lculation of d machining tion for Milli obs, estimatio	g, Application, Time values. Statemer ation – step n- important stimating pro- lepreciation time for di ng, Shaping, on of forging	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9 fferent lathe Planing and g cost, PO
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation of UNIT - V Machining operations, Grinding Pr estimation of CO Upon comp 1.	Costs, Lif ng. Invest d future cial. Case n- methor roduction cion, methor of labor of time est drilling a roduction of weldir of weldir of letion of Descri calcula Under	ecycle costs, stment Analy worth of cash e Study Meth ods of proces n equipment hods of costin cost, material imation- imp and boring tin n costs- differ eg cost, estim this course, S be the role of ations in rega stand the Mc	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to co g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, the calculations, Machining time calculat ant production processes for different jo tion of foundry cost, estimation of mac <u>COURSE OUTCOMES</u> students should be able to economics in the decision-making proc d to interest formulas netary and Fiscal Policy Tools	al Budgeting , Depreciatio tary technique aterial evalue ost estimation estimates, estimation clulation of destimation , machining tion for Million chining cost.	g, Application, Time values. Statemer ation – step n- importan stimating pro- lepreciation time for di ng, Shaping, on of forging	on of Linear ue of money nts – Cash 9 s in process ice of costing ocedure, cost. 9 fferent lathe Planing and g cost, PO PO1, PO4
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation of UNIT - V Machining operations, Grinding Pr estimation of CO Upon comp 1. 2.	Costs, Lif ng. Invest d future f cial. Case n- methor roduction roduction of labor control time est drilling a roduction of weldir of weldir of weldir pletion of Descri calcula Under	ecycle costs, stment Analy worth of cash e Study Meth ods of proces n equipment hods of costin ost, material imation- imp and boring tim n costs- differ og cost, estim this course, S be the role of ations in rega stand the Mo ate the Preser	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to c g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, the calculations, Machining time calculation ent production processes for different jo tion of foundry cost, estimation of mac <u>COURSE OUTCOMES</u> students should be able to economics in the decision-making proce d to interest formulas	al Budgeting , Depreciatio tary technique aterial evalue ost estimates, estimates leulation of d , machining tion for Milli obs, estimation chining cost.	g, Application, Time values. Statemer ation – step n- important stimating pro- lepreciation time for di ng, Shaping, on of forging	on of Linear ue of money nts – Cash 9 os in process ice of costing ocedure, cost. 9 fferent lathe Planing and g cost, PO PO1, PO4 PO1, PO4
Types of C Programmin (present and flow, Finand UNIT - IV Introduction selectionPr and estimat estimation of UNIT - V Machining operations, Grinding Pr estimation of CO Upon comp 1. 2. 3.	Costs, Lif ng. Invest d future cial. Case n- methor roduction cion, methor of labor control time est drilling a roduction of weldir of weldir letion of Descri calcula Under Estima	ecycle costs, stment Analy worth of cash e Study Meth ods of proces n equipment hods of costin cost, material imation- imp and boring tin n costs- differ ng cost, estim this course, S be the role of ations in rega stand the Mc ate the Preser n the concept	Budgets, Break even Analysis, Capit sis – NPV, ROI, IRR, Payback Period, flows). Business Forecasting – Element d. s planning-Drawing interpretation-Ma and tooling selection Introduction to c g, elements of cost estimation, types of ost, allocation of overhead charges, cal ortance of machine time calculation, the calculations, Machining time calculation et production processes for different jo tion of foundry cost, estimation of mac <u>COURSE OUTCOMES</u> tudents should be able to economics in the decision-making proc d to interest formulas netary and Fiscal Policy Tools a annual and future worth comparison	al Budgeting , Depreciatio tary techniqu aterial evalu ost estimatio estimates, es lculation of d , machining tion for Milli obs, estimatio chining cost.	g, Application, Time values. Statemer ation – step n- important stimating pro- lepreciation time for di ng, Shaping, on of forging orm	on of Linear ue of money nts – Cash 9 s in process ice of costing ocedure, cost. 9 fferent lathe Planing and g cost, PO PO1, PO4 PO1, PO4 PO1, PO4

TEXT BOC	K
1.	Pannerselvam, R., Engineering Economics., Prentice Hall India Learning Private Limited; 2nd Revised edition, 2013.
2.	Donald G. Newnan, Ted G. Eschenbach., Jerome P. Lavelle., Engineering Economic Analysis, Oxford University Press; 13th edition, 2017.
REFERENC	CES
1.	Leland Blank and Anthony Tarquin., Basics of Engineering Economy., McGraw-Hill Education; 2 edition, 2013.
2.	Chan S. Park., Contemporary Engineering Economics, Pearson Education, 6th Edition, 2015.

Course T			NES & HEAT TI		Credits	LTP	
0		LABORA	ORY (MECHA	NICAL LAB – I)	cicuits	C	
Course C						0042	
Course Ca	ategory		ODI				
OBJECTIVES							
 To study the valve timing and Port timing diagram of I.C. Engines. 							
	• To conduct the performance test on single / twin cylinder I.C. engines using different						
	loading arrangements.						
• To build a solid foundation in heat transfer exposing students to the three basic modes namely conduction, convection and radiation.							
INTERNAL COMBUSTION ENGINES LABORATORY - LIST OF EXPERIMENTS							
Valve timing diagram on single cylinder four stroke petrol engine							
Port timing diagram on single cylinder two stroke petrol engine							
Load test on single cylinder petrol engine							
• Lo	Load test on single cylinder diesel engine						
Performance test on high-speed diesel engine with alternator loading							
• Pe	erforman	ice test on T	win cylinder diese	el engine			
HEAT TRANSFER LABORATORY LIST OF EXPERIMENTS							
Heat Transfer through Composite Walls							
 Heat Transfer through a Pin- Fin 							
 Heat Transfer by Natural Convection 							
 Heat Transfer by Forced Convection 							
 Stefen Boltzman Apparatus 							
 Heat Transfer through Parallel Flow / Counter Flow Heat Exchanger 							
СО			COURSE OU	UTCOMES		РО	
Upon con	npletion	of this cour	se, Students shoul	d be able to			
1.	Analy	yse the per	formance behavio	our of petrol / diesel engin	e.		
2.	Unde	erstand the	various strokes &	scavenging process of I.C			
۷.	engin		1 1	· · · · · · ·			
3.				nsfer problem involving ar	ny of		
			of heat transfer.	perature variation using			
				le or employ approximate			
4.	-		-	to evaluate the rate of hea	t		
	trans	-					
				hangers and also estimate	the		
5.	insula	ation need	ed to reduce heat	losses where necessary.			

SEMESTER- IV

Course Title	e	DESIGN OF MACHINE ELEMENTS		LTPC
Course Code	e		Credits	3003
Course Categ	ory	PCC		
		OBJECTIVES		
To fat	miliar	ze various steps involved in the design process and failure of ma	chine parts	3.
		and the design principles of shafts with cyclic loads and various s	springs.	
		e design procedures of shafts, keys and couplings		
	5	nd analyse welded and riveted joints.		
• To ur	ndersta	and and design various types of joints for assembly.		
UNIT – I				9
		gn process – factor influencing the machine design, selection of m		
		Direct, bending and torsional stress equation, impact and shock lo	ading. Crite	eria of failure
	ety, de	sign stress, theories of failures – simple problems.		
UNIT – II				9
Variable and o	cyclic l	oads - fatigue strength and limit, S-N curve, stress concentration f	factor, size	factor, surface
finish factor,	combi	ned cyclic stress, Soderberg and Goodman's equations. Design	of helical, I	leaf, disc, and
torsional sprin	ngs un	der constant load and varying load.		
UNIT – III				9
Design of soli	d and	hollow shaft based on strength, rigidity, combined twisting and b	ending, sh	afts with
fluctuating loa	ads. K	eys – types, design and drawing of keys, keyways. Couplings – ty	pes, desigr	n of rigid and
flexible coupli	ings.			
UNIT – IV				9
Welded joints	s – stre	ngth of transverse and parallel fillet joints, stress concentration fa	ctor for we	lded joints,
		joints. Riveted joints - failure of riveted joints, strength, efficiency,	design of r	iveted joints
for pressure v	vessel a	ind structure.		
UNIT – V				9
Threaded fast	eners	design of socket and spigot cotter joint, sleeve and cotter joint, gib a	and cotter i	oint knuckle
joints, and pip				shirty initiaciae
	, c jein			
CO		COURSE OUTCOMES		PO
<u>_</u>		this course, Students should be able to		
		miliarized in various steps involved in the design process.		PO1, PO2
		stand and design shafts with cyclic stresses and various springs.		PO2, PO3
	v	n shafts with different loads, keys and couplings.		PO3
	0	n and evaluate the features of welded and riveted joints.		PO3
5.	Desig	n various types of joints for assembly of machine structures.		PO2, PO3

TEXT BOOK					
1.	JOSEPH EDWARD SHIGHLEY, Mechanical Engineering Design, McGraw Hill. 2008, 8th Edition.				
2.	R.S. KHURMI & GUPTA JK, A text book of Machine Design, S. Chand & Co.,				
3.	DONALDSON. C, Tool Design, Tata McGraw Hill & Co.				
REFERENCES					
1.	A.S. HALL, A.R. HOLOWENKO, AND H.G. LAUGHLIM, Theory And Problems In				
	Machine				
	Design Schaum's series				
2.	HALL AND ALLEN. S. Machine Design, Schaum's Series. 2008, TMH.				
3.	M.F. Spolts, Design of Machine Elements, Pearson Eduction, 2005, 7th Edition.				
4.	Gitin M. Maitra, Hand Book of Mechanical Design, 2 nd Edition.				
5.	J. B. K Das, Design of Machine Elements, Sapna Book House, 2007, 2 nd Edition.				
6.	A. S. Ravindra, Design of Machine Elements, Best Publishers, 2005. 2 nd Edition.				
7.	V. B. Bhandari, Design of Machine Elements, TMH, 2007.				
Hand book	ς				
1	Design data book, PSG College of technology, Coimbatore.				
1.	(Use of approved data books are permitted in all the examinations)				

<u> </u>	DYNAMIC	CS OF MACHINES	Cradita	LTPC
Course Code			Credits	2103
Course Category		PCC		
		OBJECTIVES		
To underst	and the unde	sirable effects of unbalances resulting from prescribed	l motions ir	ı
mechanism				
		motion relationship in components subjected to exter	mal forces a	ndanalysis
	l mechanisms		1	
	1	tiple in mechanisms used for speed control and stabili	ty control.	
		t of dynamics of free vibrations.		
	and the effect	t of dynamics of forced vibrations.		
UNIT – I				9
		nic balancing of rotating masses in different planes, pa		
- 0		V, W and radial engines. Hammer blow and swaying	g couple in l	ocomotive,
direct and reverse c	rank method.			
UNIT – II				9
INERTIA FORCE -	Inertia force a	and inertia torque calculation. Turning moment diagra	ams, recipro	ocating
		of energy and speed, Weight of flywheels.	, F	8
	,			0
UNIT – III				9
		PPE - Function of governors – porter, proell and sp	0	0
	-	l isochronisms, effect of friction, calculation of equilib	rium speed	s and ranges
of speed of governo			6	
	and effect, in	n ship and motor cycle, car, aircraft and space vehicles	s, Gyroscope	5
stabilization.				
UNIT – IV				0
FREE VIBRATION	TT 1			9
	-	ed free vibration of single degree of freedom syst	-	pendulum,
compound pendult	um, inclined s	spring-mass system, equivalent stiffness of spring co	mbinations	pendulum, - springs in
compound pendulu series, springs in p	um, inclined s arallel, comb	spring-mass system, equivalent stiffness of spring con ined series and parallel springs. Damped free vibrat	mbinations tion of sing	pendulum, – springs in le degree of
compound pendult series, springs in p freedom systems, ty	um, inclined s arallel, comb	spring-mass system, equivalent stiffness of spring co	mbinations tion of sing	pendulum, – springs in le degree of
compound pendulu series, springs in p freedom systems, ty damped system.	um, inclined s arallel, comb	spring-mass system, equivalent stiffness of spring con ined series and parallel springs. Damped free vibrat	mbinations tion of sing	pendulum, – springs in le degree of em, under
compound pendult series, springs in p freedom systems, ty damped system. UNIT – V	am, inclined s arallel, comb ypes of dampi	spring-mass system, equivalent stiffness of spring con ined series and parallel springs. Damped free vibrating, free vibrations with viscous damping, critically da	mbinations tion of sing amped syste	pendulum, – springs in le degree of em, under 9
compound pendult series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATION	am, inclined s arallel, comb ypes of damp ON - Forced	spring-mass system, equivalent stiffness of spring co- ined series and parallel springs. Damped free vibra- ing, free vibrations with viscous damping, critically da vibration of single degree of freedom system. Consta	mbinations tion of sing amped system ant harmoni	pendulum, - springs in le degree of em, under 9 ic excitation,
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATIC steady state vibratic	am, inclined s arallel, comb ypes of dampi ON - Forced on, magnificat	spring-mass system, equivalent stiffness of spring con- ined series and parallel springs. Damped free vibrating, free vibrations with viscous damping, critically da vibration of single degree of freedom system. Consta- tion factor with frequency ratio for various damping.	mbinations tion of sing amped system ant harmoni Transverse	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATIC steady state vibratic beams -natural free	am, inclined s arallel, comb ypes of dampi ON - Forced on, magnificat equency by e	spring-mass system, equivalent stiffness of spring co- ined series and parallel springs. Damped free vibra- ing, free vibrations with viscous damping, critically d vibration of single degree of freedom system. Consta- tion factor with frequency ratio for various damping. energy method, Dunkerly method-Vibration isolatic	mbinations tion of sing amped syste ant harmoni Transverse on and tran	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of asmissibility,
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATIC steady state vibratic beams -natural free whirling of shafts. T	am, inclined s arallel, comb ypes of damp ON - Forced on, magnificat equency by e forsional vibr	spring-mass system, equivalent stiffness of spring con- ined series and parallel springs. Damped free vibrating, free vibrations with viscous damping, critically da vibration of single degree of freedom system. Consta- tion factor with frequency ratio for various damping. Tenergy method, Dunkerly method-Vibration isolatic rations: Torsional vibrations of single and multiple rot	mbinations tion of sing amped syste ant harmoni Transverse on and tran	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of asmissibility,
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATIC steady state vibratic beams -natural free whirling of shafts. T shafts, Geared system	am, inclined s arallel, comb ypes of damp ON - Forced on, magnificat equency by e forsional vibr	spring-mass system, equivalent stiffness of spring co- ined series and parallel springs. Damped free vibrating, free vibrations with viscous damping, critically de vibration of single degree of freedom system. Constation factor with frequency ratio for various damping. energy method, Dunkerly method-Vibration isolation rations: Torsional vibrations of single and multiple rot method.	mbinations tion of sing amped syste ant harmoni Transverse on and tran	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of asmissibility, Equivalent
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATIC steady state vibratic beams -natural free whirling of shafts. T shafts, Geared syste CO	am, inclined s arallel, comb pes of damp ON - Forced on, magnificat equency by e forsional vibr ems, Holzer's	spring-mass system, equivalent stiffness of spring con- ined series and parallel springs. Damped free vibrating, free vibrations with viscous damping, critically da vibration of single degree of freedom system. Consta- tion factor with frequency ratio for various damping. Tenergy method, Dunkerly method-Vibration isolatic rations: Torsional vibrations of single and multiple rot method. COURSE OUTCOMES	mbinations tion of sing amped syste ant harmoni Transverse on and tran	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of asmissibility,
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATIC steady state vibratic beams -natural free whirling of shafts. T shafts, Geared syste CO Upon completion o	am, inclined s arallel, comb ypes of dampi ON - Forced on, magnificat equency by e forsional vibr ems, Holzer's	spring-mass system, equivalent stiffness of spring con- ined series and parallel springs. Damped free vibrations, free vibrations with viscous damping, critically da vibration of single degree of freedom system. Consta- tion factor with frequency ratio for various damping. energy method, Dunkerly method-Vibration isolation rations: Torsional vibrations of single and multiple rot method. COURSE OUTCOMES Students should be able to	mbinations tion of sing amped syste ant harmoni Transverse on and tran	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of asmissibility, Equivalent PO
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATION steady state vibration beams -natural free whirling of shafts. T shafts, Geared system CO Upon completion of 1. Analy	am, inclined s arallel, comb ypes of damp ON - Forced on, magnificat equency by e forsional vibr ems, Holzer's f this course, s yze the effects	spring-mass system, equivalent stiffness of spring con- ined series and parallel springs. Damped free vibrations, free vibrations with viscous damping, critically da vibration of single degree of freedom system. Consta- tion factor with frequency ratio for various damping. Tenergy method, Dunkerly method-Vibration isolatic rations: Torsional vibrations of single and multiple rot method. COURSE OUTCOMES Students should be able to s of unbalances in mechanism	mbinations tion of sing amped system ant harmoni Transverse on and trans for systems,	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of asmissibility, Equivalent PO PO2
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATIO steady state vibratio beams -natural free whirling of shafts. T shafts, Geared system CO Upon completion o 1. Analy 2. Analy	am, inclined s arallel, comb ypes of dampi ON - Forced on, magnificat equency by e forsional vibr ems, Holzer's <u>f this course</u> , <u>s</u> yze the effects yze the force r	spring-mass system, equivalent stiffness of spring con- ined series and parallel springs. Damped free vibrations, free vibrations with viscous damping, critically date vibration of single degree of freedom system. Consta- tion factor with frequency ratio for various damping. Tenergy method, Dunkerly method-Vibration isolation rations: Torsional vibrations of single and multiple rot method. COURSE OUTCOMES Students should be able to s of unbalances in mechanism motion relationship of standard mechanisms	mbinations tion of sing amped system ant harmoni Transverse yon and trans or systems,	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of asmissibility, Equivalent PO PO2 PO1, PO2
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATIC steady state vibratic beams -natural free whirling of shafts. T shafts, Geared syste CO Upon completion of 1. Analy 2. Analy 3. Analy	am, inclined s arallel, comb ypes of dampi ON - Forced on, magnificat equency by e forsional vibr ems, Holzer's f this course, s ze the effects ze the force r ze and calcul	spring-mass system, equivalent stiffness of spring con- ined series and parallel springs. Damped free vibrations, free vibrations with viscous damping, critically date vibration of single degree of freedom system. Consta- tion factor with frequency ratio for various damping. Tenergy method, Dunkerly method-Vibration isolatic rations: Torsional vibrations of single and multiple rot method. COURSE OUTCOMES Students should be able to s of unbalances in mechanism motion relationship of standard mechanisms late speed control and stability control in mechanisms	mbinations tion of sing amped system ant harmoni Transverse yon and trans or systems,	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of asmissibility, Equivalent PO PO2 PO1, PO2 PO2 PO2
compound pendulu series, springs in p freedom systems, ty damped system. UNIT - V FORCED VIBRATIC steady state vibratic beams -natural free whirling of shafts. T shafts, Geared syste CO Upon completion o 1. Analy 2. Analy 3. Analy 4. Analy	am, inclined s arallel, comb ypes of dampi ON - Forced on, magnificat equency by e forsional vibr ems, Holzer's f this course, s yze the effects yze the force r yze and calcul yze the effect	spring-mass system, equivalent stiffness of spring con- ined series and parallel springs. Damped free vibrations, free vibrations with viscous damping, critically date vibration of single degree of freedom system. Consta- tion factor with frequency ratio for various damping. Tenergy method, Dunkerly method-Vibration isolation rations: Torsional vibrations of single and multiple rot method. COURSE OUTCOMES Students should be able to s of unbalances in mechanism motion relationship of standard mechanisms	mbinations tion of sing amped system ant harmoni Transverse yon and trans or systems,	pendulum, - springs in le degree of em, under 9 ic excitation, vibrations of asmissibility, Equivalent PO PO2 PO1, PO2

TEXT BOC	
1.	AMITABH GHOSH AND ASHOK KUMAR MALLIK, Theory of mechanism and Machines – 3 nd
1.	Edition, Affiliated East West Press Limited, 2007.
2.	J.E.SHIGLEY AND J.J.VICKER Jr. Theory of Machines and Mechanism, 2 nd ed. Mc GrawHill ISE
۷.	1995
3.	R.S. KHURMI & GUPTA .J.K, A text book of Theory of Machines, S. Chand & Co., 2008, 14 th
5.	Edition.
4.	G.K.GROVER, Mechanical Vibrations, New Chand and Brothers, Roorkee.
REFERENC	CES
1.	J.HANNAH AND R.C STEPHENS ARNOLD, Mechanics of Machines – ISE 1986.
2.	BEER & JOHNSTON 5 TH Edition, Vector Mechanics for Engineers. McGraw Hill. ISE 1988.
3.	THOMAS BEVAN - 3 rd Edition, The Theory of Machines - CBS 1984.
4.	P.L.BALLANEY, Theory of Machines, Khanna Publishers, 2005, 24th Edition.
5.	S.S.RATTAN, Theory of Machines, Tata McGraw Hill. 2008, 2 nd Edition.
6.	RAO .J.S. & DUKKIPATI. R.V. Mechanism and Machine Theory, 2 nd ed. Wiley Eastern Ltd.,
	2007,
7.	HAMILTON H. MABIE & CHARLES F. REINNOLTZ, Mechanisms and Dynamics of
	Machinery, 4 th ed. John Wiley & Sons, 1995
8.	THOMSON W.T, Theory of Vibration and Applications, Prentice Hall India, 1975
9.	Sadhu Singh, Theory of Machines, Pearson Education Ltd, 2007.
10.	Ashok G. Ambekar, Mechanism and Machine Theory, Eastern Economy Edition. 2007.
11.	John. J. Uicker, Theory of Machines and Mechanisms, Oxford University Press, 2008, 3 rd
	Edition.
12.	S. S. Rao, Mechanical Vibrations, Pearson Education, 2007, 4th Edition.

Course Title	METROLOGY AND QUALITY CONTROL		
Course Title	Note : Use of approved statistical table permitted in the examination	Credits	L T P C
Course Code		Cicuits	3003
Course Category	PCC		
	OBJECTIVES		
To underst	and the concept of metrology and principles of measuring instrur	nents	
To underst	and the concept of different types of comparative measurements		
To gain the	knowledge about calibration technique in measuring instrument	S	
-	knowledge on quality control and control charts		
To impart	he knowledge on control charts for variables		
UNIT - I BASICS (9
Repeatability, Sens Micrometer – types Vernier and optical	logy - Objective of metrology - Precision and Accuracy - Source itivity, Readability and Reliability – Linear measurements – ty - Vernier height gauges – depth gauges – Slip gauges – Angular Bevel protractor - Sine Principle and Sine Bar - Optical Instrumen cocollimator - Angle Gauge.	vpes – Vern measuremen	ier caliper – nts – Types -
UNIT - II COMPA	RATIVE MEASUREMENT		9
Taylors principle -	itic – Testing of straightness – Flatness – parallelism and circulari Snap gauges – plain plug gauges – progressive plug gauges - Rir ges – radius gauges – engineers square and parallel – dial gauges - etic V block.	ng gauges – '	Thread pitch
UNIT - III CA	LIBRATION AND MEASURING MACHNES		9
Dial gauges – Meas makers microscope	itivity – Range – standards – Traceability - Calibration of Vernie surement using surface roughness tester – Co-ordinate measuring - Gear measurement – Gear tooth caliper – Circular pitch measurir nardness tester – Surface plates – bore gauges – Machine tool metr	g machine – Ig machine –	Types - Tool Parkinson
	JALITY CONTROL FOR VARIABLES		9
limitation of SQC, (– process capability	tion of quality – Facts of quality - basic concept of quality, definiti Quality assurance - Concepts of Quality control - Quality cost-Vari – process capability studies and simple problems – Theory of contr t for variables – X chart, R chart and (P & C) chart – six sigma concep	ation in proc ol chart- use	cess- factors s of control
	DCESS CONTROL FOR ATTRIBUTES		9
charts, State of cont - O.C. curves - pro	oportion or fraction defectives – p chart and np chart – control cha rol and process out of control identification in charts – Acceptance ducer's Risk and consumer's Risk. AQL, LTPD, AOQL concepts- uses of standard sampling plans.	sampling pl	an – Types
<i>Note</i> : Use of appro	ved statistical table permitted in the examination		
L			

СО	COURSE OUTCOMES	РО		
Upon com	pletion of this course, Students should be able to			
1.	Understand the basics of metrology and linear and angular measuring instruments	PO1, PO2		
2.	Explain the working principles of comparators and limit gauges	PO2		
3.	Determine the status of the measuring instruments and different parameters using measuring machines	PO2		
4.	Understand the concepts of quality and to Solve the problems in process control charts for variables			
5.	Solve the problems in process control charts for attributes	PO4		
TEXT BOO)K			
1.	R.K.JAIN, Engineering Metrology, Khanna publishers, 21st edition, 1984			
2.	GRANT, EUGENE.L "Statistical Quality Control", Tata McGraw-Hill, 7th edition,	2005		
REFEREN	CES			
1.	MONOHAR MAHAJAN, "Statistical Quality Control", Dhanpat Rai & Sons, 2001	l.		
2.	R.C.GUPTA, "Statistical Quality control", Khanna Publishers, 9th edition, 1998.			
3.	BESTERFIELD D.H., "Quality Control", Prentice Hall, 7th edition, 2003.			
4.	SHARMA S.C., "Inspection Quality Control and Reliability", Khanna Publishers,	2002.		

	e POWER P	LANT ENGINEERING	Cradita	LTPC	
Course Cod	e		Credits	3003	
Course Cate	gory	PCC			
OBJECTIVES					
To und	erstand the layout	and various systems of coal based thermal power pla	nt.		
• To hav	e the knowledge of	types of boilers, mountings/accessories.			
To und	erstand the layout	and various systems of gas, diesel and hydel power p	olants.		
To und	erstand the layout	and various systems of nuclear power plant.			
To stuce	y the economics of	power plant & estimate the costs of electrical energy	generation.		
UNIT – I TH	ERMAL POWER I	PLANT		9	
Essential of	steam power plant	equipment - power station design - characteristics	of steam po	ower plant –	
layout - Stol	ers - Types- pulve	erized fuel firing - Principles of FBC - Types & arran	gement of d	ifferent FBC	
plants - Ash	handling – dust co	llectors - draft measurements - chimneys - calculation	n of chimney	v heights –	
feed water tr	eatment – air prehe	eater – superheaters, condenser, cooling towers.			
UNIT - II ST	EAM GENERATO	ORS		9	
Boilers – type	s of modern high-p	ressure boiler – boiler mountings and accessories – the	rmal efficien	cy of boiler	
- boiler perfo	rmance - selection	of fuel for boiler - boiler maintenance - selection of boil	er – heat bala	nce sheet for	
boiler – India	n boiler act.				
UNIT – III G	AS TURBINE, HY	(DEL& DIESEL POWER PLANT		9	
Gas turbine j	ower plant layout	- Classification & comparison of different types - gove	erning syster	n.	
Hydroelectri	c power plant layo	ut - Classification - storage reservoir plants - pump st	orage plants	s – MHD	
power plant.	Diesel power plan	t layout - Various systems of diesel power plant.			
UNIT - IV NUCLEAR POWER PLANT 9					
Nuclear Rea	ctor - General com	ponents- types of reactors - pressurized water react	or (PWR), B	oiling water	
reactor (BWI	R), heavy water coo	oled and moderated - reactor, gas cooled reactor, liqu	uid metal co	oled reactor,	
fast breeder	reactor, site selecti	on of nuclear power plant, comparison of nuclear po	ower plant v	with thermal	
power plant.	Nuclear materials	- fuels - coolant - moderators & reflecting materials -	control rod -	- shielding	
materials.					
UNIT - V	POWER PLANT E	CONOMICS			
Load curves	- Terminologies - e	effect of variable load on power plant design & operati		9	
		ficer of value four off power plant design a operad	on – require		
-		g cost - load diversion - Power tariff methods - com	-	ment of peak	
-			-	ment of peak	
-		g cost - load diversion - Power tariff methods - com	-	ment of peak	
various pow	er plants – environi etion of this course,	g cost – load diversion – Power tariff methods – com mental hazards of various power plants. COURSE OUTCOMES , Students should be able to	parison of e	ment of peak economics of	
various power CO Upon comple	er plants – environi etion of this course, Explain the layou	g cost – load diversion – Power tariff methods – com mental hazards of various power plants. COURSE OUTCOMES , Students should be able to at, construction and working of the components inside	parison of e	ment of peak economics of PO	
various power CO Upon comple 1.	er plants – environi etion of this course, Explain the layou thermal power p	g cost – load diversion – Power tariff methods – com mental hazards of various power plants. COURSE OUTCOMES , Students should be able to 1t, construction and working of the components inside lant.	parison of e	ment of peak economics of PO PO1	
various power CO Upon comple	er plants – environi etion of this course, Explain the layou thermal power p Discuss the types	g cost – load diversion – Power tariff methods – com mental hazards of various power plants. COURSE OUTCOMES , Students should be able to at, construction and working of the components inside lant. s of steam boilers & its performance	e a	ment of peak economics of PO	
various power CO Upon comple 1.	er plants – environi etion of this course, Explain the layou thermal power p Discuss the types Explain the layou	g cost – load diversion – Power tariff methods – com mental hazards of various power plants. COURSE OUTCOMES , Students should be able to at, construction and working of the components inside lant. s of steam boilers & its performance at, construction and working of the components inside	e a	PO PO1	
various power CO Upon comple 1. 2.	er plants – environi etion of this course, Explain the layou thermal power p Discuss the types Explain the layou Diesel, Gas and h	g cost – load diversion – Power tariff methods – com mental hazards of various power plants. COURSE OUTCOMES , Students should be able to at, construction and working of the components inside lant. s of steam boilers & its performance at, construction and working of the components inside hydel power plants.	e a	PO PO1 PO1	
various power CO Upon comple 1. 2.	er plants – environi etion of this course, Explain the layou thermal power p Discuss the types Explain the layou Diesel, Gas and h Explain the layou	g cost – load diversion – Power tariff methods – com mental hazards of various power plants. COURSE OUTCOMES , Students should be able to at, construction and working of the components inside lant. s of steam boilers & its performance at, construction and working of the components inside nydel power plants. at, construction and working of the components inside	e a	PO PO1 PO1	
various power CO Upon comple 1. 2. 3.	er plants – environi etion of this course, Explain the layou thermal power p Discuss the types Explain the layou Diesel, Gas and h Explain the layou nuclear power pl	g cost – load diversion – Power tariff methods – com mental hazards of various power plants. COURSE OUTCOMES , Students should be able to at, construction and working of the components inside lant. s of steam boilers & its performance at, construction and working of the components inside nydel power plants. at, construction and working of the components inside ant.	e a	PO1 PO1 PO1 PO1 PO1	
various power CO Upon complete 1. 2. 3. 4.	er plants – environi etion of this course, Explain the layou thermal power p Discuss the types Explain the layou Diesel, Gas and h Explain the layou nuclear power pl Explain the appli	g cost – load diversion – Power tariff methods – commental hazards of various power plants. COURSE OUTCOMES , Students should be able to at, construction and working of the components inside lant. s of steam boilers & its performance at, construction and working of the components inside hydel power plants. at, construction and working of the components inside ant. cations of power plants while extend their knowledge	e a e a e to	PO1 PO1 PO1 PO1 PO1 PO1 PO1	
various power CO Upon comple 1. 2. 3.	er plants – environi etion of this course, Explain the layou thermal power p Discuss the types Explain the layou Diesel, Gas and h Explain the layou nuclear power pl Explain the appli	g cost – load diversion – Power tariff methods – com mental hazards of various power plants. COURSE OUTCOMES , Students should be able to at, construction and working of the components inside lant. s of steam boilers & its performance at, construction and working of the components inside nydel power plants. at, construction and working of the components inside ant.	e a e a e to	PO1 PO1 PO1 PO1 PO1	

TEXT BOC	0K
1.	El-Wakil. M.M., "Power Plant Technology", Tata McGraw – Hill Publishing Company Ltd., 2019
2.	ARCHIEW, CULP Jr., Principle of Energy Conversation, Tata McGraw Hill, 1979
3.	P. K. NAG, Power Plant Engineering, Tata McGraw Hill, 2017.4th Edition
4.	G. R. NAGPAL, Power Plant Engineering, Khanna Publishers, Sixteenth edition, 1995
REFEREN	CES
1.	VOPAL AND STORTZKI, Power Plant Engineering, PHI, year.
2.	DOMKUNDWAR, Power Plant Engineering, Dhanpat Rai & Sons., Eight Edition, 2016.
3.	JOEL WEISMAN AND ROY ECKART, Morden Power Plant Engineering, Prentice Hall, 1985.
4.	Thomas C. Elliott, Kao Chen and Robert C. Swanekamp, "Power Plant Engineering", Second
	Edition, Standard Handbook of Tata McGraw – Hill, 2 nd edition, 2012.
5.	V. Kadambi, An Introduction to Energy Conversion, New Age Publication Ltd, 2011

Course Titl	LAB		CS AND MEASUREMENTS FORY (MECHANICAL LAB – II)	Credits	C	
Course Coo					0042	
Course Category						
			OBJECTIVES			
• To 1	understand	d the ki	nematic and dynamic characteristics of mech	anical devi	ces	
			ifferent measurement devices			
			LIST OF EXPERIMENTS			
• Deter	rmination	of M.I	by suspension of simple and compound pend	lulum metl	nod.	
• Cam	& followe	er and n	notion studies			
• Deter	rmination	of critic	al speed for whirling of shaft.			
• Deter	rmination	of natu	ral frequency and damping coefficient for spi	ring mass s	system.	
• Deter	rmination	of torsi	onal natural frequency for single rotor system	n.		
• Strain	n measure	ement u	sing Rosette strain gauge			
• Torq	ue measur	ring dev	rice - Rope and Prony brake arrangements			
 Temp 	perature n	neasurii	ng device- Thermocouples			
Press	sure measu	uring de	evices – Pressure and vacuum gauge calibrati	on		
• Displ	lacement r	measuri	ng devices- LVDT			
Chec	king strai	ghtness	of a surface plate using Autocollimator			
• Use d	of electron	ic, pneu	imatic and mechanical comparator for detern	nining flatt	ness	
CO			COURSE OUTCOMES		РО	
Upon compl	letion of th	nis cour	se, Students should be able to	,		
1.	Character	rize the	dynamic behavior of mechanical systems			
				1		

2. Understand the mechanical measurement devices

SEMESTER- V

Course Tit	tle	CAD/CAM		Cradita	LTPC
Course Co	de			Credits	3003
Course Cat	egory		PCC		
			OBJECTIVES		
• To u	nderstan	d the basics	of CAD/CAM.		
			e concepts of computer graphics.		
		-	tric issues concerned to the manufacturing and its rela	ated areas.	
			dvances in the manufacturing perspectives.		
• To p plan		n overview o	f how computers are being used in design, developm	ent of man	ufacturing
UNIT- I - C	COMPUT	ER AIDED	DESIGN		9
and DDA, O	Graphics	software, Cli	troduction to CAD/CAM – Graphics I/O Devices -Bi ipping, Hidden line/surface removal, Color models I le formats –IGES, STEP		0
UNIT-II-P	RINCIPI	LES OF COM	IPUTER GRAPHICS		9
and B-Rep	- World ion, trans	/device co	ne, Surface and Solid – Parametric representation of ordinate representations, 2D and 3Dgeometric to ng, shearing, rotation and reflection, composite transf	ransformat	ions, Matrix
		CHINE TOO	DLS		9
Examples u	ising NC	codes- Adap	Manual part Programming - Computer Assisted Par otive Control - Canned cycles and subroutines - CAD nguage, machining from 3D models.	-	-
			OGY, CAPP & FMS		9
Introduction group techr	n to part nology – ot-transfe	t families-pa Process Plan	rts classification and cooling – group technology n ning – CAPP & types of CAPP – Flexible manufactur head changing FMS –Introduction to Rapid prototyp	ring system	s (FMS) – the
UNIT V CO	OMPUTE	ER INTEGRA	ATED MANUFACTURING		9
	architectu		-OSI Model- Networking Standards in CIM Environn , MAP - Virtual Reality, Augmented Reality- Artificia		
CO			COURSE OUTCOMES		РО
Upon comp	oletion of	this course,	Students should be able to		
1.	Unders	tand the basi	ics of CAD/CAM.		PO1
2.	Exposu	re over the c	oncepts of computer graphics.		PO5
3.	Learn a areas.	bout the geo	metric issues concerned to the manufacturing and its	related	PO5
4.	Unders	tand the late	st advances in the manufacturing perspectives.		PO5
5.	Provide		v of how computers are being used in design, develop	pment	PO5

TEXT BOO	K
1.	P.N. Rao, CAD/CAM: Principles and Applications 3 rd Edition, Tata McGraw Hill, India, 2010.
2.	Ibrahim Zeid and R. Sivasubramaniam, Mastering CAD/CAM, 2 nd Edition, Tata McGraw Hill,
	India, 2009
REFERENC	CES
1.	Mikell P. Groover, "Automation, Production Systems and Computer Integrated Manufacturing",
	Pearson Education, 2007
2.	James A. Rehg, Henry W. Kraebber, "Computer Integrated Manufacturing", Pearson Education.
	2007
3.	Donald Hearn and M.Pauline Baker "Computer Graphics" with OpenGL Prentice Hall,
	International, 2010

Course Code		Credits	
Course Code		Credits	3003
Course Category	PCC		
	OBJECTIVES		
	tand the concepts metal cutting		
	e knowledge on various types of lathes used		
	tand the difference between shaper planner and slotter in ma		<u> </u>
	e knowledge on different types of grinding machines and	related too	ols for
	rring various components		
	the basic gear manufacturing machines used in industries		
UNIT – I		<u></u>	9
	AL CUTTING - Introduction, mechanics of metal cutting -	-	
	force calculations, Torque and Power Calculations in Machi	0	
U 1	ng tool, Tool materials, Influence of tool Geometry, Tool		0
	nability – evaluating and rating, metal cutting economics, pr	oblems in N	/lerchant's
circle, tool life, and	1 machining time.		
UNIT – II			9
	he, constructional features, cutting tool geometry, various op		
	cutting methods, special attachments, machining time a	-	estimation.
-	t lathes – automats – single spindle, Swiss type, automatic so	crew type,	
	rret Indexing mechanism, bar feed mechanism.		
UNIT – III			9
SHAPER, PLANE	R AND MILLING PROCESSES - Shaper, Planer and Slotte	er: Introduc	tion, types,
specification, mecl	nanism - holding devices, hydraulic drives in shaper, differen	ce between	shaper and
planer.			
Introduction, type	es and specifications, mechanisms, holding devices, types	of milling	operation.
Milling tool nome	nclature and its specifications, Indexing – Types-Simple, Cor	mpounding	and
differentials.			
UNIT – IV			9
Abrasive process	es: grinding wheel - specifications and selection, types	of grindin	g process-
cylindrical grindir	g, surface grinding, centreless grinding, internal grinding- m	nicro finishi	ng methods
- Typical applicati	ons – concepts of surface integrity, broaching machines: broa	ach	
construction – pus	h, pull, surface and continuous broaching machines.		
UNIT – V			9
Gear manufacturii	ng processes - Gear Machining-Forming or Form cutting - Gea	ar generatin	g process-
Gear shaping, Gea	r hobbing Gear planning, Gear broaching. Bevel gear genera	ation.	
Gear finishing pro	cess- Gear Finishing Methods - Gear Shaving, Gear Grindin	g, Gear lap	ping, Gear
L			

СО	COURSE OUTCOMES	РО
Upon comp	letion of this course, Students should be able to	
1.	Understand the mechanics of metal cutting process	PO1
2.	Understand the various types of lathe machines	PO1
3.	Understand the shaper, planer and slotter machines	PO1
4.	Understand the application grinding operation in manufacturing	PO1
5.	Understand the gear manufacturing used in industries	PO1
TEXT BOO	K	
1.	Kalpakjian and Schmid, Manufacturing processes for engineering materials (5th F	Edition)-Pearson
	India, 2014.	
2.	Mikell P. Groover, Fundamentals of Modern Manufacturing: Materials, Processe	es, and Systems,
	Wiley, 3 rd Edition, 2009.	
3.	Degarmo's Materials and Processes in Manufacturing, Black & Kohser, Wiley, 20	008.
4.	Hajra Choudhury, "Elements of Workshop Technology, Vol. I and II", Media Pr	romotorsPvt
	Ltd.,	
	Mumbai, 2001.	
REFERENC	CES	
1.	B.S. Magendran Parashar & R.K. Mittal," Elements of Manufacturing Processes",	Prentice Hall of
	India, 2003	
2.	P.N. Rao," Manufacturing Technology", Tata McGraw-Hill Publishing Limited, I	I Edition, 2002.
3.	P.C. Sharma, "A text book of production technology", S. Chand and Company, I	V Edition, 2003.
4.	Beddoes.J and Bibby M.J, 'Principles of Metal Manufacturing Processes', Elsevie	r, 2006

Course Tit	tle	FINITE ELEMENT ANALYSIS	C 11.	LTPC
Course Co	ode		Credits	3003
Course Cat	egory	PEC-I		
		OBJECTIVES		
• To	apprecia	ate the use of FEM to a range of Engineering Problems.		
• To	impart l	pasic knowledge in finite element method		
• To	provide	e knowledge in 1D elements		
• To	provide	knowledge in 2D elements		
• To	provide	knowledge on isoparametric elements and Numerical Integration	methods	
UNIT - I	INT	RODUCTION		9
Gaussian el	liminatic	nd – Matrix approach – Application to the continuum – Discretisa on – Governing equations for continuum – Classical Techniques in Ritz method.		-
UNIT - II	ON	E DIMENSIONAL PROBLEMS		9
	y of stiff	eling – Coordinates and shape functions- Potential energy approad ness matrix and load vector – Finite element equations –Quadr ne trusses.		
UNIT - III	TW	O DIMENSIONAL CONTINUUM		9
	element	te element modelling – Scalar valued problem – Poisson equation s – Element stiffness matrix – Force vector – Galarkin approach s.	-	-
UNIT - IV	AX	ISYMMETRIC CONTINUUM		9
temperatur	e effects	ulation – Element stiffness matrix and force vector – Galarkin app – Stress calculations – Boundary conditions –Applications to cylin e – Rotating discs		
		AMETRIC ELEMENTS FOR TWO DIMENSIONAL CONTINU	UM	9
integration	-	rilateral – Shape functions – Element stiffness matrix and force ve ss integration – Stress calculations – Four node quadrilateral for av		problems.
СО		COURSE OUTCOMES		PO
Upon comp	1	f this course, Students should be able to	11	
1.	Apply	<i>t</i> the numerical methods to formulate the simple finite element provide t	oblems .	PO1, PO2, PO3
2.	Apply proble	ν one dimensional finite element method to solve bar and truss typ ems	be 1	PO1, PO2, PO3
3.	Apply	v two-dimensional finite element method to plane stress and strair	n type	PO1, PO2, PO3
		mine temperature distribution of one-dimensional heat transfer pr	oblems	PO1, PO2,
4.		one dimensional finite element		PO3

TEXT BOC	K
1.	CHANDRUPATLA T.R., AND BELEGUNDU A.D., "Introduction to Finite Elements in
	Engineering", Pearson Education 2002, 3 rd Edition.
2.	DAVID V HUTTON "Fundamentals of Finite Element Analysis" 2004. Tata McGraw-Hill Int. Ed.
3.	RAO S.S., "The Finite Element Method in Engineering", Pergammon Press, 1989
REFERENC	CES
1.	LOGAN D.L., "A First course in the Finite Element Method", Third Edition, Thomson Learning,
	2002.
2.	ROBERT D.COOK., DAVID.S, MALKUCS MICHAEL E PLESHA, "Concepts and Applications
	of Finite Element Analysis" 4 Ed. Wiley, 2003.
3.	REDDY J.N., "An Introduction to Finite Element Method", McGraw-Hill International Student
	Edition, 1985
4.	O.C.ZIENKIEWICZ AND R.L.TAYLOR, "The Finite Element Methods, Vol.1", "The basic
	formulation and linear problems, Vol.1", Butterworth Heineman, 5th Edition, 2000.
5.	C. S. KRISHNAMOORTHY, Finite Element Analysis, TMH, 2007, 2 nd Edition.
6.	K. J. BATHE, Finite Element Procedures, PHI, 2006,
7.	DESAI ABEL, Introduction to Finite Element Method, CBS Publishers, 2005.
8.	S. M. MURIGENDRAPPA, Fundamental of Finite Element Method, Interline Publishing, 2006.

	PRODUC	DESIGN AND	DEVELOPMENT		Credits	LTPC
Course Code					Cleans	3003
Course Catego	ory	PEC-I				
		OI	BJECTIVES			
• To teach	the students about	t the basic concept	s of Product Design and	l Process D	Pevelopment	
To expos	se the students ab	out concept genera	ion, selection and its tes	sting for pr	oduct devel	opment.
To literat	te various parts of	product architectu	re and its importance ir	n product d	lesign and d	levelopment.
To explai	in the needs of va	rious tools in indus	trial design process.			
To teach developr		t the design for ma	nufacturing and protot	yping tech	niques used	for product
UNIT – I INTI						9
planner, Com understanding	petitor and custo	mer - behavior a er in development	gration of customer, dest nalysis. Understanding and managing requiren	customer	– promoti	-
UNIT – II COI	NCEPT GENERA	TION, SELECTIO	NAND TESTING			9
internally - Exp	Plan and establish product specifications. Task - Structured approaches – clarification – search - externally and internally - Explore systematically - reflect on the solutions and processes – concept selection – methodology - benefits. Implications – Product change - variety - component standardization - product					
UNIT – III PR						9
Product develo development -	CODUCT ARCHI Opment managem - Fundamental an	FECTURE ent - establishing t l incidental interac	ne architecture - creation tions – related system le led interface specificatio	evel design	issues - sec	c layout ondary
Product develo development - systems -archit	CODUCT ARCHI Opment managem - Fundamental an	FECTURE ent - establishing t l incidental interac iks - creating detai	tions – related system le	evel design	issues - sec	c layout ondary
Product develo development - systems -archit UNIT - IV IN Integrate proce product perfor process - inves	CODUCT ARCHI opment managem - Fundamental an tecture of the chu IDUSTRIAL DES ess design - Man mance and manus	TECTURE ent - establishing the l incidental interact iks - creating detai IGN ging costs - Robust acturing processes	tions – related system le	evel design ons-Portfoli CAE, CAD r industrial	i issues - seco io Architectu , CAM tools l design - im	c layout ondary ire. 9 s-Simulating
Product develo development - systems -archit UNIT - IV IN Integrate proce product perfor process - inves industrial desi	CODUCT ARCHI opment managem - Fundamental an tecture of the chu IDUSTRIAL DES ess design - Man mance and manu stigation of custor gn process.	TECTURE ent - establishing the l incidental interact iks - creating detai IGN ging costs - Robust acturing processes her needs-concepto	tions – related system le led interface specificatio st design - Integrating (electronically – Need fo	evel design ons-Portfoli CAE, CAD r industrial managem	i issues - seco io Architectu , CAM tools l design - im	c layout ondary ire. 9 s-Simulating
Product develo development - systems -archit UNIT - IV IN Integrate proce product perfor process - inves industrial desi UNIT - V DES Definition - Es	CODUCT ARCHI opment managem - Fundamental an tecture of the chur IDUSTRIAL DES ess design - Mana mance and manu stigation of custor gn process. GIGN FOR MAN timation of Manu	TECTURE ent - establishing the l incidental interact iks - creating detai IGN ging costs - Robust acturing processes her needs-conceptor JFACTURINGAN	tions – related system le led interface specification st design - Integrating (electronically – Need for aalization - refinement -	evel design ons-Portfoli CAE, CAD r industrial managem DPMENT osts and as	i issues - seco io Architectu , CAM tools l design - imj ent of the sembly costs	s - Minimize
Product develo development - systems -archit UNIT - IV IN Integrate proce product perfor process - inves industrial desi UNIT - V DES Definition - Es	CODUCT ARCHI opment managem - Fundamental an tecture of the chur IDUSTRIAL DES ess design - Mana mance and manu stigation of custor gn process. GIGN FOR MAN timation of Manu	TECTURE ent - establishing the l incidental interact iks - creating detain IGN ging costs - Robust acturing processes her needs-conceptor JFACTURINGAN facturing cost - redustions - redustry isics - Principles of	tions – related system le led interface specification st design - Integrating (electronically – Need for aalization - refinement - D PRODUCT DEVELC ucing the component co	evel design ons-Portfoli CAE, CAD r industrial managem DPMENT osts and as	i issues - seco io Architectu , CAM tools l design - imj ent of the sembly costs	s – Minimize
Product develo development - systems -archit UNIT - IV IN Integrate proce product perfor process - inves industrial desi UNIT - V DES Definition - Es system comple	CODUCT ARCHI opment managem - Fundamental an tecture of the chur IDUSTRIAL DES ess design - Man mance and manu stigation of custor gn process. SIGN FOR MAN timation of Manu exity - Prototype b	TECTURE ent - establishing the l incidental interact iks - creating detain IGN ging costs - Robust acturing processes her needs-conceptor JFACTURINGAN facturing cost - redustions - redustry isics - Principles of	tions – related system le led interface specification st design - Integrating (electronically – Need for alization - refinement - D PRODUCT DEVELO ucing the component co prototyping - Planning for OUTCOMES	evel design ons-Portfoli CAE, CAD r industrial managem DPMENT osts and as	i issues - seco io Architectu , CAM tools l design - imj ent of the sembly costs	c layout ondary ure. 9 s-Simulating pact – design 9 s – Minimize mic Analysis.
Product develor development - systems -archit UNIT - IV IN Integrate proce product perfor process - inves industrial desi UNIT - V DES Definition - Es system complet CO	CODUCT ARCHI opment managem - Fundamental an tecture of the chur IDUSTRIAL DES ess design - Mana mance and manu stigation of custor gn process. SIGN FOR MAN timation of Manu exity - Prototype b	TECTURE ent - establishing the l incidental interaction iks - creating detail IGN ging costs - Robust acturing processes her needs-concepter JFACTURINGAN facturing cost - redusics - Principles of COURSE Students should be	tions – related system le led interface specification st design - Integrating (electronically – Need for alization - refinement - D PRODUCT DEVELO ucing the component co prototyping - Planning for OUTCOMES	evel design ons-Portfoli CAE, CAD r industrial manageme OPMENT osts and as for prototy	s I issues - second io Architectu	c layout ondary ure. 9 s-Simulating pact – design 9 s – Minimize mic Analysis.
Product development - systems -archit UNIT - IV IN Integrate proce product perfor process - inves industrial desi UNIT - V DES Definition - Es system complet CO Upon complet 1.	CODUCT ARCHI opment managem - Fundamental an tecture of the chur IDUSTRIAL DES ess design - Man mance and manus stigation of custor gn process. SIGN FOR MAN timation of Manu exity - Prototype b ion of this course, Get familiarized a Development. Know about the ir	TECTURE ent - establishing the l incidental interaction iks - creating detail IGN ging costs - Robust acturing processes her needs-concepter JFACTURINGAN facturing cost - red sics - Principles of COURSE Students should be bout the basic concepter inportance of concepter	tions – related system le led interface specification st design - Integrating (electronically – Need for alization - refinement - D PRODUCT DEVELC ucing the component co prototyping - Planning f OUTCOMES e able to epts of Product Design a pt generation, selection	evel design ons-Portfoli CAE, CAD r industrial manageme OPMENT osts and as for prototyp	s I source - second io Architectu Architectu CAM tools I design - imp ent of the sembly costs pes - Econor s I P ing. I P	s - Minimize mic Analysis. PO7, PO10, O11, PO12 PO7, PO10, O11, PO12
Product develor development - systems -archit UNIT - IV IN Integrate proce product perfor process - inves industrial desi UNIT - V DES Definition - Es system complet CO Upon complet 1. 1. 2.	CODUCT ARCHI opment managem - Fundamental an tecture of the chur IDUSTRIAL DES ess design - Man mance and manus stigation of custor gn process. SIGN FOR MAN timation of Manu exity - Prototype b ion of this course, Get familiarized a Development. Know about the ir	TECTURE ent - establishing the l incidental interaction iks - creating detail IGN ging costs - Robust acturing processes her needs-concepter JFACTURINGAN facturing cost - red siscs - Principles of COURSE Students should be pout the basic concepter	tions – related system le led interface specification st design - Integrating (electronically – Need for alization - refinement - D PRODUCT DEVELC ucing the component co prototyping - Planning f OUTCOMES e able to epts of Product Design a pt generation, selection	evel design ons-Portfoli CAE, CAD r industrial manageme OPMENT osts and as for prototyp	s If Sues - second issues - Econor sembly costs pes - Econor sembly costs per semb	s - Minimize mic Analysis. PO7, PO10, PO7, PO10, PO7, PO10, PO7, PO10,
Product development - systems -archit UNIT - IV IN Integrate proce product perfor process - inves industrial desi UNIT - V DES Definition - Es system complet CO Upon complet 1. I 2. F 3. C	CODUCT ARCHI opment managem - Fundamental an tecture of the chur IDUSTRIAL DES ess design - Man mance and manus stigation of custor gn process. SIGN FOR MAN timation of Manu exity - Prototype b ion of this course, Get familiarized a Development. Know about the ir	TECTURE ent - establishing the l incidental interaction iks - creating detail IGN ging costs - Robust acturing processes her needs-concepter JFACTURINGAN facturing cost - redusics - Principles of COURSE Students should be bout the basic concepter in product architect	tions – related system le led interface specification st design - Integrating (electronically – Need for alization - refinement - D PRODUCT DEVELC ucing the component co prototyping - Planning f OUTCOMES e able to epts of Product Design a pt generation, selection	evel design ons-Portfoli CAE, CAD r industrial manageme OPMENT osts and as for prototyp	s I issues - seco io Architectu , CAM tools l design - imp ent of the sembly costs pes - Econor s I s I pes - Econor s I F ing. I F I F I F	s - Minimize mic Analysis. PO7, PO10, O7, PO10,

TEXT BOC	TEXT BOOK				
1.	Ulrich K.T. and Eppinger S.D., "Product Design and Development" Tata McGraw -Hill				
	International Editions, 1999.				
REFEREN	REFERENCES				
1.	BelzA., 36-Hour Course: "Product Development" Tata McGraw-Hill, 2010.				
2.	Rosenthal S., "Effective Product Design and Development", Business One Orwin, Homewood,				
	1992, ISBN 1-55623-603-4.				
3.	Pugh S.," Total Design -Integrated Methods for successful Product Engineering", Addison				
	Wesley Publishing, 1991, ISBN 0-202-41639-5.				

Course Title	3D PRINT	ING	Carlin	LTPC			
Course Code			Credits	3003			
Course Category		PEC-I					
	OBJECTIVES						
To develop	To develop CAD models for 3D printing.						
To import	and export C	AD data and generate. STL file.					
To select a	specific mate	rial for the given application.					
To select a	3D printing	process for an application.					
To produce	e a product u	sing 3D printing or Additive Manufacturing (AM	Л).				
UNIT – I: 3D PRIN	JTING (ADE	ITIVE MANUFACTURING)		9			
		ion, Advantages, Additive V/s Conventional M	anufacturing pro	ocesses,			
Applications.							
UNIT – II: CAD FO	OR ADDITIV	'E MANUFACTURING		9			
CAD Data formats	, Data transla	ion, Data loss, STL format.					
UNIT – III: ADDI'	ΓΙ VE MANU	FACTURING TECHNIQUES		9			
		, SLS, SLM, Binder Jet technology. Process, Proc	ess parameter, P	rocess			
01	5	s. Additive Manufacturing Application Domains	1				
		e, Construction, Food Processing, Machine Tool	-				
UNIT – IV: MATE	RIALS			9			
Polymers, Metals, 1	Non-Metals, (Ceramics. Various forms of raw material – Liquid	, Solid, Wire, Po	wder;			
Powder Preparatio	n and their de	esired properties, Polymers and their properties.	Support Materia	ıls			
UNIT – V: ADDIT	IVE MANU	ACTURING EQUIPMENT AND POST PROC	ESSING	9			
Process equip:	ment- design	and process parameters					
Governing bo	nding mechai	nism					
Common faul	ts and trouble	shooting					
Process design	ı						
Post processin	ıg: requireme	nt and techniques					
Product qualit	5						
Inspection and	0						
Defects and their causes							
CO	6.1.1	COURSE OUTCOMES		PO			
1 1		Students should be able to					
_	1.Develop CAD models for 3D printing.PO3, PO5						
-	2. Import and Export CAD data and generate . STL file. PO3, PO5						
	-	aterial for the given application.		PO3, PO5			
	=	g process for an application.		PO3, PO5			
5. Prod	uce a product	using 3D Printing or Additive Manufacturing (A	11VI).	PO3, PO5			

TEXT BOC	
IEAI DUC	
1.	Andreas Gebhardt and Jan-Steffen Hötter "Additive Manufacturing: 3D Printing for Prototyping
	and Manufacturing", Hanser publications, United States, 2015, ISBN: 978-1-56990-582-1.
2.	Ian Gibson, David W. Rosen and Brent Stucker "Additive Manufacturing Technologies: Rapid
	Prototyping to Direct Digital Manufacturing", 2 nd edition, Springer., United States, 2015, ISBN-
	13: 978-1493921126.
REFEREN	CES
1.	Khanna Editorial, "3D Printing and Design", Khanna Publishing House, Delhi.
2.	CK Chua, Kah Fai Leong, "3D Printing and Rapid Prototyping- Principles and Applications",
	World Scientific, 2017.
3.	J.D. Majumdar and I. Manna, "Laser-Assisted Fabrication of Materials", Springer Series
	inMaterial Science, 2013.
4.	L. Lu, J. Fuh and Y.S. Wong, "Laser-Induced Materials and Processes for Rapid Prototyping",
	Kulwer Academic Press, 2001.
5.	Zhiqiang Fan And Frank Liou, "Numerical Modelling of the Additive Manufacturing
	(AM)Processes of Titanium Alloy", InTech, 2012.

Course Title	TRIBOLOC	GY		LTPC		
Course Code			Credits	3003		
Course Category		PEC-I				
		OBJECTIVES				
1.To understan	nd the concept	t and different types of friction				
2. To understa	nd the concep	t and different types of wear				
3. To understa	nd the mecha	nism of hydro static lubrication				
4 To understan	nd the mechar	ism of hydro static lubrication				
5. To understa	nd the concep	t and testing of lubricants				
UNIT – I				9		
dissipation. Theory present concept of f characteristics of me	of molecular friction – bou	topography of surfaces – contact between surfaces – c attraction – fretting corrosion and prevention – v ndary friction – oiliness – variables of boundary fri -metals– rolling friction – sources of measurement o	ariables in c ction – frictio	dry friction -		
UNIT – II				9		
		ors affecting wear. Adhesive wear – abrasive wear, f mination – wear measurement.	atigue wear	- corrosive		
UNIT – III				9		
problems – differen simple problems – l	t types of con	drostatic lubrication – hydrostatic step bearing – mu npensation and their effect on bearing, parameters – urnal bearing, simple problems – hydrostatic squeez	hydrostatic	lift,		
UNIT – IV				9		
 design of hydrod bearings and rotor 	HYDRODYNAMIC LUBRICATION - Solution of Reynold's equation – application to tilting pad thrust bearing – design of hydrodynamic journal bearings – force feed of oil flow with various types of grooves – dynamic bearings and rotor systems – brief discussion, lubrication systems, bearing materials – gas bearings – brief discussion – elasto hydrodynamic lubrication – brief discussion.					
UNIT – V				9		
LUBRICANTS AND MAINTENANCE - Lubricants - types-solids ,and liquid-properties-additives-testing- reclamation of lubricants, surface treatment-phospating of metal surface, Teflon coating. Predictive maintenance-signature analysis and condition monitoring-basic principles-instrumentation. (APPROVED HAND BOOK MAY BE USED IN THE EXAMINATION)						
CO		COURSE OUTCOMES		PO		
		Students should be able to know	•			
		types of friction		PO1, PO4		
		types of wear		PO1, PO4		
		ydrostatic lubrication		PO2, PO4		
4. The me	echanism of h	ydrodynamic lubrication		PO2, PO4		
5. The co	ncept and tes	ting of lubricants		PO1, PO2, PO5		

TEXT BOC	К
1.	HUTCHINGS. M, Tribology, Friction and Wear of Engg. Materials, Edward Arnold, London,
	1992.
2.	MAJUMDAR, Introduction of Tribology of Bearings, A.H.Wheeler & Co., 1986.
REFERENC	CES
1.	NCALC, NEWNCS, Tribology Handbook, Butterworths, 1975.
2.	DUDLEY D.FULLER, Theory and Practice of Lubrication for Engineers, John Wiley & Sons, 1984.
3.	CAMERON.A, Basic Lubrication Theory, Wiley Eastern Ltd., 1987.
4.	BHARAT BHUSAN & B.K.GUPTA, Handbook of Tribology, Tata McGraw Hill Inc., 1991.

Course Titl	e	CAD/CAM LABORATORY	Carlin	LTPC				
Course Coc	le		Credits	0032				
Course Category PCC								
OBJECTIVES								
	 To gain practical experience in handling 2D drafting and 3D modelling software systems. To study the features of CNC machine tool. 							
	5	tudents to modern control systems (Fanuc, Sinumeric etc.,)						
		e application of various CNC machines like CNC lathe, CNC Ver	tical machini	ng centre,				
CNC	C EDM	and CNC wire-cut and study of rapid prototyping.						
		LIST OF EXPERIMENTS						
		3-D GEOMETRIC MODELLING (24- PERIODS)						
		assembly model of following machine elements using 3-D mod BD Modelling software	elling softw	are				
1.		ge Coupling						
2.		nmer Block						
3.		w Jack						
4.		e Tailstock						
5.		zersal Joint						
6.		hine Vice						
7.		necting rod						
8.	Pisto	<u> </u>						
9.		hshaft						
	Ciui	MANUAL PART PROGRAMMING (21 PERIODS)						
I. Part Pr	ogrami	ning - CNC Machining Centre						
1.	U	ar Cutting.						
2.		ular cutting.						
3.		er Radius Compensation.						
4.		ned Cycle Operations.						
II. Part P		ming - CNC Turning Centre						
1.	-	ght, Taper and Radius Turning.						
2.		ead Cutting.						
3.		gh and Finish Turning Cycle.						
4.	Drilling and Tapping Cycle.							
		ided Part Programming						
1.	-	Data and Post process generation using CAM packages.						
2.		lication of CAPP in Machining and Turning Centre.						
3.		y of CNC EDM, CNC EDM Wire-Cut and rapid Prototyping.						

СО	COURSE OUTCOMES	РО				
Upon comp	Upon completion of this course, Students should be able to					
1.	Gain practical experience in handling 2D drafting and 3D modelling software systems. PO1, PO					
2.	Study the features of CNC machine tool.	PO1, PO5				
3.	Expose students to modern control systems (Fanuc, Sinumerik etc.,)	PO1, PO5				
	Know the application of various CNC machines like CNC lathe, CNC Vertical					
4.	machining centre, CNC EDM and CNC wire-cut and study of rapid	PO1, PO5				
	prototyping.					
TEXT BOO	K					
1.	Prof. Sham Tickoo, Pro/Engineer Wildfire 4.0: For Engineers and Designers, Dr	eamtech Press,				
	2008.					
2.	K. Venugopal, Engineering Drawing & Graphics, New Age International, 2016.					
REFERENC	REFERENCES					
1.	Thomas Ewing French, Charles J. Vierck, Robert Jay Foster, Engineering Drawin	ng and Graphic				
	Technology, McGraw-Hill, 1993.					
2.	Frederick E. Giesecke, Alva E. Mitchell, Henry C. Spencer, Technical Drawing with Engineering					
	Graphics, Mechanical Design Technology, 2016.					
3.	Kuang-Hua Chang, Machining Simulation Using SOLIDWORKS CAM, SDC Publications, 2019.					
4.	Hans B. Kief, Helmut A. Roschiwal, CNC Handbook, McGraw Hill Professional	l, 2012.				

SEMESTER- VI

Course Title	AUTOMATION IN MANUFACTURING	0 11	LTPC	
Course Code		Credits	3003	
Course Category	PCC			
	OBJECTIVES			
• To know the	basic components of CIM and its hardware and software			
To understar	nd about CAD/CAM and its integration with manufacturing			
To nurture the second sec	ne principles of computer aided process planning and GT			
To understar	nd about different Control and monitoring systems used in CIM			
To study abc	out FMS and its applications			
UNIT - I INT	TRODUCTION TO AUTOMATION SYSTEM		9	
Automating, Manu Relationships, Prod System, Advanced	tems, Types of Automation, Computerized manufacturing Supp ifacturing Industries and Products, Manufacturing operations, uction Concepts and Mathematical Models. Basic elements of an A Automation Functions, Levels of Automation.	, Product /	Production	
	TEGRATION OF MANUFACTURING SYSTEM		9	
	AD, CAM and CAE, CIM Definition, CIM Wheel, CIM component mputers - Needs of CIM, Benefits of CIM. CIM Hardware & Softw			
	k system - Data base and DBMS - requirement, features and archi			
	Network) System, Communication Matrix, Network Architectures,			
	TOMATED PROCESS PLANNING SYSTEM		9	
and Generative typ Manufacturing Plan Group Technology	 tructure of Process Planning, Process Planning function, CAPP - Too CAPP, Concurrent engineering, Design for Manufacturing aroning. Introduction - coding and classification system, Production Flow ICLASS, Benefits of Group Technology, Machine cell design. 	nd Assembly	, Advanced	
	TOMATED CONTROL AND MONITORING SYSTEM		9	
Fundamentals of NC Technology – Basic components of an NC System, NC Coordinate and Motion Control systems, Computer Numerical Control, Features of CNC, Machine Control Unit for CNC, CNC Software, DNC Machines, Application of NC machine tools Applications, Structure of CNC Machines, CNC Controllers, NC Part Programming, Computer-Assisted Part Programming. Features and Applications of CNC Turning Centre, CNC Milling Machine, CNC Turn-Mill Centre, CNC machining Centre, CNC Tooling system and Automatic Tool Changing System, Computer Aided Quality Control - contact, non contact inspection methods, Coordinate Measuring Machine CMM - Integration of CAQC with CAD / CAM.				
UNIT - V FLI	EXIBLE MANUFACTURING SYSTEMS		9	
scheduling and con Production Suppor Guided Vehicles, A Developments in M	5. Components of FMS, Type of FMS, Classification of FMS Configu trol. Knowledge Based Scheduling, Applications and Benefits of F t Machines and Systems -Industrial Robots, Automated Material F utomated Storage and Retrieval system. lanufacturing Technologies- AI and Expert System, Agile manufac tual Manufacturing, Simulation in Manufacturing – Factories of F	⁷ MS. Iandling, Au cturing, Lean	tomatic	

CO	COURSE OUTCOMES	РО				
Upon comp	Upon completion of this course, Students should be able to					
1.	Classify the Production system and Automated Systems in Manufacturing	PO1, PO2, PO5				
2.	Discuss the various Components, Evolution, Network and Data base system for CIM.	PO1, PO2, PO5				
3.	Acquire Process Planning, part coding and Group technology concept	PO1, PO2, PO5				
4.	Get CNC machining and programming knowledge	PO1, PO2, PO5				
5.	Obtain Knowledge in Flexible Manufacturing.	PO1, PO2, PO5				
TEXT BOO)K					
1.	KANT VAJPAYEE.S, Principles of Computer-Integrated Manufacturing; 1st ed. P	HI				
2.	MIKELL P. GROOVER, Automation, Production Systems & CIM, 2 nd ed. PHI.					
3.	3. James A.Rehg, Henry W.Kraebber, Computer- Integrated Manufacturing, second Edition, Pearson Education.					
4.	P.N. Rao, CAD/CAM Principles and Applications Second Edition, TMH.					
REFERENC	CES					
1.	1. Radhakrishnan.P, Subramanyan. S, Raju.V, 'CAD/CAM/CIM', Second Edition, New Age International publishers,					
2.	Daniel Hunt.V., 'Computer Integrated Manufacturing Hand Book', Chapman & Hall,					
3.	3. Groover M.P, 'Computer Aided Design and Manufacturing', Prentice Hall of India,					
4.	Yorem Koren, 'Computer Control of Manufacturing System', Tata McGraw Hill,					
5.	Ranky Paul. G., 'Computer Integrated Manufacturing', Prentice Hall International,.					
6.	ROGER MANNAM, Computer Integrated Manufacturing from Concepts of Realization 1 st ed. Addison Wiley.					
7.	P. N. Rao, Computer Aided Manufacturing, TMH.					

Course Title	MECHATR	ONICS		Cradita	LTPC
Course Code				Credits	3003
Course Category		PCC			
		OBJECTIVES			
 displacemunderstam To understam To understam To develop mechanica To study a and also, s To understam 	ent, flow, tem d the emergin tand the princ s Mechatronic o mathematica 1 and hydro m bout the work ome case stud	l models for various systems such echanical systems ing principle of Programmable lo ies are discussed on the Mechatro ent stage of design process and al	systems which are ems, system model n as mechanical, ele gic controller (PLC onics systems.	e very much s which are i ectrical, therr) and its com	essential to nvolved for nal, electro nponents
Control Systems – Sensors for Displa	Microprocesso cement, Posit	nsducers: Introduction to Mecha or based Controllers–Sensors and on and Proximity; Velocity, Mo Sensors – Selection of Sensors.	Transducers – Per	formance Te	rminology –
UNIT – II	Jerature, Ligh	Sensors - Selection of Sensors.			9
Mechanical Actuat	ion Systems - n Systems – M	and Hydraulic System –Directi Cam – Gear Train – Ratchet and echanical Switches – Solid State S	l pawl – Belt and	Chain Drives	s -Bearings-
UNIT – III					9
Rotational – Trar Continuous and c Derivative Mode –	nslational Sys liscrete proces Integral Mode	s: Building blocks of Mechanica tems, Electro-Mechanical System is Controllers – Control Mode: e – PID Controllers – Digital Contr Micro Processor Control.	ms – Hydraulic Two –Step mode	- Mechanica - Proportio	al Systems- nal Mode -
UNIT – IV					9
Output Processing	-Programmir	Programmable Logic Controllers g – Mnemonics – Timers, Interna Handling – Analogs Input / Outp	al relays and count	ers – Shift R	egisters –
	ronics System	s: Stages in designing Mechatron	ics Systems - Trad	itional and N	/lechatronics
Design – Possible I	Design Solutio	ns–Case Studies: Pick and place r Camera, Washing machine.	5		

СО	COURSE OUTCOMES	РО
Upon comp	eletion of this course, Students should be able to	
1.	Demonstrate the basic structure of mechatronics system, different sensors and its characteristics.	PO1
2.	Evaluate various types of hydraulic and pneumatic actuators used in mechatronics and they will be able to design and develop simple hydraulic and pneumatic automation circuits.	PO2, PO3
3.	Illustrate the empirical models for the Mechanical, Electrical, Thermal, Fluid, Electro-mechanical and Hydro-mechanical Systems.	PO2, PO3
4.	Get the knowledge on the working principles of the different components of the programmable logic controller (PLC) with Ladder diagrams.	PO2, PO3
5.	Realize the working of the different real-world systems used in our daily life through various case studies.	PO2, PO3
TEXT BOO		
1.	W. Bolton, "Mechatronics", Pearson Education, 3rd Edition, 2007.	
2.	HMT Ltd, Mechatronics, Tata McGraw Hill, 2007.	
REFERENC	CES	
1.	Michael B. Histand and David G. Alciatore, "Introduction to Mechatronics and Systems", McGraw-Hill International Editions, 2007. 3rd Edition	Measurement
2.	Bradley D. A., Dawson D., Buru N.C. and. Loader A.J, "Mechatronics", Chapman	n and Hall, 1993.
3.	Dan Necsulesu, "Mechatronics", Pearson Education Asia, 2002 (Indian Reprint).	
4.	Lawrence J. Kamm, "Understanding Electro – Mechanical Engineering", An Intro Mechatronics, Prentice – Hall of India Pvt., Ltd., 2000.	
5.	Nitaigour Premchand Mahadik, "Mechatronics", Tata McGraw-Hill publishing (2003	Company Ltd,
6.	Prof. C. R. Venkataramana, Mechatronics, Sapna Book House, 2003.	

	REFRIGERATION AND AIR CONDITIONING		LTPC		
Course Code		Credits	3003		
Course Category	PEC-II				
	OBJECTIVES				
	To learn the concepts of refrigeration & its related cycles.				
	• To learn the concepts of refrigeration systems and the mechanisms of refrigeration equipment.				
9	the principles of other refrigeration systems.				
	e concepts of thermodynamics to air conditioning.				
To analyze	the principles of air conditioning equipment.				
UNIT – I INTROI	DUCTION		9		
	efrigeration - Unit of Refrigeration and C.O.P Ideal cycles- fication - Nomenclature - ODP & GWP.	Refrigeran	ts Desirable		
UNIT - II VAPO	UR COMPRESSION REFRIGERATION SYSTEM		9		
heating- effects of condenser and evaporator pressure on COP- multi pressure system - low temperature refrigeration - Cascade systems – problems. Equipments: Type of Compressors, Condensers, Expansion devices, Evaporators (Elementary treatment).					
devices, Evaporato	scade systems – problems. Equipments: Type of Compressors, ors (Elementary treatment).		, Expansion		
devices, Evaporate UNIT - III OTHE Working principle	scade systems - problems. Equipments: Type of Compressors,	Condensers - Steam jet r	efrigeration		
devices, Evaporate UNIT – III OTHE Working principle Thermoelectric ref	scade systems – problems. Equipments: Type of Compressors, ors (Elementary treatment). R REFRIGERATION SYSTEMS s of Vapour absorption systems and adsorption cooling systems -	Condensers - Steam jet r	efrigeration-		
devices, Evaporato UNIT - III OTHE Working principle Thermoelectric ref UNIT - IV PSYCE Fundamental prop room sensible heat	scade systems – problems. Equipments: Type of Compressors, ors (Elementary treatment). R REFRIGERATION SYSTEMS s of Vapour absorption systems and adsorption cooling systems - rigeration- Air refrigeration - Magnetic - Vortex and Pulse tube ref	Condensers - Steam jet r frigeration sy ric processes mfort and co	9 efrigeration- ystems. 9 s, grand and omfort chart,		
devices, Evaporato UNIT - III OTHE Working principle Thermoelectric ref UNIT - IV PSYCE Fundamental prop room sensible heat factor governing o	scade systems – problems. Equipments: Type of Compressors, ors (Elementary treatment). R REFRIGERATION SYSTEMS s of Vapour absorption systems and adsorption cooling systems - rigeration- Air refrigeration - Magnetic - Vortex and Pulse tube ref HROMETRIC PROPERTIES AND PROCESSES perties of psychrometry - Use of psychometric chart, psychometri factor, by pass factor, requirements of comfort air conditioning, co	Condensers - Steam jet r frigeration sy ric processes mfort and co	9 efrigeration- ystems. 9 s, grand and omfort chart,		

СО	COURSE OUTCOMES	РО
Upon com	pletion of this course, Students should be able to	
		PO1, PO2,
1.	Explain the basic concepts of refrigeration.	PO3, PO6,
		PO10, P12
		PO1, PO2,
2.	Explain the vapor compression refrigeration systems and to solve problems	PO3, PO6,
		PO10, P12
		PO1, PO2,
3.	Discuss the various types of refrigeration systems	PO3, PO6,
		PO10, P12
		PO1, PO2,
4.	Calculate the psychrometric properties and its use in psychrometric processes	PO3, PO6,
		PO10, P12
_	Explain the concepts of air conditioning and to solve problems	PO1, PO2,
5.		PO3, PO6,
		PO10, P12
TEXT BO		D 11 : 0017
1.	Arora, C.P., "Refrigeration and Air Conditioning", 3rd edition, McGraw Hill, New	Delhi, 2017.
2.	P.L BALLANY, "Refrigeration and Air conditioning" Khanna Publishers, 1972	
REFEREN	CES	
1.	ARORA S.C AND DOMKUNDWAR S, Refrigeration & Air Conditioning, Dhang	oat Rai and Sons
1.	Publishers, 2007.	
2.	MANOHAR PRASAD, Refrigeration and Air Conditioning, Wiley Eastern Ltd,	
3.	Jones W.P., "Air conditioning engineering", 5th edition, Elsevier Butterworth-Heir	nemann, 2007.
4.	Roy J. Dossat, "Principles of Refrigeration", 4th edition, Pearson Education Asia, 2	011.
5.	Stoecker, W.F. and Jones J. W., "Refrigeration and Air Conditioning", Tata	McGraw Hill,
5.	2 nd Edition, New Delhi, 2014.	

Course Title	INTERNA	COMBUSTION I	ENGINES	Creadita	LTPC
Course Code				Credits	3003
Course Category		PEC-II			
OBJECTIVES					
• To understand fuel supply system and combustion phenomena with different combustion chambers of SI engines					
 To understa principles of 		pray structure and	air movements and super cl	narging, turl	bo charging
To understar	nd the polluta	nt formation and emi	ssion controlling methods in IO	C engines	
To understar	nd the function	ns of different sensor	s and Engine management syst	tems	
To know the	recent trends	in the development	of fuel supply and ignition met	hods in IC er	ngines
UNIT - I SPARK I	GNITION EN	GINES			9
	-		n carburetors – petrol injection be of combustion chambers in S	•	normal and
UNIT - II COMPR	ESSION IGN	ITION ENGINES			9
	n CI engines -	Ũ	ect and indirect ignition system , spray generation and evapor		
UNIT - III POLLU	TANT FORM	ATION AND CON	TROL		9
Pollutants from IC engines – formation of NO _x , CO and hydrocarbon, emission mechanism, particulate emission – method of controlling emissions Catalytic convertors and particulate traps – methods of measurements of emission and driving cycles.					
UNIT- IV ENGIN	E ELECTRON	ICS			9
	, 0	ent systems – positi nsor – O2 sensor – ty	on displacement and speed ser ces.	nsor – pressi	ure sensor –
UNIT - V RECENT	Γ TRENDS IN	IC ENGINES			9
0	i 0	0	engines, dual fuel engine – n n ignition engines – plasma ig	-	,

CO	COURSE OUTCOMES	РО			
Upon com	pletion of this course, Students should be able to				
1.	Explain the principles of fuel supply system and combustion mechanism in SI engines	PO1			
2.	Examine the air flow movements in various combustion chambers of CI engines	PO1, PO2			
3.	Analyze the emission mechanism and controlling methods of pollutants in IC engines	PO2, PO7			
4.	Understand the role of engine management systems and sensors.	PO1			
5.	Gain knowledge about the recent trends in the engine development.	PO1, PO5			
TEXT BO	TEXT BOOK				
1.	GANESAN. V. Internal Combustion Engines, Tata McGraw Hill, 2012, 4th Editio	n.			
2.	GILL SMITH & ZURICH, Fundamentals of IC Engines. Oxford and IBH publica	tion Co,1999.			
3.	JOHN B. HEYWOOD, Internal Combustion Engine Fundamentals, McGraw Hill,	Ist edition, 1999			
REFEREN	CES				
1.	DOMKUNDWAR V.M, Internal Combustion Engines, Dhanpat Rai & Sons, 2018	3			
2.	P. L. Ballaney, Internal Combustion Engines, Khanna Publishers, 2006, 6th Editio	n.			
3.	MATHUR R.B AND SHARMA. R.B, Internal Combustion Engines, Dhanpat Rai	& Sons, 2016			

Course Ti	tle	TURBO MACHINES	Cradita	L T P C
Course Co	ode		Credits	3003
Course Cat	tegory	PEC-II		
		OBJECTIVES		
•	To unde	erstand the fundamental concepts of turbo machines.		
٠	To learr	the velocity triangle & design concept of centrifugal fan & blower	r.	
•	To learr	the velocity triangle & design concept of centrifugal compressor.		
•	To learr	the velocity triangle & design concept of axial compressor.		
•	To learr	the velocity triangle & design concept of axial & radial turbines.		
UNIT - I B	ASIC C	ONCEPT OF TURBO MACHINES		9
reheat, prel	heat. Ae oefficier	Total-to-total efficiency, total to static efficiency, infinitesimal staro-foil section, cascading of compressor and turbine blades, energy at for compressor and turbine blades, variation of lift, deflection <i>a</i> .	y transfer in	terms of lift
UNIT – II	CENTR	IFUGAL FANS AND BLOWERS		9
v 1	0	design parameters, flow analysis in impeller blades, volute res and selection, fan drives and fan noise.	and diffu	sers, losses,
UNIT - III	CENTR	IFUGAL COMPRESSOR		9
Constructio	on detai	s, types, impeller flow losses, slip factor, diffuser analysis, losses a	nd perform	ance curves.
UNIT - IV	AXIAL	FLOW COMPRESSOR		9
		gle, enthalpy-entropy diagram, stage losses and efficiency, workd nd performance characteristics.	one factor,	simple stage
~ *		ND RADIAL FLOW TURBINES		
UNIT -V A	AXIAL A			9
	city dia	grams, reaction stages, losses and coefficients blade design	principles,	
Stage velo	city dia	grams, reaction stages, losses and coefficients blade design	principles,	
Stage velo performano CO	city dia ce chara pletion c	agrams, reaction stages, losses and coefficients blade design cteristics. COURSE OUTCOMES of this course, Students should be able to		testing and
Stage velo performano CO	city dia ce chara pletion c Comp	igrams, reaction stages, losses and coefficients blade design cteristics. COURSE OUTCOMES of this course, Students should be able to ute the energy transfer and energy transformation in turbomachin		testing and
Stage velo performane <u>CO</u> Upon comj	city dia ce chara pletion c Comp Analy	agrams, reaction stages, losses and coefficients blade design cteristics. COURSE OUTCOMES of this course, Students should be able to ute the energy transfer and energy transformation in turbomachin se the design of centrifugal fans & blowers		testing and
Stage velo performano CO Upon com 1.	city dia ce chara pletion c Comp Analy Analy	Igrams, reaction stages, losses and coefficients blade design cteristics. COURSE OUTCOMES of this course, Students should be able to ute the energy transfer and energy transformation in turbomachin se the design of centrifugal fans & blowers se the design of centrifugal compressor		testing and PO PO1, PO2
Stage velo performano CO Upon com 1. 2.	city dia ce chara pletion c Comp Analy Analy Analy	agrams, reaction stages, losses and coefficients blade design cteristics. COURSE OUTCOMES of this course, Students should be able to ute the energy transfer and energy transformation in turbomachin se the design of centrifugal fans & blowers		testing and PO PO1, PO2 PO2

TEXT BO	ОК
1.	S.M YAHYA, Fundamentals of Compressible flow with Aircraft and Rocket Propulsion, New
	Age International, 6 th Edition, 2018.
2.	GANESAN. V, Gas Turbines, Tata McGraw Hill, 3 rd edition, 2017
3.	SHEPERD DG. Theory of Turbo machines, McMillan, 1969
REFEREN	ICES
1.	JOHN D.ANDERSON Jr. Introduction to Flight, 7th Edition, Tata McGraw Hill ISE 2011.
2.	ALAN J. CHAPMAN, WILLIAM.F.WALKER, HOLT, Introduction to gas dynamics, Rineharl
	and winston, 1971
3.	Dr.SL. SOMASUNDRAM, Gas dynamics and jet propulsion. New Age International (P) Limited,
	Publishers; First edition (2008).
4.	A.H.CHURCH ND.JAGDISH LAL, Centrifugal Pumps and Blower, Metropolitan Book Co. PVT
	Ltd. ND 1973.
5.	COHEN H. REC ROGERS & SRAVANAMUTOO, Gas Turbine Theory, Addison Wiley, 6th
	Edition, 2008.
6.	KADAMBHI V. MANOHAR PRASAD, Introduction to Energy Conversions, Vol - III, Turbo
	machines, Wiley Eastern, 2011.
7.	JAGDISHLAL, Centrifugal Pumps and Blowers, Metropolitan Press (P) Ltd., 1973

Course C	itle	GAS DYNAMICS & JET PROPULSION	Cradita	LTPC		
Course C	Code		Credits	3003		
Course Ca	ategory	PEC-II				
		OBJECTIVES				
		and the basic difference between incompressible flow and compriable area ducts.	pressible flo	ow and flow		
• To	To understand the flow through constant area Ducts.					
• To	To understand the phenomenon of shock waves and its effect on flow.					
• To	To gain the basic knowledge about jet propulsion					
• To	gain the	basic knowledge and rocket propulsion.				
UNIT – I				9		
flows - Sta flow throu	agnation a ugh varia	5 AND ISENTROPIC FLOWS - Energy and momentum equation states, Mach waves and Mach cone - Effect of Mach number on con ble area ducts - Nozzle and Diffusers - Use of Gas tables.	-			
UNIT – II	[9		
(Fanno flo	ow) - Vari	DUCTS - Flow through constant area ducts with heat transfer (Ray ation of flow properties - Use of tables and charts - Generalized ga	-			
UNIT – II	I			9		
		BLIQUE SHOCKS - Governing equations - Variation of flow paran s - Prandtl - Meyer relations - Use of table and charts - Applications		s the normal		
UNIT – IV	V			9		
Operation	ı principl	- Theory of jet propulsion - Thrust equation - Thrust power and e, cycle analysis and use of stagnation state performance of ram j - Aircraft combustors		e efficiency -		
				5		
UNIT - V	•			5		
UNIT - V SPACE PE	ROPULS	ON - Types of rocket engines - Propellants - Ignition and combu mance study - Staging - Terminal and characteristic velocity - App		, turbofan & 9 ory of rocket		
UNIT - V SPACE PE	ROPULS			, turbofan & 9 ory of rocket		
UNIT - V SPACE PI propulsion	ROPULS n - Perfor	mance study - Staging - Terminal and characteristic velocity - App COURSE OUTCOMES of this course, Students should be able to		, turbofan & 9 ory of rocket 5pace flights.		
UNIT - V SPACE PI propulsion	ROPULS n - Perfor	mance study - Staging - Terminal and characteristic velocity - App COURSE OUTCOMES	blications - S	, turbofan & 9 ory of rocket 5pace flights.		
UNIT - V SPACE PF propulsion CO Upon com	ROPULS n - Perfor pletion of Apply Apply	mance study - Staging - Terminal and characteristic velocity - App COURSE OUTCOMES of this course, Students should be able to the concept of compressible flows in variable area ducts. the concept of compressible flows in constant area ducts.	blications - S	, turbofan & 9 ory of rocket Space flights. PO		
UNIT - V SPACE PF propulsion CO Upon com 1.	ROPULS n - Perfor pletion c Apply Apply Exami	mance study - Staging - Terminal and characteristic velocity - App COURSE OUTCOMES of this course, Students should be able to the concept of compressible flows in variable area ducts. the concept of compressible flows in constant area ducts. ne the effect of compression and expansion waves in compressible	plications - S	, turbofan & 9 ory of rocket 5pace flights. PO PO1, PO2		
UNIT - V SPACE PE propulsion CO Upon com 1. 2.	ROPULS n - Perfor pletion of Apply Apply Exami Use th	mance study - Staging - Terminal and characteristic velocity - App COURSE OUTCOMES of this course, Students should be able to the concept of compressible flows in variable area ducts. the concept of compressible flows in constant area ducts.	e flow.	, turbofan & 9 ory of rocket 5pace flights. PO PO1, PO2 PO1, PO2		

TEXT BO	ОК
1.	S.M. Yahya, "Fundamentals of Compressible Flow ", New Age International (P)Limited, New
	Delhi, 2018.
2.	Anderson, J.D., "Modern Compressible flow", 3rd Edition, Tata McGraw Hill, 2017.
REFEREN	ICES
1.	Cohen. H., G.E.C. Rogers and Saravanamutto, "Gas Turbine Theory", Longman Group Ltd., 2001.
2.	Ganesan. V., "Gas Turbines", Tata McGraw Hill Publishing Co., New Delhi, 2017.
3.	Shapiro. A.H.," Dynamics and Thermodynamics of Compressible Fluid Flow", John wiley, New York, 1977.
4.	Sutton. G.P., "Rocket Propulsion Elements", John wiley, New York, 7thEdition. 2017
5.	Zucrow. N.J., "Principles of Jet Propulsion and Gas Turbines", John Wiley, New York.
6.	E. Radhakrishnan, Gas Dynamics, PHI, 6thEdition. 2017.

	ENERGY CONSERVATION IN INDUSTRIES	Credits	LTPC
Course Code		Credits	3003
Course Category	PEC-II		
	OBJECTIVES		
	tand the concepts of thermodynamic limitations and energy co tion, agricultural and industrial sectors.	onservation i	in domestic
	tand the methodology of improving the boiler performance and	l energy con	servation i
	the heat exchanger systems, heat exchange networking, wa on schemes.	iste heat re	covery an
• To learn the	ne concepts of energy conservation in various industries and their	case studies	
• To learn th	e concepts of economic analysis of energy and energy auditing.		
UNIT - I CONCE	PT OF ENERGY CONSERVATION		9
availability analysi	thermodynamic limitations: first and second laws of thermodyna is of various thermodynamics processes/devices/cycles. Need for tation, agricultural and industrial sectors – Lighting and HVAC	r energy con	servation i
UNIT - II THERM	AL ENERGY CONSERVATION		9
the boiler performa	ns and processes – combustion efficiency – boiler performance – me ance – steam turbine and distribution systems: energy conservatio	on in turbine	
	f correct pressure, temperature and quality of steam – condensate ad gas removal – thermal insulation.	e recovery -	recovery c
flash steam - air ar	correct pressure, temperature and quality of steam – condensate ad gas removal – thermal insulation. EXCHANGER SYSTEMS	e recovery –	
flash steam – air ar UNIT - III HEAT Recuperative and systems – heat pur	nd gas removal – thermal insulation. EXCHANGER SYSTEMS regenerative heat exchangers – compact heat exchangers – fluid mps – heat pipes – heat recovery from industrial processes. heat target setting, problem table approach, composite curves – w	lized bed he	g at exchang etworking
flash steam – air ar UNIT - III HEAT Recuperative and systems – heat pur pinch analysis – t cogeneration scher	nd gas removal – thermal insulation. EXCHANGER SYSTEMS regenerative heat exchangers – compact heat exchangers – fluid mps – heat pipes – heat recovery from industrial processes. heat target setting, problem table approach, composite curves – w	lized bed he	etworking ecovery and
flash steam – air ar UNIT - III HEAT Recuperative and systems – heat pur pinch analysis – the cogeneration schert UNIT - IV ENERC Energy conservation emergency DG sets	nd gas removal – thermal insulation. EXCHANGER SYSTEMS regenerative heat exchangers – compact heat exchangers – fluid mps – heat pipes – heat recovery from industrial processes. heat target setting, problem table approach, composite curves – w nes. GY CONSERVATION IN INDUSTRIES on in pumps, fans, compressed air systems, refrigeration & ai s, illumination, electrical motors – energy efficient motors and vari- conservation in various industries such as cement, iron and ste	lized bed he exchange n raste heat re ir conditioni iable speed r	etworking ecovery and ng systems notors. Cas
flash steam – air ar UNIT - III HEAT Recuperative and systems – heat pur pinch analysis – to cogeneration scher UNIT - IV ENERO Energy conservative emergency DG sets studies for energy processing, refiner	nd gas removal – thermal insulation. EXCHANGER SYSTEMS regenerative heat exchangers – compact heat exchangers – fluid mps – heat pipes – heat recovery from industrial processes. heat target setting, problem table approach, composite curves – w nes. GY CONSERVATION IN INDUSTRIES on in pumps, fans, compressed air systems, refrigeration & ai s, illumination, electrical motors – energy efficient motors and vari- conservation in various industries such as cement, iron and ste	lized bed he exchange n raste heat re ir conditioni iable speed r	etworking ecovery an ng systems notors. Cas

СО	COURSE OUTCOMES	РО
Upon com	pletion of this course, Students should be able to	
1.	Apply availability analysis of various thermodynamics processes, devices and cycles and explain the energy conservation in domestic, transportation, agricultural and industrial sectors.	PO1, PO2
2.	Apply the methodology of improving the boiler performance, steam turbine and distribution systems: explain the energy conservation in turbines.	PO1, PO2
3.	Explain the concepts of heat exchanger systems, heat pumps, heat pipes and heat recovery from industrial processes and apply the heat exchange networking, waste heat recovery and cogeneration schemes.	PO2, PO3
4.	Explain the energy conservation in pumps, fans, compressed air systems, refrigeration & air conditioning systems, emergency DG sets, illumination, electrical motors, energy efficient motors and variable speed motors.	PO2, PO3
5.	Apply economic analysis of energy, energy auditing, explain the energy conservation systems analysis for safety, health and pollution.	PO2, PO3
TEXT BO	OK	
1.	Patrick, D. and Fardo, S. W., Energy conservation and Management, Prentice-Ha	all Inc., 1990
2.	Witte, Larry C., Industrial energy management and utilization, Hemisph Washington, 1988	ere publishers,
3.	Tyagi, A. K., Handbook of energy audits and management, TERI PCRA Booklets	5.
REFEREN	CES	
1.	Thipse, S.S., Energy conservation and management, Alpha Science Internation	nal Ltd., 2014
2.	Frank Kreith and Yogi Goswami, D., Energy Management and Conservation H Press, 2008.	land Book, CRC

Course Ti	itle MECHATRONICS LABORATORY	Castita	L T P C
Course Co	ode	- Credits	0032
Course Cat	tegory PCC	·	
	OBJECTIVES		
	o understand the functions of the various valves, logic gates and cylinde		
	neumatic systems through the simulation and PLC programming on the		
	o understand the working of servo systems and microcontrollers for a su		
• To	o design and simulate the hydraulic and pneumatic circuits by using LA	BVIEW softwa	re.
	LIST OF EXPERIMENTS		
1.	Design and testing of fluid power circuits to control. (i) velocity (ii) direction and (iii) force of single and double acting actuators		
2.	Design of circuits with logic sequence using electro pneumatic traine	er kit.	
3.	Simulation of basic hydraulic, Pneumatic and electric circuits using software.		
4.	Circuits with multiple cylinder sequences in electro pneumatic using PLC.		
5.	Servo controller interfacing for open loop.		
6.	Servo controller interfacing for closed loop.		
7.	PID controller interfacing.		
8.	Stepper motor interfacing with 8051 Micro controllers. (i) full step resolution (ii) half step resolution		
9.	Modeling and analysis of basic electrical, hydraulic and pneumatic systems using Lab View software.		
10.	Computerized data logging system with control for process variable temperature.	s like Pressure,	flow and
СО	COURSE OUTCOMES		РО
Upon comj	pletion of this course, Students should be able to		
1.	Study the sensors, components for pneumatic and hydraulic actuatin	ng systems.	PO1, PO4, PO5
2.	Demonstrate the functioning of mechatronics systems with various p		F05
	· · ·	oneumatic,	PO1, PO4,
	hydraulic and electrical systems.		PO1, PO4, PO5
3.	hydraulic and electrical systems.Develop pneumatic/hydraulic circuit for Industrial application		PO1, PO4,
3. 4.	hydraulic and electrical systems.Develop pneumatic/hydraulic circuit for Industrial applicationautomation softwareDemonstrate the functioning of control systems with the help of DC	ons using	PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4,
	hydraulic and electrical systems.Develop pneumatic/hydraulic circuit for Industrial applicationautomation softwareDemonstrate the functioning of control systems with the help of DCand	ons using	PO1, PO4, PO5 PO1, PO4, PO5
4.	hydraulic and electrical systems.Develop pneumatic/hydraulic circuit for Industrial applicationautomation softwareDemonstrate the functioning of control systems with the help of DC	motors	PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4,
4. 5.	hydraulic and electrical systems.Develop pneumatic/hydraulic circuit for Industrial applicationautomation softwareDemonstrate the functioning of control systems with the help of DCandstepper motors.Develop an understanding of PLC ladder diagram related to industriaautomation systems and measure its performance.	motors	PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4, PO5
4. 5. TEXT BOO	hydraulic and electrical systems. Develop pneumatic/hydraulic circuit for Industrial application automation software Demonstrate the functioning of control systems with the help of DC and stepper motors. Develop an understanding of PLC ladder diagram related to industria automation systems and measure its performance. OK	motors	PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4,
4. 5. TEXT BOO 1.	hydraulic and electrical systems. Develop pneumatic/hydraulic circuit for Industrial application automation software Demonstrate the functioning of control systems with the help of DC and stepper motors. Develop an understanding of PLC ladder diagram related to industria automation systems and measure its performance. DK W. Bolton, "Mechatronics", Pearson Education, 3 rd Edition, 2007.	motors	PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4,
4. 5. TEXT BOC 1. 2.	hydraulic and electrical systems. Develop pneumatic/hydraulic circuit for Industrial application automation software Demonstrate the functioning of control systems with the help of DC and stepper motors. Develop an understanding of PLC ladder diagram related to industria automation systems and measure its performance. DK W. Bolton, "Mechatronics", Pearson Education, 3 rd Edition, 2007. HMT Ltd, Mechatronics, Tata McGraw Hill, 2007.	motors	PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4,
4. 5. TEXT BOO 1. 2. REFEREN	hydraulic and electrical systems. Develop pneumatic/hydraulic circuit for Industrial application automation software Demonstrate the functioning of control systems with the help of DC and stepper motors. Develop an understanding of PLC ladder diagram related to industria automation systems and measure its performance. DK W. Bolton, "Mechatronics", Pearson Education, 3 rd Edition, 2007. HMT Ltd, Mechatronics, Tata McGraw Hill, 2007.	ons using motors	PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4, PO5
4. 5. TEXT BOO 1. 2.	hydraulic and electrical systems. Develop pneumatic/hydraulic circuit for Industrial application automation software Demonstrate the functioning of control systems with the help of DC and stepper motors. Develop an understanding of PLC ladder diagram related to industria automation systems and measure its performance. DK W. Bolton, "Mechatronics", Pearson Education, 3 rd Edition, 2007. HMT Ltd, Mechatronics, Tata McGraw Hill, 2007.	ons using motors	PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4, PO5 PO1, PO4, PO5

SEMESTER- VII

Course Title	AUTOMOBILE ENGINEERING	Castlin	LTPC
Course Code		- Credits	3003
Course Category	PCC		
	OBJECTIVES		
To un	derstand the construction and working principle of various parts	s of an automo	bile.
To un	derstand the various engine auxiliary systems.		
	rn the construction and working principle of various transmissio		
	irn the construction and working principle of Steering, Brakes an	d Suspension s	ystems
To stu	idy the alternate sources of energy for IC Engines.		
UNIT - I VEHICI	E STRUCTURE AND ENGINES		9
<i>v</i> 1	iles - vehicle construction and different layouts, chassis, frame ar rious resistances and moments involved), IC engines –componer ing (VVT).	5	
UNIT - II ENGIN	E AUXILIARY SYSTEMS		9
system (Unit injection ignition system (T (WGT, VGT), Engi	trolled gasoline injection system for SI engines, Electronically ctor system, Rotary distributor type and common rail direct in Transistorized coil ignition system, capacitive discharge ignition ine emission control by three-way catalytic converter system, Emi	njection system n system), Turl	h), Electronic bo chargers
UNIT - III TRAN	SMISSION SYSTEMS		9
box, fluid flywhee	construction, gear boxes- manual and automatic, gear shift mech el, torque converter, propeller shaft, slip joints, universal joints, D nd Torque Tube drive – four wheel drive.		
	RING, BRAKES AND SUSPENSION SYSTEMS		9
Tyres – construction Types of Suspensi	ng - Steering geometry and wheel alignment – Steering linkages - on – tyre wear - Types of Front and rear axle, stub axles. on Systems, torsion bar – shock absorbers /draulic braking Systems, Antilock Braking System (ABS), electron		-
Ň,	NATIVE ENERGY SOURCES		9
Use of Natural Ga Engine modificati alternate fuels - El	s, Liquefied Petroleum Gas, Bio-diesel, Bio-ethanol, Gasohol and ons–Performance, Combustion and Emission Characteristics of S ectric and Hybrid Vehicles, Fuel Cell aining in dismantling and assembling of engine parts and transm	and CI engine	Automobiles- es with these
CO	COURSE OUTCOMES		РО
Upon completion	of this course, Students should be able to		
	ognize the various parts of the automobile and their functions an erials.	d	PO1, PO6
	cuss the engine auxiliary systems and engine emission control.		PO1, PO6
3. Dist	inguish the working of different types of transmission systems		PO1, PO6
			,
4. Exp	lain the Steering, Brakes and Suspension Systems.		PO1, PO6

TEXT BOO	K
1.	Jain K.K. and Asthana. R.B, "Automobile Engineering" Tata McGraw Hill Publishers, New
	Delhi,
	2017.
2.	Kirpal Singh, "Automobile Engineering", Vol 1 & 2, Seventh Edition, Standard Publishers, New
	Delhi, 15th Edition 2017.
3.	William H Crouse, Automotive Mechanics. Tata McGraw-Hill. 2010
REFERENC	CES
1.	Ganesan V. "Internal Combustion Engines", Fourth Edition, Tata McGraw-Hill, 2017
2.	Heinz Heisler, "Advanced Engine Technology," SAE International Publications USA, 1998
3.	Joseph Heitner, "Automotive Mechanics," East-West Press, 2017.
4.	Martin W, Stockel and Martin T Stockle, "Automotive Mechanics Fundamentals," The Good
	heart - Will Cox Company Inc, USA ,1978
5.	Newton K, Steeds W and Garret T K. "Motor Vehicles", Butterworth Publishers, IE, 1996

	DESIGN F	OR MANUFACT	URING		Credits	LTPC
Course Code					Cleuits	3003
Course Category		PEC-III				
		OBJI	ECTIVES			
• To underst	and the princi	ples of design such	that the manufacturing o	of the pro	oduct is pos	ssible.
		0 1	ts to be considered for m	nanufact	uring the p	roducts
U	rent processes				• 1 •	
To provide manufactu		with knowledge to p	perform designing of con	nponent	s considerir	ng
To develop	the ability to	design casting and	weld structures.			
To develop	the ability to	use principles of de	sign for assembly			
UNIT - I MANUF	ACTURING	METHODOLOGY	AND PROCESSES			9
Methodologies an	d tools, desig	n axioms, design fo	or assembly and evaluat	tion, mir	nimum par	t assessment,
0	0	0	ring process rules, desig		-	
			/alue analysis, Design f			
_	-		riations, design of parts t	to be mu	lti-function	al, multi-use,
ease of fabrication,	Poke Yoke p	rinciples.				
UNIT - II GEOM	ETRIC ANA	LYSIS				9
		1.1	11.1 1	1 1.00		
		-	able tolerance grades and	d differe	nt machini	
part features-featu	Surface finish, review of relationship between attainable tolerance grades and different machining processes, part features-feature of size-control from-placement material condition – MMC – LMC.					ng processes,
1	re of size-con	rol from-placement	6			ng processes,
UNIT - III FORM			material condition - MN			ng processes,
	I DESIGN OI	F CASTINGS AND	material condition – MM WELDMENTS	AC – LM	C.	9
Redesign of castin	ו DESIGN OI gs based on ן	F CASTINGS AND	material condition – MM WELDMENTS rations, minimizing core	AC – LM	C.	9
Redesign of castin	I DESIGN OI gs based on j ed structure, u	CASTINGS AND parting line consider se of welding symb	material condition – MM WELDMENTS rations, minimizing core	AC – LM	C.	9
Redesign of castin members by welde UNIT - IV MECH	I DESIGN OI gs based on j ed structure, u IANICAL AS	F CASTINGS AND parting line consider use of welding symbols SEMBLY	material condition – MM WELDMENTS rations, minimizing core ols.	AC – LM e require	C. ements, red	9 esigning cast 9
Redesign of castin members by welde UNIT - IV MECH Selective assembly	I DESIGN OI gs based on j ed structure, u IANICAL AS , deciding the	CASTINGS AND parting line consider use of welding symb SEMBLY number of groups,	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa	AC – LM e require amples, (C. ements, red Grouped da	9 esigning cast 9 ntum systems
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types,	I DESIGN O gs based on j ed structure, u IANICAL AS , deciding the geometric an	F CASTINGS AND parting line consider use of welding symbous SEMBLY number of groups, alysis and application	material condition – MM WELDMENTS rations, minimizing core ols.	AC – LM e require amples, (C. ements, red Grouped da	9 esigning cast 9 ntum systems
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types,	I DESIGN OI gs based on j ed structure, u IANICAL AS , deciding the geometric an worst case A	F CASTINGS AND parting line consider use of welding symb SEMBLY number of groups, alysis and applicati rithmetic method, N	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to	AC – LM e require amples, (C. ements, red Grouped da	9 esigning cast 9 itum systems
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE	I DESIGN OI gs based on j ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T	F CASTINGS AND parting line consider use of welding symbols SEMBLY number of groups, alysis and application rithmetic method, Mathematic HEORY	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method.	AC – LM e require amples, (facilitat	ements, red Grouped da ce automate	9 esigning cast 9 ntum systems ed assembly, 9
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE Virtual size conce	I DESIGN OI gs based on j ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an	F CASTINGS AND parting line consider use of welding symbol SEMBLY number of groups, alysis and application rithmetic method, M HEORY d fixed fasteners, provide	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method.	AC – LM e require amples, (facilitat assembl	Erouped da e automate	9 esigning cast 9 atum systems ed assembly, 9 ket, zero true
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE Virtual size conception tolerance,	I DESIGN OI gs based on p ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an functional ga	ECASTINGS AND parting line consider use of welding symbol SEMBLY number of groups, alysis and application rithmetic method, M HEORY d fixed fasteners, produces, paper layout	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method. rojected tolerance zone, gauging, examples. Ope	AC – LM e require amples, (facilitat assembl ration se	C. Ements, red Grouped da e automate y with gasl	9 esigning cast 9 ntum systems ed assembly, 9 set, zero true typical shaft
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE Virtual size conception tolerance,	I DESIGN OI gs based on p ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an functional ga ats. Preparatio	ECASTINGS AND parting line consider use of welding symbol SEMBLY number of groups, alysis and application rithmetic method, M HEORY d fixed fasteners, produces, paper layout	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method.	AC – LM e require amples, (facilitat assembl ration se	C. Ements, red Grouped da e automate y with gasl	9 esigning cast 9 ntum systems ed assembly, 9 set, zero true typical shaft
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE Virtual size concep position tolerance, type of componer	I DESIGN OI gs based on p ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an functional ga ats. Preparatio	ECASTINGS AND parting line consider use of welding symbol SEMBLY number of groups, alysis and application rithmetic method, M HEORY d fixed fasteners, produces, paper layout	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method. rojected tolerance zone, gauging, examples. Open ngs for different operat	AC – LM e require amples, (facilitat assembl ration se	C. Ements, red Grouped da e automate y with gasl	9 esigning cast 9 ntum systems ed assembly, 9 set, zero true typical shaft
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE Virtual size concep position tolerance, type of component centrality analysis, CO	I DESIGN OI gs based on j ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an functional ga its. Preparatio examples.	F CASTINGS AND parting line consider use of welding symbol SEMBLY number of groups, alysis and application rithmetic method, M HEORY d fixed fasteners, pro- uges, paper layout on of process drawing	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method. rojected tolerance zone, gauging, examples. Ope ngs for different operat	AC – LM e require amples, (facilitat assembl ration se	C. Ements, red Grouped da e automate y with gasl	9 esigning cast 9 atum systems ed assembly, 9 set, zero true typical shaft rksheets and
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE Virtual size conception tolerance, type of component centrality analysis, CO	I DESIGN OI gs based on p ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an functional ga ats. Preparatic examples.	F CASTINGS AND parting line consider use of welding symbols SEMBLY number of groups, alysis and application rithmetic method, M HEORY d fixed fasteners, pro- uges, paper layout on of process drawing COURSE ON Students should be	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method. rojected tolerance zone, gauging, examples. Ope ngs for different operat	AC – LM e require amples, (facilitat assembl ration se tions, to	EC. Ements, red Grouped date automate y with gash equence for lerance wo	9 esigning cast 9 atum systems ed assembly, 9 set, zero true typical shaft rksheets and
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE Virtual size conception position tolerance, type of component centrality analysis, CO Upon completion of 1. Under	I DESIGN OI gs based on p ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an functional ga its. Preparatio examples.	F CASTINGS AND parting line consider use of welding symbols SEMBLY number of groups, alysis and application rithmetic method, M HEORY d fixed fasteners, pro- uges, paper layout on of process drawing COURSE ON Students should be acept of mass custom	material condition – MN WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method. rojected tolerance zone, gauging, examples. Ope ngs for different operat UTCOMES able to nization and product fam	AC – LM e require amples, (facilitat assembl ration se tions, to	EC. Ements, red Grouped date automate y with gash equence for lerance wo	9 esigning cast 9 ntum systems ed assembly, 9 set, zero true typical shaft rksheets and PO PO1, PO2
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE Virtual size conception position tolerance, type of component centrality analysis, CO Upon component 1. Under 2. Apply	I DESIGN OI gs based on p ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an functional ga ts. Preparation examples.	F CASTINGS AND parting line consider use of welding symbol SEMBLY number of groups, alysis and application rithmetic method, M HEORY d fixed fasteners, pro- uges, paper layout on of process drawing COURSE ON Students should be acept of mass custom methods to achieve	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method. rojected tolerance zone, gauging, examples. Oper- ngs for different operat UTCOMES able to nization and product fam quality in product design	AC – LM e require amples, (facilitat assembl ration se tions, to nily desig	EC. Ements, red Grouped date automate y with gash equence for lerance wo	9 esigning cast 9 atum systems ed assembly, 9 cet, zero true typical shaft rksheets and PO PO1, PO2 PO1, PO2
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE Virtual size concer position torrance, type of component centrality alysis, CO Upon completion of 1. Under 2. Apply 3. Analy	I DESIGN OI gs based on p ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an functional ga its. Preparation examples. of this course, rstand the cor v appropriate rze product de	F CASTINGS AND parting line consider use of welding symbols SEMBLY number of groups, alysis and applicati rithmetic method, M HEORY d fixed fasteners, print uges, paper layout on of process drawing COURSE OF Students should be cept of mass custon methods to achieve esign for assembly, r	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method. rojected tolerance zone, gauging, examples. Ope ngs for different operat UTCOMES able to nization and product fam quality in product design nanufacturing, and end-	AC – LM e require amples, (facilitat assembl ration se tions, to nily design; of-life is	C. Ements, red Grouped date automate y with gash equence for lerance wo gn; sues;	9 esigning cast 9 ntum systems ed assembly, 9 set, zero true typical shaft rksheets and PO PO1, PO2 PO1, PO2 PO1, PO2 PO1, PO2
Redesign of castin members by welde UNIT - IV MECH Selective assembly , different types, Assembly analysis UNIT - V TRUE I Virtual size concer position tolerance, type of component centrality alysis, CO I Upon completion of 1. Under 2. Apply 3. Analy 4. Under	I DESIGN OI gs based on p ed structure, u IANICAL AS , deciding the geometric an worst case A POSITION T ot, floating an functional ga examples. of this course, rstand the cor v appropriate rze product de rstand how gl	F CASTINGS AND parting line consider use of welding symbol SEMBLY number of groups, alysis and application rithmetic method, M HEORY d fixed fasteners, pro- uges, paper layout on of process drawing COURSE ON Students should be acept of mass custom methods to achieve esign for assembly, r obal environmental	material condition – MM WELDMENTS rations, minimizing core ols. control of axial play, exa ons, design features to lonte -Carlo method. rojected tolerance zone, gauging, examples. Oper- ngs for different operat UTCOMES able to nization and product fam quality in product design	AC – LM e require amples, (facilitat assembl ration se tions, to nily desig n; of-life is duct desi	C. Ements, red Grouped date automate y with gash equence for lerance wo gn; gn; sues; agn;	9 esigning cast 9 atum systems ed assembly, 9 xet, zero true typical shaft rksheets and PO PO1, PO2 PO1, PO2

TEXT BO	OK
1.	Harry pack, "Designing for Manufacture", Pitman Publications, 1983.
2.	Matousek, "Engineering Design, - A Systematic Approach" - Blackie & Son Ltd, London, 1974
REFEREN	ICES
1.	Spotts M.F. "Dimensioning and Tolerance for Quantity Production, Prentice Hall Inc. 1983.
2.	Oliver R. Wade, "Tolerance Control in Design and Manufacturing ". Industrial Press Inc. New York Publications. 1967.
3.	James G. Bralla. "Hand Book of Product Design for Manufacturing". Tata McGraw Hill Publications, 1983.
4.	Trucks H.E. "Design for Economic Production". Society of Manufacturing Engineers, Michigan, 2 nd edition, 1987.

a a i	DIGITAL MANUFACTURING		LTPC
Course Code		- Credits	3003
Course Categor	y PCE-III		•
	OBJECTIVES		
• To devel	op ideas on digital manufacturing.		
• To impo	rt and export CAD data and generate .stl file.		
• To gain I	knowledge on reverse engineering for the given application.		
• To gain I	knowledge on virtual manufacturing.		
To devel	op knowledge on IoT.		
	ODUCTION TO DIGITAL MANUFACTURING		9
Definition of dig	gital manufacturing, Operation Mode and Architecture of Digital N	/lanufacturing	System.
UNIT - II CAD)/CAM		9
generation, Sim	ponent modeling, Machine and tool selection, Defining process a ulation, Post processing. / ERSE ENGINEERING AND CONCEPT MODELERS	r	-
Need, Reverse development. Introduction to	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m		
Need, Reverse development. Introduction to GenisysXs print	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing.		aetric model 3-D printer,
Need, Reverse development. Introduction to GenisysXs print UNIT - IV DIC Introduction, Sc Introduction to	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m	odel market, rtual factory s systems, Feat	aetric model 3-D printer, 9 imulation.
Need, Reverse development. Introduction to GenisysXs print UNIT - IV DIC Introduction, Sc Introduction to System, System	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing. GITAL FACTORY, VIRTUAL MANUFACTURING AND PLM ope, Methods and tools used in virtual manufacturing, benefits. vi Product Life Cycle Management, Types of Product Data, PLM	odel market, rtual factory s systems, Feat	aetric model 3-D printer, 9 imulation.
Need, Reverse development. Introduction to GenisysXs print UNIT - IV DIC Introduction, Sc Introduction to System, System UNIT - V INT Introduction to Technological cl implementing I	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing. GITAL FACTORY, VIRTUAL MANUFACTURING AND PLM ope, Methods and tools used in virtual manufacturing, benefits. vi Product Life Cycle Management, Types of Product Data, PLM architecture, Product information models, Functionality of the PL ERNET OF THINGS Internet of Things, Applications, IOT data management requirem hallenges, RFID and the Electronic Product Code (EPC) network, f DT.	odel market, rtual factory s systems, Feat M Systems. nents, Archited he web of thir	aetric model 3-D printer, 9 imulation. ures of PLM 9 cture of IOT, ngs, Issues in
Need, Reverse development. Introduction to GenisysXs print UNIT - IV DIC Introduction, Sc Introduction to System, System UNIT - V INT Introduction to Technological cl implementing IC	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing. GITAL FACTORY, VIRTUAL MANUFACTURING AND PLM ope, Methods and tools used in virtual manufacturing, benefits. vi Product Life Cycle Management, Types of Product Data, PLM architecture, Product information models, Functionality of the PL ERNET OF THINGS Internet of Things, Applications, IOT data management requirem nallenges, RFID and the Electronic Product Code (EPC) network, f DT. ESION: 3D Modeling of Engineering components and assemblies in	odel market, rtual factory s systems, Feat M Systems. nents, Archited he web of thir	aetric model 3-D printer, 9 imulation. ures of PLM 9 cture of IOT, ngs, Issues in
Need, Reverse development. Introduction to GenisysXs print UNIT - IV DIC Introduction, Sc Introduction to System, System UNIT - V INT Introduction to Technological cl implementing IC TUTORIALSES simulation using	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing. GITAL FACTORY, VIRTUAL MANUFACTURING AND PLM ope, Methods and tools used in virtual manufacturing, benefits. vi Product Life Cycle Management, Types of Product Data, PLM architecture, Product information models, Functionality of the PL ERNET OF THINGS Internet of Things, Applications, IOT data management requirem hallenges, RFID and the Electronic Product Code (EPC) network, f OT. ESION: 3D Modeling of Engineering components and assemblies in g CAM software, Reverse Engineering using microscribe.	odel market, rtual factory s systems, Feat M Systems. nents, Archited he web of thir	aetric model 3-D printer, 9 imulation. ures of PLM 9 cture of IOT, ngs, Issues in e, Machining
Need, Reverse development. Introduction to GenisysXs print UNIT - IV DIC Introduction, Sc Introduction to System, System UNIT - V INT Introduction to Technological cl implementing IC TUTORIALSES simulation using CO	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing. GITAL FACTORY, VIRTUAL MANUFACTURING AND PLM ope, Methods and tools used in virtual manufacturing, benefits. vi Product Life Cycle Management, Types of Product Data, PLM architecture, Product information models, Functionality of the PL ERNET OF THINGS Internet of Things, Applications, IOT data management requirem hallenges, RFID and the Electronic Product Code (EPC) network, f OT. SION: 3D Modeling of Engineering components and assemblies in g CAM software, Reverse Engineering using microscribe. COURSE OUTCOMES	odel market, rtual factory s systems, Feat M Systems. nents, Archited he web of thir	aetric model 3-D printer, 9 imulation. ures of PLM 9 cture of IOT, ngs, Issues in
Need, Reverse development. Introduction to GenisysXs print UNIT - IV DIC Introduction, Sc Introduction to System, System UNIT - V INT Introduction to Technological cl implementing IC TUTORIALSES simulation using CO	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing. GITAL FACTORY, VIRTUAL MANUFACTURING AND PLM ope, Methods and tools used in virtual manufacturing, benefits. vi Product Life Cycle Management, Types of Product Data, PLM architecture, Product information models, Functionality of the PL ERNET OF THINGS Internet of Things, Applications, IOT data management requirem nallenges, RFID and the Electronic Product Code (EPC) network, f OT. SION: 3D Modeling of Engineering components and assemblies in g CAM software, Reverse Engineering using microscribe. COURSE OUTCOMES n of this course, Students should be able to	odel market, rtual factory s systems, Feat M Systems. nents, Architec he web of thir . CAD software	aetric model 3-D printer, 9 imulation. ures of PLM 9 cture of IOT, ngs, Issues in e, Machining PO
Need, Reverse development. Introduction to GenisysXs print UNIT - IV VIC Introduction, Sc Introduction to System, System VNIT - V VIT Introduction to Technological cl implementing IC TUTORIALSES simulation using CO Upon completice 1. Development	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing. GITAL FACTORY, VIRTUAL MANUFACTURING AND PLM ope, Methods and tools used in virtual manufacturing, benefits. vi Product Life Cycle Management, Types of Product Data, PLM architecture, Product information models, Functionality of the PL ERNET OF THINGS Internet of Things, Applications, IOT data management requirem hallenges, RFID and the Electronic Product Code (EPC) network, f OT. SION: 3D Modeling of Engineering components and assemblies in g CAM software, Reverse Engineering using microscribe. COURSE OUTCOMES	odel market, rtual factory s systems, Feat M Systems. nents, Architec he web of thir CAD software	aetric model 3-D printer, 9 imulation. ures of PLM 9 cture of IOT, ngs, Issues in e, Machining
Need, Reverse development.Introduction to GenisysXs printUNIT - IV DICIntroduction to System, SystemUNIT - V INTIntroduction to Technological claimIntroduction to Simulation using COUpon completion1.Dev2.Implement	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing. SITAL FACTORY, VIRTUAL MANUFACTURING AND PLM ope, Methods and tools used in virtual manufacturing, benefits. vi Product Life Cycle Management, Types of Product Data, PLM architecture, Product information models, Functionality of the PL ERNET OF THINGS Internet of Things, Applications, IOT data management requirem hallenges, RFID and the Electronic Product Code (EPC) network, f OT. SION: 3D Modeling of Engineering components and assemblies in g CAM software, Reverse Engineering using microscribe. COURSE OUTCOMES n of this course, Students should be able to velop ideas on digital manufacturing.	odel market, rtual factory s systems, Feat M Systems. nents, Architec he web of thir CAD software	aetric model 3-D printer, 9 imulation. ures of PLM 9 cture of IOT, ngs, Issues in e, Machining PO PO1, PO5
Need, Reverse development.Introductionto GenisysXs printUNIT - IV DICIntroduction, SoIntroductionto System, SystemUNIT - V INTIntroduction to System, SystemUNIT - V INTIntroduction to System, SystemIntroduction to Technological cl implementing ICTUTORIALSES simulation using COUpon completion1.Dev2.Imp3.Gai	engineering process, Reverse engineering hardware and so concept modelers, Principle, Thermo jet printer, Sander's m er, JP system 5, object quadra system-Rapid proto typing. GITAL FACTORY, VIRTUAL MANUFACTURING AND PLM ope, Methods and tools used in virtual manufacturing, benefits. vi Product Life Cycle Management, Types of Product Data, PLM architecture, Product information models, Functionality of the PL ERNET OF THINGS Internet of Things, Applications, IOT data management requirem nallenges, RFID and the Electronic Product Code (EPC) network, f OT. GSION: 3D Modeling of Engineering components and assemblies in g CAM software, Reverse Engineering using microscribe. COURSE OUTCOMES n of this course, Students should be able to velop ideas on digital manufacturing. port and export CAD data and generate .stl file.	odel market, rtual factory s systems, Feat M Systems. nents, Architec he web of thir CAD software	aetric model 3-D printer, 9 imulation. ures of PLM 9 cture of IOT, ngs, Issues in e, Machining PO PO1, PO5 PO1, PO5

TEXT BO	OK
1.	Ibrahim Zeid and Sivasubramanian R, "CAD/CAM - Theory and Practice", Tata McGraw Hill
	Education, 2011.
2.	Vinesh Raja and Kiran J Fernandes, "Reverse Engineering- An Industrial Perspective", Springer-
	Verlag, 2008
3.	Pham D T and Dimov S S, "Rapid Manufacturing: The Technologies and Applications of Rapid
	Prototyping", Springer-Verlag, 2001.
4.	Adrian McEwan and Hakim Cassimally, "Designing the internet of things", Wiley, 2013.
REFEREN	ICES
1.	Gerard Jounghyun Kim, "Designing Virtual Systems: The Structured Approach", Springer, 2005.
2.	Antti Saaksvuori and AnselmiImmonen, "Product Lifecycle Management", Springer, 2004.

Course Title	COMPOSITE MATERIALS	Credits	LTPC	
Course Code		Cleans	3003	
Course Categor	PEC-III			
	OBJECTIVES			
To learn	bout the fundamentals, classifications and need for composite mate	erials.		
To know	about the various manufacturing methods of polymer matrix compo	osites.		
To learn	bout the properties and various processing techniques of metal mat	trix composi	ites.	
To learn	bout the properties, classifications and production methods of cerai	mic compos	ites.	
To know	about the advances in composite materials and testing procedures.			
UNIT – I			9	
composites – M composites (CN	N TO COMPOSITES - need for composites – Enhancement of prop atrix-Polymer matrix composites (PMC), Metal matrix composites (C) – Reinforcement – Particle reinforced composites, Fibre rei advantages of various types of composites.	(MMC), Cer	amic matrix	
UNIT – II			9	
Reinforcement f processes - Han Reaction injectio	POLYMER MATRIX COMPOSITES - Polymer matrix resins – Thermosetting resins, thermoplastic resins – Reinforcement fibres – Rovings – Woven fabrics – Non woven random mats – various types of fibres. PMC processes - Hand layup, Spray layup processes – Vacuum bagging – Compression moulding – Reinforced Reaction injection moulding - Resin transfer moulding – Pultrusion – Filament winding – Injection moulding.			
UNIT – III			9	
vs. MMC, Advar of reinforcem er	K COMPOSITES - Characteristics of MMC, Various types of Metal r stages of MMC, Limitations of MMC, Metal Matrix, Reinforcements t - Volume fraction – Rule of mixtures. Processing of MMC – Powo g – stir casting – squeeze casting.	– particles –	fibres. Effect	
UNIT – IV			9	
CERAMIC MAT Monolithic ceran ceramics – non	RIX COMPOSITES - Engineering ceramic materials – properties – ac nics - Need for CMC – Ceramic matrix- Various types of Ceramic M oxide ceramics – aluminium oxide – silicon nitride – reinforcem ng - Hot pressing – Cold isostatic pressing (CIPing) – Hot isostatic p	/latrix comp nents – part	osites- oxide icles- fibres-	
UNIT – V			9	
ADVANCES IN carbon matrix. technique. Com	ADVANCES IN COMPOSITES - Carbon / Carbon composites – Advantages of carbon matrix – limitations of carbon matrix. Carbon fibre – chemical vapour deposition of carbon on carbon fibre preform, Sol gel technique. Composites for aerospace applications – Introduction to Nano composite. Various testing procedures for composite materials –Eco-friendly composite materials.			
60	COURSE OUTCOMES		DO	
CO			PO	
I	n of this course, Students should be able to		РО	
Upon completio			PO PO1	
Upon completion 1. Lea	n of this course, Students should be able to			
Upon completion 1. Lea 2. Kno	n of this course, Students should be able to rn about the fundamentals of composite materials.		PO1	
Upon completion 1. Lea 2. Known 3. Uno	n of this course, Students should be able to rn about the fundamentals of composite materials. w the manufacturing methods of polymer matrix composites.	s	PO1 PO1, PO3	

TEXT BO	ОК
1.	Mathews F.L. and Rawlings R.D., "Composite materials: Engineering and Science", Chapman
1.	and Hall, London, England, 1 st edition, 1994.
2.	Chawla K.K., "Composite materials", Springer – Verlag, 1987
REFEREN	ICES
1.	Clyne T.W. and Withers P.J., "Introduction to Metal Matrix Composites", Cambridge University
1.	Press, 1993.
2.	Strong A.B., "Fundamentals of Composite Manufacturing", SME, 1989.
3.	Sharma S.C., "Composite materials", Narosa Publications, 2000.
4	"Short Term Course on Advances in Composite Materials, Composite Technology Centre,
4.	Department of Metallurgy", IIT- Madras, December 2001.
5.	Madhu Jit Mukho Padhyay, Mechanics of Composite Materials and Structures, University Press,
5.	2004.

Course Ti	itle	Incom	OI MILIA	AL FORMIN	IG		0 11	LTPC
Course Co	ode						Credits	3003
Course Ca	tegory		PEC-III					
				OBJECT	ΓIVES			
• To 1	understa	and the basic	concepts	of plasticity				
• To (educate	students on v	various m	echanical testir	ng			
• To]	provide	the students	s with know	wledge on meta	tal forming			
• To 1	understa	and the sheet	t metal for	ming				
• To	develop	the special for	orming pr	ocess				
UNIT- I	THEO	RY OF PLAS	STICITY					9
					strain relationshi – Plastic work –			nsor – Strain
UNIT - II	COI	NSTITUTIV	E RELAT	IONSHIPS AN	ND INSTABILIT	ГҮ		9
compressio	on, plast	ic instability			hardening, Comj s, plastic instabili	-	0	ss – Material
models – E UNIT - III Slab analys friction, the	Elasto pla AN sis – Sli ermo ela	asticity, Rigić ALYSIS OF I p line metho astic- analysia	in uniaxia d plasticity METAL F od, upper is of forgir	l tension stress 7, visco plasticit ORMING bound solutiong, rolling, extr	s, plastic instabilitity. ons, numerical r rusion and wire	ity in biaxial	tension stream	9 ms, effect of
models – E UNIT - III Slab analys friction, the Net and ne	Elasto pla AN sis – Sli ermo ela ear net sl	asticity, Rigić ALYSIS OF I p line metho astic- analysis nape forming	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar	l tension stress 7, visco plasticit ORMING bound solutiong, rolling, extr and hot forging.	s, plastic instabilitity. ons, numerical r rusion and wire	ity in biaxial	tension stream	9 ms, effect of
models – E UNIT - III Slab analys friction, the Net and ne UNIT- IV Sheet Meta workability	Elasto pla AN, sis – Sli ermo ela ear net sl ear net sl SHI al Formi y – Form	asticity, Rigić ALYSIS OF I p line metho astic- analysis ape forming ET METAL ng methods	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar FORMIN – Bending agram – An	l tension stress v, visco plasticit ORMING bound solution ng, rolling, extra nd hot forging. G g - Drawing - nalysis of Shee	s, plastic instabilitity. ons, numerical r rusion and wire	ity in biaxial nethods, con drawing pr - Stretch for	tension strea ntact problem ocesses – for rming – Form	9 ms, effect of ming load – 9 nability and
models – E UNIT - III Slab analys friction, the Net and ne UNIT- IV Sheet Meta workability	Elasto pla AN sis – Sli ermo ela ear net sl ear net sl SHI al Formi y – Form rameters	ALYSIS OF I p line metho astic- analysis ape forming ET METAL ng methods aing limit dia s – Superplas	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar , FORMIN - Bending agram – An stic formin	l tension stress v, visco plasticit ORMING bound solution ng, rolling, extra nd hot forging. G g - Drawing - nalysis of Shee	s, plastic instabilitity. ons, numerical r rusion and wire Deep Drawing et metal forming	ity in biaxial nethods, con drawing pr - Stretch for	tension strea ntact problem ocesses – for rming – Form	9 ms, effect of ming load – 9 nability and
models - E UNIT - III Slab analys friction, the Net and ne UNIT - IV Sheet Meta workability process par UNIT - V Orbital forg	Elasto pla AN, sis – Sli ermo ela ear net sl SHI al Formi y – Form rameters SPE ging, Iso	ALYSIS OF I p line metho astic- analysis ape forming ET METAL ng methods aing limit dia s – Superplas CIAL META thermal forg	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar FORMIN – Bending agram – An stic formin AL FORMI ging, Warn	l tension stress v, visco plasticit ORMING bound solution ng, rolling, extr nd hot forging. G g - Drawing - nalysis of Shee g. ING PROCESS n forging, Hot a	s, plastic instabilitity. ons, numerical r rusion and wire Deep Drawing et metal forming	ity in biaxial nethods, con drawing pro - Stretch for - HERF Tec phical pressin	tension strea ntact problem ocesses – for cming – Forn hniques – Pr ng, high spee	9 ms, effect of ming load – 9 nability and inciples and 9
models - E UNIT - III Slab analys friction, the Net and ne UNIT - IV Sheet Meta workability process par UNIT - V Orbital forg	Elasto pla AN, sis – Sli ermo ela ear net sl SHI al Formi y – Form rameters SPE ging, Iso	ALYSIS OF I p line metho astic- analysis ape forming ET METAL ng methods aing limit dia s – Superplas CIAL META thermal forg	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar FORMIN - Bending agram – An stic formin AL FORM ging, Warn hking – Ov	l tension stress v, visco plasticit ORMING bound solution ng, rolling, extr nd hot forging. G g - Drawing - nalysis of Shee g. ING PROCESS n forging, Hot a	s, plastic instabilitity. ons, numerical r rusion and wire Deep Drawing et metal forming SES and Cold isotrop vder Metal Techr	ity in biaxial nethods, con drawing pro - Stretch for - HERF Tec phical pressin	tension strea ntact problem ocesses – for cming – Forn hniques – Pr ng, high spee	9 ms, effect of ming load – 9 nability and inciples and 9
models – E UNIT - III Slab analys friction, the Net and ne UNIT - IV Sheet Meta workability process par UNIT - V Orbital forg rubber pad	Elasto pla AN, sis – Sli ermo ela ear net sl ear net sl SHI al Formi y – Form rameters SPE ging, Iso l formin	ALYSIS OF I p line metho astic- analysis ape forming ET METAL ng methods aing limit dia s – Superplas CIAL META thermal forg g, micro blan	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar FORMIN – Bending agram – An stic formin AL FORMI ging, Warm hking – Ov	l tension stress z, visco plasticit ORMING bound solution ng, rolling, extr nd hot forging. G g - Drawing - nalysis of Shee g. ING PROCESS n forging, Hot a verview of Pow	s, plastic instabilitity. ons, numerical r rusion and wire Deep Drawing et metal forming SES and Cold isotrop vder Metal Techr COMES	ity in biaxial nethods, con drawing pro - Stretch for - HERF Tec phical pressin	tension strea ntact problem ocesses – for cming – Forn hniques – Pr ng, high spee	9 ms, effect of ming load – 9 mability and inciples and 9 ed extrusion,
models – E UNIT - III Slab analys friction, the Net and ne UNIT - IV Sheet Meta workability process par UNIT - V Orbital forg rubber pad	Elasto pla AN, sis – Sli ermo ela ear net sl ear net sl SHI al Formi y – Form rameters SPE ging, Iso l formin pletion o Under	ALYSIS OF I ALYSIS OF I p line metho astic- analysis ape forming ET METAL ng methods ang limit dia a – Superplas CIAL META thermal forg g, micro blan of this course rstand the course	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar FORMIN – Bending agram – An stic formin AL FORMI ging, Warn hking – Ov Co e, Students ncept of p	l tension stress v, visco plasticit ORMING bound solution ng, rolling, extr nd hot forging. G g – Drawing – nalysis of Shee g. ING PROCESS n forging, Hot a rerview of Pow OURSE OUTC should be able lasticity	s, plastic instabilitity. ons, numerical r rusion and wire Deep Drawing et metal forming SES and Cold isotrop vder Metal Techr COMES e to	ity in biaxial nethods, con drawing pro - Stretch for - HERF Tec phical pressin	tension strea ntact problem ocesses – for crming – Forn hniques – Pr ng, high spee vder rolling.	9 ms, effect of ming load – 9 mability and inciples and 9 ed extrusion,
models - E UNIT - III Slab analys friction, the Net and ne UNIT - IV Sheet Meta workability process par UNIT - V Orbital forg rubber pad CO Upon com	Elasto pla AN, sis – Sli ermo ela ear net sl ear net sl SHI al Formi y – Form rameters SPE ging, Iso I formin, pletion o Under Develo	ALYSIS OF I p line metho astic- analysis hape forming ET METAL ng methods hing limit dia s – Superplas CIAL META thermal forg g, micro blan of this course stand the course op ideas on v	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar FORMIN - Bending agram – An stic formin AL FORMI ging, Warn hking – Ov Color e, Students ncept of pl various me	l tension stress , visco plasticit ORMING bound solution ng, rolling, extr nd hot forging, G g - Drawing - nalysis of Shee g. ING PROCESS n forging, Hot a rerview of Pow OURSE OUTC should be able lasticity echanical testin	s, plastic instabilitity. ons, numerical r rusion and wire Deep Drawing et metal forming SES and Cold isotrop vder Metal Techr COMES e to	ity in biaxial nethods, con drawing pro - Stretch for - HERF Tec phical pressin	tension stream ntact problem ocesses – for ming – Forn hniques – Pr ng, high spee vder rolling.	9 ms, effect of ming load – 9 nability and inciples and 9 ed extrusion, PO1, PO2 PO1, PO2
models - E UNIT - III Slab analys friction, the Net and ne UNIT - IV Sheet Meta workability process par UNIT - V Orbital for rubber pad CO Upon com 1.	Elasto pla AN, sis – Sli ermo ela ear net sl ear net sl SHI al Formi y – Form rameters SPE ging, Iso l forming pletion of Under Develo	ALYSIS OF I p line metho astic- analysis hape forming ET METAL ng methods hing limit dia a – Superplas CIAL META thermal forg g, micro blan of this course rstand the course op ideas on v	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar FORMIN - Bending agram – An stic formin AL FORMI ging, Warn hking – Ov Co e, Students incept of pl various me incept of m	l tension stress v, visco plasticit ORMING bound solution ng, rolling, extr nd hot forging, G g – Drawing – nalysis of Shee g. ING PROCESS ING PROCESS n forging, Hot a verview of Pow OURSE OUTC should be able lasticity echanical testin netal forming	s, plastic instabilitity. ons, numerical r rusion and wire Deep Drawing et metal forming SES and Cold isotrop vder Metal Techr COMES e to	ity in biaxial nethods, con drawing pro - Stretch for - HERF Tec phical pressin	tension stream ntact problem ocesses – for ming – Forn hniques – Pr ng, high spee rder rolling.	9 ms, effect of ming load – 9 nability and inciples and 9 ed extrusion, PO1, PO2 PO1, PO2 PO1, PO2
models - E UNIT - III Slab analys friction, the Net and ne UNIT - IV Sheet Meta workability process par UNIT - V Orbital forg rubber pad CO Upon com 1. 2.	Elasto pla AN, sis – Sli ermo ela ear net sl ear net sl SHI al Formi y – Form rameters SPE ging, Iso l formin, pletion o Under Under Under	ALYSIS OF I P line methor astic- analysis hape forming ET METAL ng methods hing limit dia s – Superplas CIAL META thermal forg g, micro blan of this course stand the course stand the course stand the sho	in uniaxia d plasticity METAL F od, upper is of forgir g – Cold ar FORMIN - Bending agram – An stic formin AL FORMI ging, Warn hking – Ov <u>Co</u> e, Students ncept of pl various me ncept of m eet metal f	l tension stress , visco plasticit ORMING bound solution ng, rolling, extr nd hot forging, G g - Drawing - nalysis of Shee g. ING PROCESS n forging, Hot a rerview of Pow OURSE OUTC should be able lasticity echanical testin	s, plastic instabilitity.	ity in biaxial nethods, con drawing pro - Stretch for - HERF Tec phical pressin	tension stream ntact problem ocesses – for ming – Forn hniques – Pr ng, high spee vder rolling.	9 ms, effect of ming load – 9 nability and inciples and 9 ed extrusion, PO1, PO2 PO1, PO2

TEXT BO	ОК
1.	Dieter G.E, "Mechanical Metallurgy" Mc Graw – Hill Co. S1. Edition 1995
2.	Surender Kumar, "Technology of Metal Forming Processes", PHI, New Delhi, 2008.
REFEREN	ICES
1.	Nagpal G.R "Metal Forming Process", Kanna Pub, New Delhi – 2000.
2.	Wagoner, R.H and Chenot, JJ Metal Forming Analysis, Cambridge University Press, 2002.
3.	Slater, R.A.C., Engineering Plasticity – Theory and Applications to Metal Forming, John Wiely and Sons, 1987.
4.	Shiro Kobayshi, Altan. T, Metal Forming and Finite Element Method, Oxford University Press, 1989.
5.	Hosford, W.F and Caddell, R.M., Metal Forming Mechanics and Metallurgy, Prentice Hall Eaglewood Cliffs, 1993.
6.	Narayanaswamy. R, Theory of Metal Forming and Plasticity Narosa Publishers, 1999.
7.	Kurt Lange, "Handbook of Metal Forming", Society of Manufacturing Engineers, Michigan, USA, 1988.
8.	Avitzur, "Metal Forming - Process and Analysis", Tata McGraw-Hill Co., New Delhi,

Course Title	TOTAL QU	ALITY MANAGEMENT	Credits	LTPC
Course Code			Credits	3003
Course Categor	I	PEC-IV		
		OBJECTIVES		
To intro	uce the basic fun	ctions of Total Quality Management		
To learn	he principles of T	ГQМ		
To impai	knowledge on s	tatistical process control techniques		
To study	the usage of tools	s for problem solving		
To famil:	rize various syst	tem standards		
UNIT – I INTR	DUCTION			9
Costs, basic cond Role of senior	epts of total quali	of quality, quality planning, quality costs - analys ty management, historical review, principles of TQ ality council, quality statements, Strategic planni	M, leadershij	p – concepts,
		ANAGEMENT PRINCIPLES		9
retention, emplo appraisal, bene partnership – pa	vee involvement ts, continuous j tnering, sourcing	er perception of quality, customer complaints, se – motivation, empowerment, teams, recognition a process improvement – Juran trilogy, pdsa cyc g, supplier selection, supplier rating, relationship de gy, performance measure.	nd reward, j cle, 5s, kaize	performance en, supplier
UNIT - III TO	AL QUALITY M	IANAGEMENT TOOLS		9
of quality, QFD		nmark, benchmarking process, quality function de taguchi quality loss function, total productive main ges of FMEA.		
	ALITY SYSTEM			9
		9000 and Other Quality Systems, ISO 9000:2000 Qu em, Documentation, TS 16949, ISO 14000 - Con		
UNIT - V STA	FISTICAL PROC	CESS CONTROL (SPC)		9
	nal curve, contro	cal fundamentals – measures of central tendency ar l charts for variables and attributes, process capabi		
CO		COURSE OUTCOMES		PO
		tudents should be able to		
	erstand the basic	-		PO1
-	ain the principle			PO1
	-	atistical process control		PO1, PO4
	the tools for find			PO1, PO4
5. Gai	ı knowledge on s	system standards		PO1, PO4

TEXT BO	OK
1.	DALE H.BESTERFILED, et al., "Total Quality Management", Pearson Education, Inc. 2003.
	(Indian reprint 2004). ISBN 81-297-0260-6.
REFEREN	ICES
1.	JAMES R.EVANS & WILLIAM M.LIDSAY, "The Management and Control of Quality", (5th
	Edition), South-Western (Thomson Learning), 2002 (ISBN 0-324-06680-5).
2.	OAKLAND.J.S. "Total Quality Management", Butterworth - Hcinemann Ltd., Oxford. 1989.
3.	NARAYANA V. AND SREENIVASAN, N.S. "Quality Management - Concepts and Tasks", New
	Age International 1996.
4.	ZEIRI. "Total Quality Management for Engineers", Wood Head Publishers, 1991.

Course Titl	e ENT	REPRE	NEURSHIP DE	VELOPMENT		Credits	LTPC
Course Coo	le					Cleuits	3003
Course Cate	gory]	PEC-IV				
OBJECTIVES							
• To ga	ain knowledg	e on bas	sics of Entreprene	urship			
• To st	udy on motiv	vation of	Entrepreneurshi	p development			
 To gate 	ain knowledg	e of bus	iness entity, sour	ce of capital			
 To gate 	ain knowledg	ge on fina	ancially evaluate	the project			
 To gate 	ain knowledg	ge on ma	nufacturing syste	m			
UNIT – I EN	NTREPRENE	EURSHI	Р				9
-	7 1		trepreneurs – Dowth, factors affect		1	eur and in	ntrapreneur-
UNIT – II N	IOTIVATIO	N					9
thematic app	perception tes	0	trepreneur – Ach s management, er		0	0	d, objectives.
UNIT – III					1.		9
Steps involv and research	Small enterprises – Definition, classification – Characteristics, ownership structures – Project formulation – Steps involved in setting up a business – Identifying, selecting a good business opportunity, market survey and research, techno economic feasibility assessment – Preparation of preliminary project reports – Project appraisal – Sources of information – Classification of needs and agencies.						
**			ACCOUNTING				9
			oans, capital struc ork analysis tech				
UNIT – V S	UPPORT TO) ENTR	EPRENEURS				9
Government	Policy for	Small 9	Concept, Magnitu Scale Enterprises orger and Sub Cor	- Growth Str			
CO			COURSE (DUTCOMES			РО
Upon compl	etion of this o	course, S	Students should b	e able to			
	Acquire the influencing e		edge on the type neur.	es of entreprene	eurship and the		PO6, PO8, 209, PO11, PO12
2.	Explain abou	ıt skills a	and motivation re	equired to becom	ie an entrepreneu		PO6, PO8, PO9, PO11, PO12
3.	Enhance the	busines	s concepts toward	ls a start – up co	nsidering all facto		PO6, PO8, 2O9, PO11, PO12
	Explain the f a small enter		and accounting of	details required	for starting and r	0	PO6, PO8, PO9, PO11, PO12
			s supports, resouse to establish a supports		and skills requ		PO6, PO8, PO9, PO11,

TEXT BOOK				
1.	S.S. Khanka "Entrepreneurial Development" S.Chand & Co. Ltd. Ram Nagar New Delhi, 1999			
2.	2. Kuratko & Hodgetts, "Enterprenuership – Theory, process and practices", Thomson.			
REFERENCES				
1.	Robert Mellor., Entrepreneurship for Everyone: A Student textbook, Sage Publications Ltd., 2008.			
2.	Lee Swanson, Entrepreneurship and Innovation Toolkit, University of Saskatchewan, 2017.			

Course Title	NON-TRA	DITIONAL MACHINING PROCESSE	ES	Credits	LTPC
Course Code				Cleans	3003
Course Category		PEC-IV			
		OBJECTIVES			
To develop	To develop ideas on traditional machining				
• To gain kno	To gain knowledge on mechanical process for the given application				
• To impart k	To impart knowledge on electrical discharge machining				
• To gain kno	To gain knowledge on chemical machining				
• To understa	To understand material removal by using high energy process				
UNIT – I INTROI	DUCTION				9
transfer media and	l process - Pro	ng processes – Classification based on ener ess selection-based on physical parameters riew of all processes.			
UNIT - II MECH	ANICAL PRO	CESS			9
Tool feed mechanis - Process variables	sm – Advantag – Material rer s variables -	Transducer types – Concentrators - Abras es and limitations – Applications. abrasive noval rate - advantages and limitations – A Advantages and limitations – Practical ap	e jet macl pplicatio	hining: proce ons. Water je	ss- principle t machining:
UNIT - III ELECT	FRICAL DISC	HARGE MACHINING			9
materials - Spark e	erosion genera	echanism of metal removal – Dielectric flu ors – Electrode feed system – Material ren ar characteristics of spark eroded surfaces	noval rat	te – Process p	oarameters –

Tool electrode design – Tool wear characteristics of spark eroded surfaces - Advantages and limitations – Practical applications. Electrical discharge wire cut and grinding: principle – wire feed system - advantages and limitations

- Practical applications

UNIT - IV CHEMICAL AND ELECTRO CHEMICAL MACHINING

Chemical machining: fundamentals, principle – Classification and selection of etchant -chemical milling, engraving, blanking - advantages and limitations – Applications. electro chemical machining: electrochemistry of the process- electrolytes - electrolyte and their properties – material removal rate – tool material – tool feed system – design for electrolyte flow – process variables - advantages and limitations – applications - electro chemical grinding: honing, cutting off, deburring and turning.

UNIT - V HIGH ENERGY MACHINING PROCESS

Electron beam machining: principle – Generation and control of electron beam- Advantages and limitations – applications. laser beam machining: principle –solid and gas laser application – Thermal features of LBM - Advantages and limitations – Applications. Ion beam machining: equipment – process characteristics - advantages and limitations – applications. Plasma arc machining: principle – Gas mixture– Types of torches – Process parameters - advantages and limitations – applications. Ion beam machining: principle – Gas mixture– Types of torches advantages, limitation, applications.

9

9

СО	COURSE OUTCOMES	РО			
Upon com	Upon completion of this course, Students should be able to				
1.	Acquire the knowledge on the various types of non-traditional machining PO1, PO2 techniques				
2.	Understand the basics of mechanical process PO1				
3.	Understand the basics of EDM	PO5			
4.	Understand the various types of chemical machining	PO5			
5.	Understand the basics of HIGH ENERGY PROCESS	PO5			
TEXT BO	TEXT BOOK				
1.	P.C Pandey And H.S. Shan, "Modern Machining Process", Tata Mc Graw – Hill Publishing Company Limited, New Delhi, 2007				
2.	V.K. Jain, " Advanced Machining Process", Allied Publishers Pvt Limited 2007				
REFEREN	REFERENCES				
3.	Amithaba Bhattacharyya, "New Technology", The Institution of Engineers, (In Technology", HMT Bangalore, Tata Mc Graw-Hill Publishing Company Limi 2006.				
4.	Hassan El - Hofy "Advanced machining Processes" Tata MC Graw-Hill, 2005.				

Course Code Credits I I I Course Category PEC-IV OBJECTIVES • To understand the basic concepts of flexible manufacturing systems • • • To gain basic knowledge on computer control and software associated with flexible manufacturing systems • • To educate students about simulation and database systems with respect to flexible manufacturing	g ing			
OBJECTIVES To understand the basic concepts of flexible manufacturing systems To gain basic knowledge on computer control and software associated with flexible manufacturing systems	ing			
 To understand the basic concepts of flexible manufacturing systems To gain basic knowledge on computer control and software associated with flexible manufacturing systems 	ing			
To gain basic knowledge on computer control and software associated with flexible manufacturing systems	ing			
systems	ing			
To educate students about simulation and database systems with respect to flexible manufactur	0			
systems				
To know about group technology and justifications on implementing flexible manufacturing syste	.n			
To educate the applications of flexible manufacturing systems in various industrial sectors				
UNIT - I PLANNING, SCHEDULING AND CONTROL	9			
Introduction to FMS– development of manufacturing systems – benefits – major elements – types of flexibi – FMS application and flexibility –single product, single batch, n – batch scheduling problem – knowled based scheduling system.	2			
UNIT - II COMPUTER CONTROL AND SOFTWARE	9			
Introduction – composition of FMS– hierarchy of computer control –computer control of work center a assembly lines – FMS supervisory computer control – types of software specification and selection – trend				
UNIT - III FMS SIMULATION AND DATA BASE	9			
Application of simulation – model of FMS– simulation software – limitation – manufacturing data systems – data flow – FMS database systems – planning for FMS database.				
UNIT - IV GROUP TECHNOLOGY AND JUSTIFICATION OF FMS 9				
Introduction – matrix formulation – mathematical programming formulation –graph formulation – knowledge based system for group technology – economic justification of FMS- application of possibility distributions in FMS systems justification.				
UNIT - V APPLICATIONS OF FMS AND FACTORY OF THE FUTURE 9				
FMS application in machining, sheet metal fabrication, prismatic component production – aerospace application – FMS development towards factories of the future – artificial intelligence and expert systems in FMS – design philosophy and characteristics for future.				
CO COURSE OUTCOMES PO				
Upon completion of this course, Students should be able to				
1.Appreciate the fundamentals of flexible manufacturing systemsPO5				
2. Explain the use of software and computer control in flexible manufacturing PO5 systems				
3. Recognise the importance of simulation and database systems PO5				
4.Explain the group technology and understand the justification of implementing flexible manufacturing systemsPO5				
5. Recognise the effectiveness of imparting flexible manufacturing systems in various industrial sectors PO5				

TEXT BO	OK			
1.	Nand K. Jha., "Handbook of flexible manufacturing systems", Academic Press Inc., 1991			
2.	Shivanand. H. K., Benal. M. M., Koti. V., "Flexible manufacturing system" New Age International Publishers., 2006.			
REFEREN	ICES			
1.	Radhakrishnan P. and Subramanyan S., "CAD/CAM/CIM", Wiley Eastern Ltd., New Age International Ltd., 1994.			
2.	Raouf A. and Daya B.M., "Flexible manufacturing systems: recent development", Elsevier Science, 1995.			
3.	Groover M.P., "Automation, production systems and computer integrated manufacturing", Prentice Hall of India Pvt., New Delhi, 1996.			
4.	Kalpakjian S., "Manufacturing Engineering and Technology", Addison-Wesley Publishsing Co., 1995.			
5.	Ohno T., "Toyota production system: beyond large-scale production", Productivity Press (India) Pvt. Ltd., 1992.			

Course Tit	tle	FLUID POWER SYSTEMS	Credits	LT PC		
Course Co	de		Cleans	3003		
Course Category PEC-IV						
	OBJECTIVES					
		student with knowledge on the application of fluid power an	d about vari	ous types of		
	raulic p	*	. 1. 1	• 1 . • 1		
-		students with an understanding of the fluids and components util system.	ized in mode	rn industrial		
		a measurable degree of competence in the design, construction	n and opera	tion of fluid		
	er circu		in and opera	tion of fiuld		
-		students with knowledge on pneumatics and is applications in in	ndustries.			
		e students about the various trouble shooting methods and appl		vdraulic and		
		systems.		,		
UNIT - I FI	UID P	OWER PRINCIPLES AND HYDRAULIC PUMPS		9		
Law and its	applica	id power- Advantages and Applications- Fluid power systems - ation- Principles of flow, Pumping Theory – Pump Classificatior es, Disadvantages, Performance, Selection criterion of Linear, Ro	n, Constructio	on, Working,		
displacement	nt pum	28.	-			
UNIT - II H	IYDRA	ULIC ACTUATORS AND VALVES		9		
valves: Dire	Hydraulic Actuators: Linear and Rotary– Types and construction, Hydraulic cushioning - Hydraulic control valves: Direction control, Flow control and Pressure control valves-Types, Construction and Operation- Servo and Proportional valves – Types of actuation, Reservoirs, Cylinder mountings, Fluid Power ANSI Symbols.					
UNIT - III	HYDRA	AULIC SYSTEMS		9		
balance, See	quencin	blication circuits, Intensifiers - application circuit, hydraulic circui g, Automatic Reciprocation, Synchronization, Speed control, El ircuits: Cylinder control by limit switch, Reciprocation, Cylinder	lectrical contr			
UNIT - IV	PNEUM	IATIC SYSTEMS		9		
Properties of air– Perfect Gas Laws - Compressors- Filter, Regulator, Lubricator, Muffler, Air control Valves, Actuators. Pneumatic Circuits: Speed control, Quick exhaust, Air-Oil-reservoir circuit, Design of pneumatic circuit by cascade method.						
UNIT - V T	ROUB	LE SHOOTING AND APPLICATIONS		9		
	Maintenance, Trouble Shooting in Hydraulic and Pneumatic systems. Design of hydraulic circuits for Shaper, Milling, Grinding, Pressing and Hydraulic lift-Conveyer feed system - Low cost Automation.					
CO		COURSE OUTCOMES		РО		
Upon comp	letion c	f this course, Students should be able to				
1.		re knowledge of the working principles of fluid power syste alic pumps.	ms and	PO1, PO2		
2.	-	re knowledge of the working principles of hydraulic actuated l components.	ors and	PO1, PO2		
3.	Under	stand different types of hydraulic circuits and systems.		PO1, PO2		
4.	Explai	n the working of different pneumatic circuits and systems.		PO1, PO2		
5.		arize the various troubleshooting methods and applications of hy neumatic systems	ydraulic	PO1, PO2		

TEXT BO	TEXT BOOK				
1.	Anthony Esposito, "Fluid Power with Applications", Prentice Hall, 2009.				
2.	Shanmugasundaram.K, "Hydraulic and Pneumatic Controls", S Chand & Co, 2006.				
REFEREN	REFERENCES				
1.	Majumdar, S.R., "Oil Hydraulics Systems- Principles and Maintenance", Tata McGraw Hill, 2001				
2.	Majumdar, S.R., "Pneumatic Systems – Principles and Maintenance", Tata McGraw Hill, 2007.				
3.	Dudelyt, A Pease and John J Pippenger, "Basic Fluid Power", Prentice Hall, 1987.				
4.	Srinivasan.R, "Hydraulic and Pneumatic Controls", Vijay Nicole Imprints, 2008.				
5.	Joji.P, "Pneumatic Controls", John Wiley & Sons India, 2008				